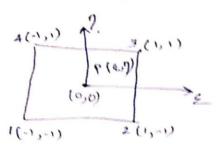


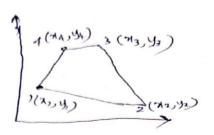


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Element Stiffness matrix Equation for a Noded IsoParametric. awadricateral teement:



· Parens element



Isoparametric quadrilatoral clement

The displacement function u for parent rodangular element,

displacement function u for parent rodangular element
$$u = \begin{cases} u_1 \\ v_2 \\ v_3 \end{cases} = \begin{bmatrix} v_1 & 0 & v_2 & 0 & v_3 & 0 & v_4 & 0 \\ 0 & v_1 & 0 & v_3 & 0 & v_4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}$$

The displacement function a for isoparametric quadrilateral element,

$$u = \begin{cases} x^{2} \\ y^{2} \end{cases} = \begin{cases} N_{1} & 0 & N_{2} & 0 & N_{3} & 0 & N_{4} & 0 \\ 0 & N_{1} & 0 & N_{2} & 0 & N_{3} & 0 & N_{4} \end{cases} \begin{cases} y_{1} \\ y_{2} \\ y_{3} \\ y_{3} \\ y_{4} \\ y_{4} \\ y_{4} \\ y_{5} \\ y_{7} \\ y_{4} \\ y_{7} \\$$

The relationship between natural & global Co-ordinates an be calculated by wing thain rule of partial differential equation,

$$\frac{\partial f}{\partial z} = \frac{\partial f}{\partial x} \times \frac{\partial x}{\partial z} + \frac{\partial f}{\partial y} \times \frac{\partial y}{\partial z}$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial x} \times \frac{\partial x}{\partial y} + \frac{\partial f}{\partial y} \times \frac{\partial y}{\partial y}$$





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Arranging the above equations

$$\begin{cases}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{cases} = \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix} = \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix} \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix} \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix} \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix}$$

where [J] is the Jacobian matrix,

$$\begin{bmatrix} J \end{bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial x} & \frac{\partial y}{\partial x} \\ \frac{\partial x}{\partial y} & \frac{\partial y}{\partial y} \end{bmatrix} \Rightarrow \begin{bmatrix} J_1 \end{bmatrix} = \begin{bmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{bmatrix}$$

where,
$$J_{11} = \frac{\partial x}{\partial \xi}$$
, $J_{12} = \frac{\partial y}{\partial \xi}$
 $J_{21} = \frac{\partial x}{\partial y}$, $D_{22} = \frac{\partial y}{\partial y}$

WKT

$$J_{11} = \frac{\partial N_1}{\partial s} \times_1 + \frac{\partial N_2}{\partial s} \times_2 + \frac{\partial N_3}{\partial s} \times_3 + \frac{\partial N_4}{\partial s} \times_4 \longrightarrow \emptyset$$

$$J_{12} = \frac{\partial N_1}{\partial \Sigma} g_1 + \frac{\partial N_2}{\partial \Sigma} g_2 + \frac{\partial N_3}{\partial \Sigma} g_3 + \frac{\partial N_4}{\partial \Sigma} g_4 \rightarrow \emptyset$$

$$J_{21} = \frac{\partial N_1}{\partial y} \times_1 + \frac{\partial N_2}{\partial y} \times_2 + \frac{\partial N_3}{\partial y} \times_3 + \frac{\partial N_4}{\partial y} \times_4 \rightarrow 3$$

$$J_{22} = \frac{\partial N_1}{\partial \eta} y_1 + \frac{\partial N_2}{\partial \eta} y_2 + \frac{\partial N_3}{\partial \eta} y_3 + \frac{\partial N_4}{\partial \eta} y_4 \xrightarrow{\mathcal{D}} \Phi$$





