

SNS COLLEGE OF TECHNOLOGY

Coimbatore-35 An Autonomous Institution



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DEPARTMENT OF ELECTRONICS & COMMUNICATION ENGINEERING

19ECT213- IOT SYSTEM ARCHITECTURE

II ECE / IV SEMESTER

UNIT 3 – ACTUATORS AND IOT NETWORKING DEVICES

TOPIC 7 – ESP8266 Wi-Fi Module



ESP8266 Vs NodeMCU



- **ESP8266**: This is a tiny, low-power Wi-Fi microcontroller chip made by Espressif Systems. It's the core component and the brains behind the operation.
- NodeMCU: This is an open-source firmware (software) that specifically works with the ESP8266 chip. It provides a user-friendly development environment, making it easier to program the ESP8266.
- An analogy:
- Think of ESP8266 as a powerful engine in a car.
- NodeMCU is like the dashboard and steering wheel it provides a way to interact with the engine (ESP8266) and control its functions



ESP8266 Vs NodeMCU

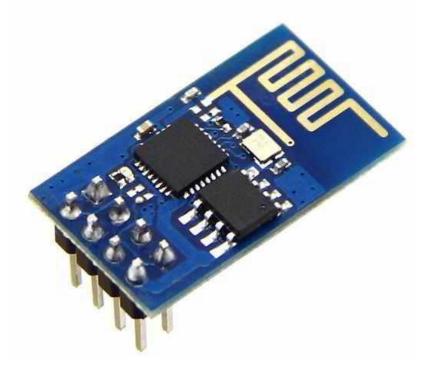


Specifications	ESP8266	ESP32		
MCU	Xtensa® Single-Core 32-bit L106	Xtensa® Dual-Core 32-bit LX6 600 DMIPS		
802.11 b/g/n Wi-Fi	Yes, HT20	Yes, HT40		
Bluetooth	None	Bluetooth 4.2 and below		
Typical Frequency	80 MHz	160 MHz		
SRAM	160 kBytes	512 kBytes		
Flash	SPI Flash , up to 16 MBytes	SPI Flash, up to 16 MBytes		
GPIO	17	36		
Hardware / Software PWM	None / 8 Channels	1 / 16 Channels		
SPI / 12C / 12S / UART	2/1/2/2	4/2/2/2		
ADC	10-bit	12-bit		
CAN	None	1		
Ethernet MAC Interface	None	1		
Touch Sensor	None	Yes		
Temperature Sensor	None	Yes		
Working Temperature	- 40°C - 125°C	-40°C - 125°C		



ESP8266 NodeMCU WiFi Development Board





- The ESP8266 wifi module is low cost standalone wireless transceiver that can be used for end-point IoT developments.
- ESP8266 wifi module enables internet connectivity to embedded applications.
- It uses TCP/UDP communication protocol to connect with the server/client.
- To communicate with the ESP8266 wifi module, microcontroller needs to use set of AT commands.
- The microcontroller communicates with ESP8266-01 wifi module using UART having specified Baud rate (Default 115200)



ESP8266 NodeMCU WiFi Development Board

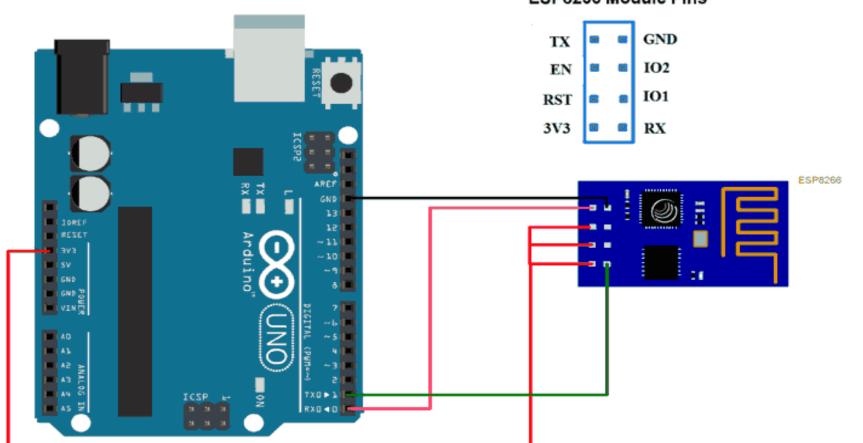


Specification:

- Voltage:3.3V.
- Wi-Fi Direct (P2P), soft-AP.
- Current consumption: 10uA~170mA.
- Flash memory attachable: 16MB max (512K normal).
- Integrated TCP/IP protocol stack.
- Processor: Tensilica L106 32-bit.
- Processor speed: 80~160MHz.
- RAM: 32K + 80K.
- GPIOs: 17 (multiplexed with other functions).
- Analog to Digital: 1 input with 1024 step resolution.
- +19.5dBm output power in 802.11b mode
- 802.11 support: b/g/n.
- Maximum concurrent TCP connections: 5.







