

### **SNS COLLEGE OF TECHNOLOGY**

Coimbatore-35 An Autonomous Institution



Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A++' Grade Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai

### **DEPARTMENT OF ELECTRONICS & COMMUNICATION ENGINEERING**

### **19ECT213- IOT SYSTEM ARCHITECTURE**

II ECE / IV SEMESTER

UNIT 2 – MICROCONTROLLER AND INTERFACING TECHNIQUES FOR IoT

DEVICES

**TOPIC 2 – Introduction to NodeMCU** 

# ESP8266 NodeMCU WiFi Development Board

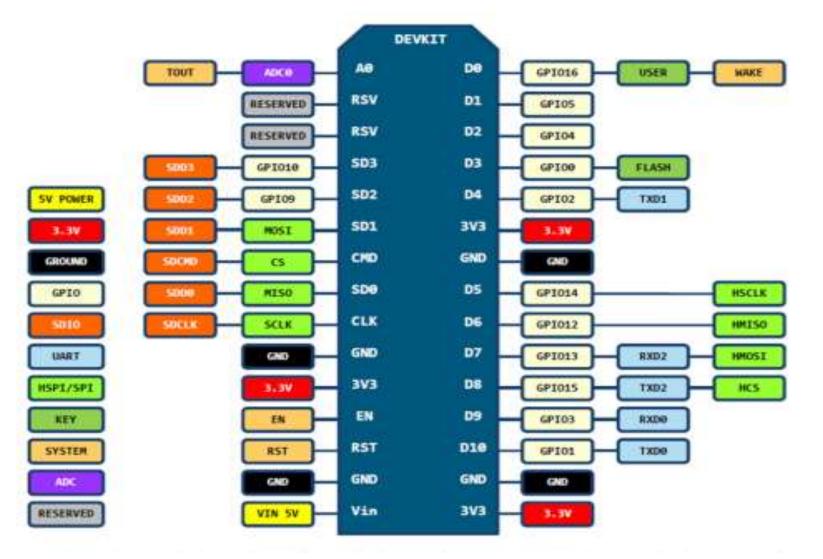
### Specification:

- Voltage:3.3V.
- · Wi-Fi Direct (P2P), soft-AP.
- Current consumption: 10uA~170mA.
- Flash memory attachable: 16MB max (512K normal).
- Integrated TCP/IP protocol stack.
- Processor: Tensilica L106 32-bit.
- Processor speed: 80~160MHz.
- RAM: 32K + 80K.
- GPIOs: 17 (multiplexed with other functions).
- Analog to Digital: 1 input with 1024 step resolution.
- +19.5dBm output power in 802.11b mode
- 802.11 support: b/g/n.
- Maximum concurrent TCP connections: 5.



## ESP8266 NodeMCU





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### 3.1 Install the Arduino IDE 1.6.4 or greater

Download Arduino IDE from Arduino.cc (1.6.4 or greater) - don't use 1.6.2 or lower version! You can use your existing IDE if you have already installed it.



You can also try downloading the ready-to-go package from the ESP8266-Arduino project, if the proxy is giving you problems.

#### 3.2 Install the ESP8266 Board Package

Enter http://arduino.esp8266.com/stable/package\_esp8266com\_index.json into Additional Board Manage field in the Arduino v1.6.4+ preferences.

Preferences	The second s		×		
Settings Networ	(k				
Sketchbook locat	tion:				
C:\Users\@Y\Doc	cuments\Arduino		Browse		
Editor language:	System Default	<ul> <li>(requires restart of Arduino)</li> </ul>			
Editor font size:	18				
Show verbose ou	utput during: 🔝 compilation 📄	upload			
Compiler warning	ps: None 👻				
Display line r	numbers				
Enable Code	: Folding				
Verify code a	after upload				
Use external	l editor				
Check for up	odates on startup				
Update sket	ch files to new extension on save	(.pde -> .ino)			
V Save when v	verifying or uploading				
Additional Boards Manager URLs: http://arduino.esp8266.com/stable/package_esp8266com_index.json					
More preference	s can be edited directly in the file				
C:\Users\BY\App	Data (Local \Arduino 15\preference	s.bt			
(edit only when J	Arduino is not running)				