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WKT, N1 = 1/4 (1-4) (1-7) N2 = 1/4 (1+5) (1-9) N3 = 1/4 (1+5) (1+7) N4 = 1/4 (1-2) (1+9) $\frac{\partial N_1}{\partial s} = \frac{1}{4} (-1) (1-9), \quad \frac{\partial N_2}{\partial s} = \frac{1}{4} (1) (1-9)$ dN3 = 1/4 (1) (1+9), dN4/25 = 1/4 (-1) (H9) $\frac{\partial N_1}{\partial g} = \frac{1}{4}(1-\xi)(-1), \quad \frac{\partial N_2}{\partial g} = \frac{1}{4}(1+\xi)(-1)$ 3N3 = 1/4 (1+5) (1), 3N4/39 = 1/4 (1-5) (1) substitute all the values in equ 0, 0, 0 + 0 J11 = 1 [-(1-9) x1 + (1-9) x2 + (1+9) x3 - (1+9) x4] J12 = 1/4 [-(1-9)41 + (1-9)42 + (1+9)43 - (1+9)44] J21 = 1/4 [- (1-5) x1 - (1+5) x2 + (1+5) x3 + (1-5) x4] J22 = 1/4 [- (1-5)4, - (1+5)42 + (1+5)43 + (1-5)42] WKF, $\begin{bmatrix} \frac{\partial f}{\partial 4} \\ \frac{\partial f}{\partial n} \end{bmatrix} = \begin{bmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{bmatrix} \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$





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$$\begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix} = \begin{bmatrix}
J_{11} & J_{12} \\
J_{21} & J_{22}
\end{bmatrix} \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix}$$

$$= \frac{1}{151} \begin{bmatrix}
J_{22} - J_{12} \\
-J_{21} & J_{11}
\end{bmatrix} \begin{bmatrix}
\frac{\partial f}{\partial x} \\
\frac{\partial f}{\partial y}
\end{bmatrix}$$

The strain displacement relations,

substituting f= u

$$= \left\{\begin{array}{c} \frac{\partial x}{\partial x} \\ \frac{\partial x}{\partial y} \end{array}\right\} = \frac{1}{121} \left[\begin{array}{c} -3^{5} \\ 12^{5} \end{array}\right] \left\{\begin{array}{c} \frac{\partial x}{\partial z} \\ \frac{\partial z}{\partial z} \end{array}\right\}$$

$$\begin{bmatrix}
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} \\
\frac{\partial \lambda^{3}\lambda^{3}}{\partial \lambda^{3}} & \frac{1}{2} & \frac{1}{$$

$$Shorin \{E\} = \begin{cases} 3x^{2} \\ 6^{3} \\ 6^{3} \end{cases} = \frac{121}{121} \begin{cases} 0 & 0 & -32^{12} \\ 2^{22} & -2^{12} \\ 2^{23} & -2^{13} \end{cases} \begin{cases} \frac{3\sqrt{3}}{3^{12}} \\ \frac{3\sqrt{3}}{3^{12}} \\ \frac{3\sqrt{3}}{3^{12}} \end{cases}$$





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with,
$$u = N_1 u_1 + N_2 u_2 + N_3 u_3 + N_4 u_4$$
.

 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
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 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$
 $v = N_1 v_1 + N_2 v_2 + N_3 v_3 + N_4 v_4$

Strain-displacement matrix [8]
$$= \frac{1}{151} \begin{bmatrix} J_{22} - J_{12} & 0 & 0 \\ 0 & 0 & -J_{2}, J_{11} \\ -J_{21} & J_{11} & J_{22} -J_{12} \end{bmatrix} \times \frac{1}{4}$$

$$\begin{bmatrix} -J_{21} & J_{11} & J_{22} & -J_{12} \end{bmatrix}$$

$$\begin{bmatrix} -(1-9) & 0 & (1+9) & 0 & -(1+9) & 0 \\ -(1-9) & 0 & (1+2) & 0 & (1+2) & 0 \\ -(1-2) & 0 & -(1+2) & 0 & (1+2) & 0 & -(1+2) \\ 0 & -(1-2) & 0 & -(1+2) & 0 & (1+2) & 0 & (1-2) \\ 0 & -(1-2) & 0 & -(1+2) & 0 & (1+2) & 0 & (1-2) \end{bmatrix}$$

Nutural co-ordinatos,

$$[k] = + \left(\begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right) = \sum_{i=1}^{n} [BJ_{i}[DJ_{i}] \times S \times SJ_{i}$$





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$$[D] = \frac{E}{1-v^2} \begin{bmatrix} 1 & v & 0 \\ v & 1 & 0 \\ 0 & 0 & \frac{1-v}{2} \end{bmatrix} \quad Plane Street$$

$$= \frac{E}{(Hv)(1-2v)} \begin{bmatrix} 1-v & v & 0 \\ v & 1-v & 0 \\ 0 & 0 & \frac{1-2v}{2} \end{bmatrix} \quad \text{for plane}$$

$$Strong$$