ESP8266 Module Pins



#include "ESP8266_AT.h"



/* Select Demo */
//#define RECEIVE_DEMO
#define SEND_DEMO

/* Define RECEIVE demo */ /* Define SEND demo */

/* Define Required fields shown below */
#define DOMAIN "api.thingspeak.com"
#define PORT "80"
#define API_WRITE_KEY "Write your Write Key here"
#define CHANNEL_ID "Write your Channel ID here"

#define SSID "Write your WIFI SSID here"
#define PASSWORD "Write your WIFI Password here"

char _buffer[150]; uint8_t Connect_Status; #ifdef SEND_DEMO uint8_t Sample = 0; #endif



void setup() {
 Serial.begin(115200);



```
while(!ESP8266_Begin());
ESP8266_WIFIMode(BOTH_STATION_AND_ACCESPOINT); /* 3 = Both (AP and STA) */
ESP8266_ConnectionMode(SINGLE); /* 0 = Single; 1 = Multi */
ESP8266_ApplicationMode(NORMAL); /* 0 = Normal Mode; 1 = Transperant Mode */
if(ESP8266_connected() == ESP8266_NOT_CONNECTED_TO_AP)/*Check WIFI connection*/
ESP8266_JoinAccessPoint(SSID, PASSWORD); /*Connect to WIFI*/
ESP8266_Start(0, DOMAIN, PORT);
```

```
void loop() {
    Connect_Status = ESP8266_connected();
    if(Connect_Status == ESP8266_NOT_CONNECTED_TO_AP) /*Again check connection to WIFI*/
    ESP8266_JoinAccessPoint(SSID, PASSWORD); /*Connect to WIFI*/
    if(Connect_Status == ESP8266_TRANSMISSION_DISCONNECTED)
    ESP8266_Start(0, DOMAIN, PORT); /*Connect to TCP port*/
```





```
#ifdef SEND DEMO
  memset(_buffer, 0, 150);
  sprintf( buffer, "GET /update?api key=%s&field1=%d", API WRITE KEY, Sample++); /*connect to
                                            thingspeak server to post data using your API_WRITE_KEY*/
  ESP8266_Send(_buffer);
  delay(15000);
         /* Thingspeak server delay */
  #endif
  #ifdef RECEIVE DEMO
  memset( buffer, 0, 150);
  sprintf(_buffer, "GET /channels/%s/feeds/last.txt", CHANNEL_ID); /*Connect to thingspeak server to get
data using your channel ID*/
  ESP8266_Send(_buffer);
  Read Data( buffer);
  delay(600);
  #endif
```



3.1 Install the Arduino IDE 1.6.4 or greater

Download Arduino IDE from Arduino.cc (1.6.4 or greater) - don't use 1.6.2 or lower version! You can use your existing IDE if you have already installed it.



You can also try downloading the ready-to-go package from the ESP8266-Arduino project, if the proxy is giving you problems.

3.2 Install the ESP8266 Board Package

Enter *http://arduino.esp8266.com/stable/package_esp8266com_index.json* into *Additional Board Manage* field in the Arduino v1.6.4+ preferences.

references	x
Settings Network	
Sketchbook location:	
C: \Users\BY\Documents\Arduino Browse	
	-
Editor font size: 18	
Show verbose output during: Compilation upload	
Compiler warnings: None 👻	
Display line numbers	
Enable Code Folding	
Verify code after upload	
Use external editor	
Check for updates on startup	
Update sketch files to new extension on save (.pde -> .ino)	
Save when verifying or uploading	
Additional Boards Manager URLs: http://arduino.esp8266.com/stable/package_esp8266com_index.json	
More preferences can be edited directly in the file	
C:\Users\BY\AppData\Local\Arduino15\preferences.txt	
(edit only when Arduino is not running)	



3.3 Setup ESP8266 Support

When you've restarted Arduino IDE, select 'Generic ESP8266 Module' from the 'Tools' -> 'Board:' dropdown me



Help				
Auto Format	Ctrl+T			
Archive Sketch				
Fix Encoding & Reload				
Serial Monitor	Ctrl+Shift+M			
Serial Plotter	Ctrl+Shift+L	n	once:	
Board: "Generic ESP8266 Module"			A	
Flash Mode: "DIO"			Arduino Ethernet	
Flash Frequency: "40MHz"			Arduino Fio	
CPU Frequency: "80 MHz"			Arduino BT	
Flash Size: "512K (64K SPIFFS)"			LilyPad Arduino USB	
Debug port: "Disabled"			LilyPad Arduino	
Debug Level: "None"			Arduino Pro or Pro Mini	
Reset Method: "ck"			Arduino NG or older	Select this
Upload Speed: "115200"			Arduino Robot Control	
]		Arduino Robot Motor	
Port	1		Arduino Gemma	/
Programmer: "AVRISP mkII"			Arduino ARM (32-bits) Boards	
Burn Bootloader			Arduino Due (Programming Port)	
			Arduino Due (Native USB Port)	
			ESP8266 Modules	
		0	Generic ESP8266 Module	
			Generic ESP8285 Module	

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E.