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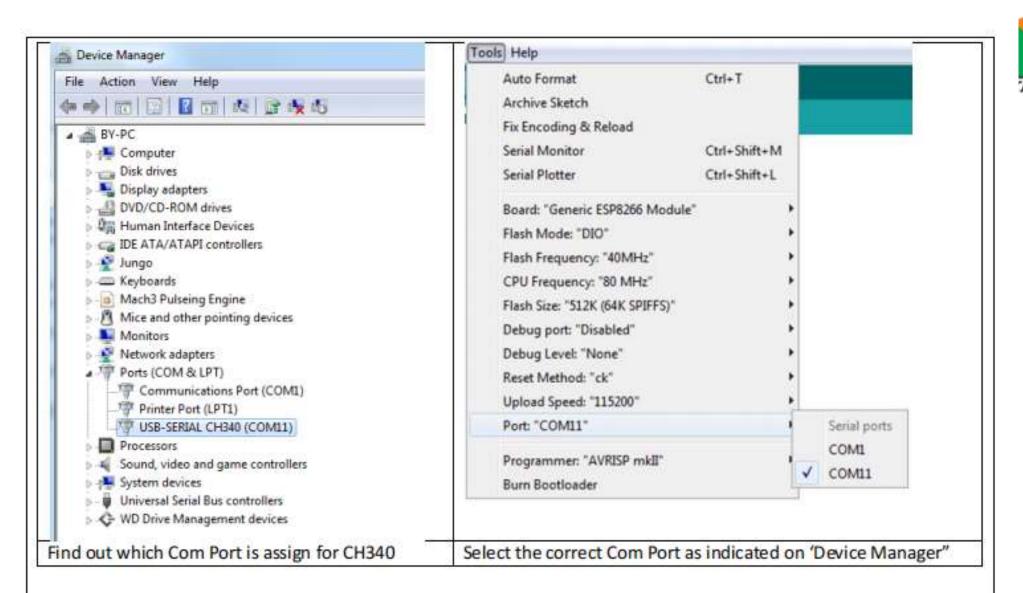
### 3.3 Setup ESP8266 Support

When you've restarted Arduino IDE, select 'Generic ESP8266 Module' from the 'Tools' -> 'Board:' dropdown me



Auto Format	Ctrl+T			
Archive Sketch				
Fix Encoding & Reload				
Serial Monitor	Ctrl+Shift+M	Ŀ		
Serial Plotter	Ctrl+Shift+L	n	once:	
Board: "Generic ESP8266 Modul	e' i	8	*	
Flash Mode: "DIO"			Arduino Ethernet	
Flash Frequency: "40MHz"			Arduino Fio	
CPU Frequency: '80 MHz'			Arduine BT	
Flash Size: "512K (64K SPIFFS)"			LilyPad Arduino USB	
Debug port: "Disabled"			LilyPad Arduino	
Debug Level: "None"			Arduino Pro or Pro Mini	
Reset Method: "ck"			Arduino NG or older Arduino Robot Control	Select this
Upload Speed: "115200"			Arduino Robot Motor	1
Port			Arduino Gemma	/
Programmer: "AVRISP mkII"			Arduino ARM (32-bits) Boards	
Burn Bootloader			Arduino Due (Programming Port)	
			Arduino Due (Native USB Port)	
			ESP8266 Modules	
		•	Generic ESP8266 Module	
			Generic ESP8285 Module	





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## **Connecting via WiFi**



We'll begin with the simple blink test.

Enter this into the sketch window (and save since you'll have to). Connect a LED as shown in Figure3-1.

	(POT): //	GP1005, D	ligital )	Pim D1
<pre>oid loop() {   digitalWrite()   delay(NOO);   digitalWrite()   delay(SOO); </pre>	, WIGN); , LOW);			

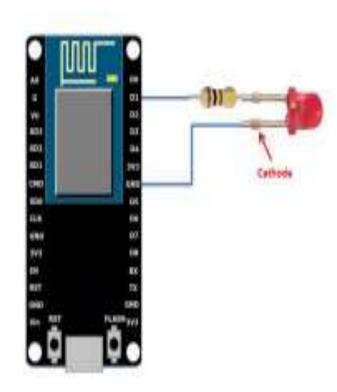
Now you'll need to put the board into bootload mode. You'll have to do this before each upload. There is no timeout for bootload mode, so you don't have to rush?

- Hold down the "Flash" button.
- While holding down' Rash', press the 'RST' button.
- Release 'RST', then release 'Flash'

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### So blinky | Arduino 1.6.7 File Edit Sketch Tools Help Ø 🔸 🖬 🖬 🖬 blinky void setup() { pinMode(5, OUTPUT); // GPI005, Digital Pin D1 void loop() { digitalWrite(5, HIGH); delay(900); digitalWrite(5, LOW); delay(500); Spurious github folder in 'Adafruit IO Arduino' library ARNING Sketch uses 222,197 bytes (51%) of program storage space. Maximum is 434,160 bytes. Global variables use 31,572 bytes (38%) of dynamic memory, leaving 50,348 bytes for local v 111 Generic ESP8266 Module, 80 MHz, 40MHz, DIO, 115200, 512K (64K SPIR

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# Connecting via WiFi

### #include <ESP8266WiFi.h>

\*/

```
const char* ssid = "handson"; // key in your own SSID
const char* password = "abc1234"; // key in your own WiFi access point
password
```

```
const char* host = "www.handsontec.com";
void setup() {
  Serial.begin(115200);
  delay (100);
  // We start by connecting to a WiFi network
  Serial.println();
  Serial.println();
  Serial.print ("Connecting to ");
  Serial.println(ssid);
  WiFi.begin(ssid, password);
  while (WiFi.status() != WL CONNECTED) {
    delay (500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
```

```
int value = 0;
void loop() {
 delay (5000);
 ++value;
 Serial.print ("connecting to ");
  Serial.println(host);
 // Use WiFiClient class to create TCP connections
 WiFiClient client;
 const int httpPort = 80;
 if (!client.connect(host, httpPort)) {
    Serial.println("connection failed");
    return;
  3
 // We now create a URI for the request
 String url = "/projects/index.html";
 Serial.print ("Requesting URL: ");
 Serial.println(url);
 // This will send the request to the server
 client.print(String("GET ") + url + " HTTP/1.1\r\n" +
               "Host: " + host + "\r\n" +
               "Connection: close\r\n\r\n");
 delay (500);
 // Read all the lines of the reply from server and print them to Serial
 while (client.available ()) {
    String line = client.readStringUntil('\r');
   Serial.print (line);
 Serial.println();
 Serial.println("closing connection");
```





## WHAT IS ESP32



ESP32 is a series of low cost, low power system on a chip

microcontrollers with integrated Wi-Fi & dual-mode Bluetooth.

CPU: Xtensa Dual-Core 32-bit LX6 microprocessor, operating at 160

or 240 MHz and performing at up to 600 DMIPS

- Memory: 520 KiB SRAM
- - Wireless connectivity:
- wi-Fi: 802.11 b/g/n/e/i
- + Bluetooth: v4.2 BR/EDR and BLE