Device Manager	Tools Help	
le Action View Help	Auto Format Ctrl+T Archive Sketch Fix Encoding & Reload Serial Monitor Ctrl+Sh	i H + M
 Disk drives Display adapters 	Serial Plotter Ctrl+Sh	
 DVD/CD-ROM drives Human Interface Devices IDE ATA/ATAPI controllers Jungo Keyboards Mach3 Pulseing Engine Mice and other pointing devices Monitors Network adapters Ports (COM & LPT) Communications Port (COM1) 	Board: "Generic ESP8266 Module" Flash Mode: "DIO" Flash Frequency: "40MHz" CPU Frequency: "80 MHz" Flash Size: "512K (64K SPIFFS)" Debug port: "Disabled" Debug Level: "None" Reset Method: "ck" Upload Speed: "115200"	* * * * * * *
Printer Port (LPT1) USB-SERIAL CH340 (COM11) Processors Sound, video and game controllers System devices Universal Serial Bus controllers	Port: "COM11" Programmer: "AVRISP mkII" Burn Bootloader	COM1 COM11



Connecting via WiFi

3.4 Blink Test

We'll begin with the simple blink test.

Enter this into the sketch window (and save since you'll have to). Connect a LED as shown in Figure3-1.

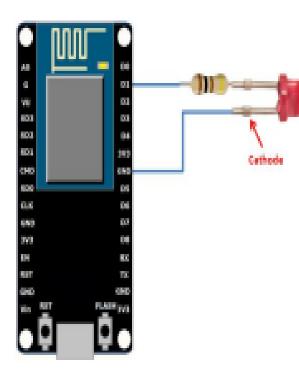
```
void setup() {
   pinNode(5, OUTPUT); // GPI005, Digital Pin D1
)
void loop() {
   digitalWrite(5, HIGH);
   delay(900);
   digitalWrite(5, LOW);
   delay(500);
}
```

Now you'll need to put the board into bootload mode. You'll have to do this before each upload. There is no timeout for bootload mode, so you don't have to rush!

- Hold down the 'Flash' button.
- While holding down' Flash', press the 'RST' button.
- Release 'RST', then release 'Flash'







oo blinky | Arduino 1.6.7 the or dones, Maximum 1 File Edit Sketch Tools Help 🕢 🔸 🗈 🖬 🖬 blinky void setup() { pinMode(5, OUTPUT); // GPI005, Digital Pin D1 } void loop() { digitalWrite(5, HIGH); delay(900); digitalWrite(5, LOW); delay(500); ploading. ARNING: Spurious .github folder in 'Adafruit IO Arduino' library Sketch uses 222,197 bytes (51%) of program storage space. Maximum is 434,160 bytes.

Global variables use 31,572 bytes (38%) of dynamic memory, leaving 50,348 bytes for local v Uploading 226352 bytes from C:\Users\BY\AppData\Local\Temp\buildb7f3357d9ec338fa2a4043584dd

III

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Generic ESP8266 Module, 80 MHz, 40MHz, DIO, 115200, 512K (64K SPIFI

*/

Connecting via WiFi

#include <ESP8266WiFi.h>

```
const char* ssid = "handson"; // key in your own SSID
const char* password = "abc1234"; // key in your own WiFi access point
password
```

```
const char* host = "www.handsontec.com";
void setup() {
  Serial.begin(115200);
  delay (100);
  // We start by connecting to a WiFi network
  Serial.println();
  Serial.println();
  Serial.print("Connecting to ");
  Serial.println(ssid);
  WiFi.begin(ssid, password);
  while (WiFi.status() != WL CONNECTED) {
    delay (500);
    Serial.print(".");
  Ъ
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
Ъ
```

```
int value = 0;
void loop() {
 delay (5000);
  ++value;
  Serial.print("connecting to ");
  Serial.println(host);
 // Use WiFiClient class to create TCP connections
  WiFiClient client;
  const int httpPort = 80;
  if (!client.connect(host, httpPort)) {
    Serial.println("connection failed");
    return;
  Ъ
  // We now create a URI for the request
  String url = "/projects/index.html";
  Serial.print("Requesting URL: ");
  Serial.println(url);
 // This will send the request to the server
  client.print(String("GET ") + url + " HTTP/1.1\r\n" +
               "Host: " + host + "\r\n" +
               "Connection: close\r\n\r\n");
 delay(500);
 // Read all the lines of the reply from server and print them to Serial
 while(client.available()) {
    String line = client.readStringUntil('\r');
    Serial.print (line);
 Serial.println();
 Serial.println("closing connection");
}
```