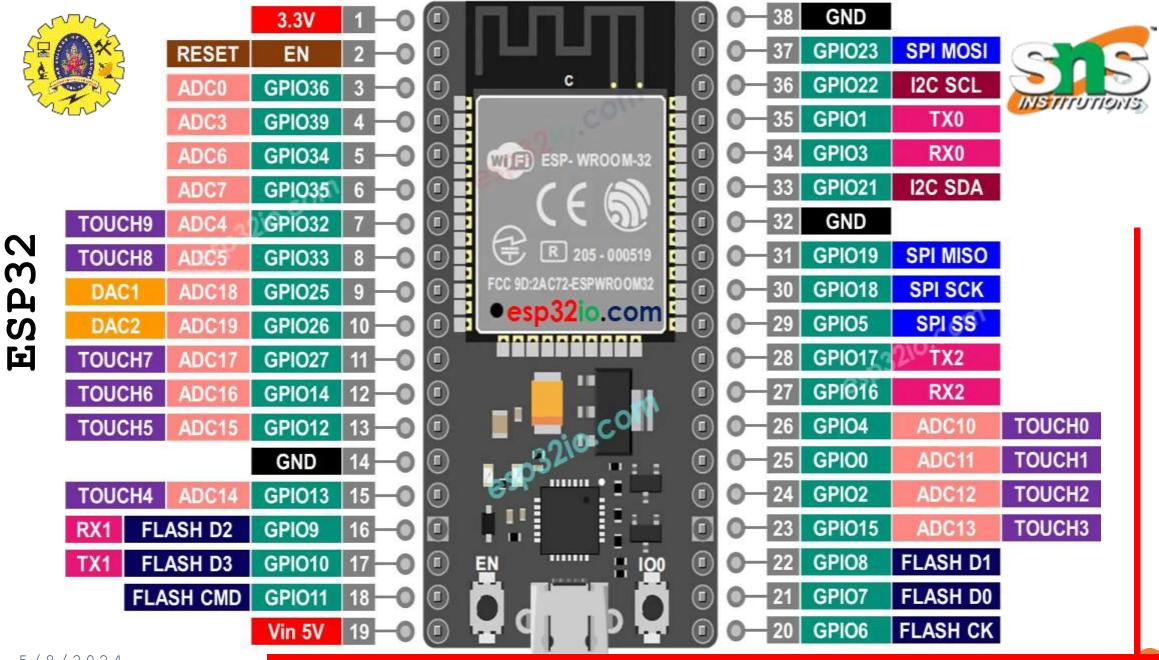
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## WHAT IS ESP32?



- Integrated Crystal- 40 MHz
- Module Interfaces- UART, SPI, I2C, PWM, ADC, DAC, GPIO, pulse counter, capacitive touch sensor
- Integrated SPI flash- 4 MB
- ROM- 448 KB (for booting and core functions)
- SRAM- 520 KB
- Integrated Connectivity Protocols- WiFi, Bluetooth, BLE
- On-chip sensor- Hall sensor
- Operating temperature range- -40 85 degrees Celsius
- Operating Voltage- 3.3V
- **Operating Current- 80 mA (average)**



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## The ESP32 peripherals include:



- 18 Analog-to-Digital Converter (ADC) channels
- 3 SPI interfaces
- 3 UART interfaces
- 2 I2C interfaces
- 16 PWM output channels
- 2 Digital-to-Analog Converters (DAC)
- 2 I2S interfaces
- 10 Capacitive sensing GPIOs 5/8/2024







Input only pin GPIOs 34 to 39 are GPIs – input only pins. These pins don't have internal pull-up or pull-down resistors. They can't be used as outputs, so use these pins only as inputs: GPIO 34 GPIO 35 GPIO 36 GPIO 39

### SPI flash integrated on the ESP-WROOM-32

GPIO 6 to GPIO 11 are exposed in some ESP32 development boards. However, these pins are connected to the integrated SPI flash on the ESP-WROOM-32 chip and are not recommended for other uses. So, don't use these pins in your projects: GPIO 6 (SCK/CLK) GPIO 7 (SDO/SD0) GPIO 8 (SDI/SD1) GPIO 9 (SHD/SD2) GPIO 10 (SWP/SD3) GPIO 11 (CSC/CMD)

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The ESP32 has 10 internal capacitive touch sensors. These can sense variations in anything that holds an electrical charge, like the human skin. So they can detect variations induced when touching the GPIOs with a finger. These pins can be easily integrated into capacitive pads and replace mechanical buttons. The capacitive touch pins can also be used to wake up the ESP32 from deep sleep.

Those internal touch sensors are connected to these GPIOs: T0 (GPIO 4) T1 (GPIO 0) T2 (GPIO 2) T3 (GPIO 15) T4 (GPIO 13) T5 (GPIO 12) T6 (GPIO 14) T7 (GPIO 27) T8 (GPIO 33) T9 (GPIO 32)

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- ADC2\_CH0 (GPIO 4) 5/8/2024
- ADC1\_CH7 (GPIO 35)
- ADC1\_CH6 (GPIO 34)
- ADC1\_CH5 (GPIO 33)
- ADC1\_CH4 (GPIO 32)
- ADC1\_CH3 (GPIO 39)
- ADC1\_CH2 (GPIO 38)
- ADC1\_CH1 (GPIO 37)
- ADC1\_CH0 (GPIO 36)

- Analog to Digital Converter (ADC)

  - ADC2\_CH2 (GPIO 2) •
  - ADC2\_CH1 (GPIO 0)



ADC2\_CH8 (GPIO 25)

• ADC2\_CH9 (GPIO 26)

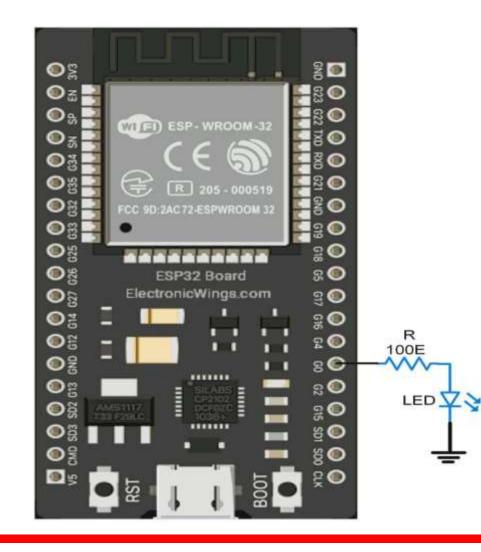
- ADC2\_CH7 (GPIO 27)
- ADC2\_CH6 (GPIO 14)
- ADC2\_CH5 (GPIO 12)
- ADC2\_CH4 (GPIO 13)

- ADC2\_CH3 (GPIO 15)





## Blink LED Using ESP32



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## Blink LED Using ESP32

```
void setup()
{
    pinMode(0, OUTPUT); // sets the digital pin 0 as output
}
```

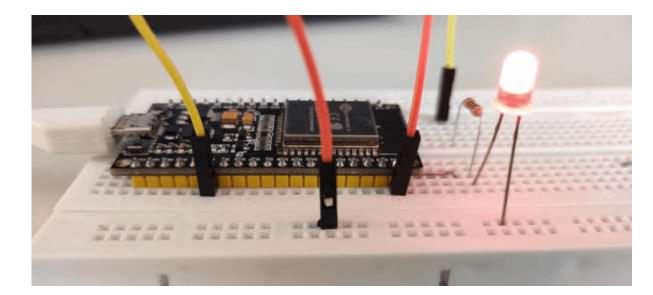
```
void loop()
{
    digitalWrite(0, HIGH); // sets the digital pin 0 on
    delay(1000); // waits for a second
    digitalWrite(0, LOW); // sets the digital pin 0 off
    delay(1000); // waits for a second
```

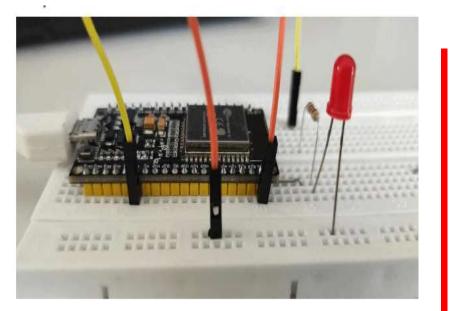




## Blink LED Using ESP32

### Output





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