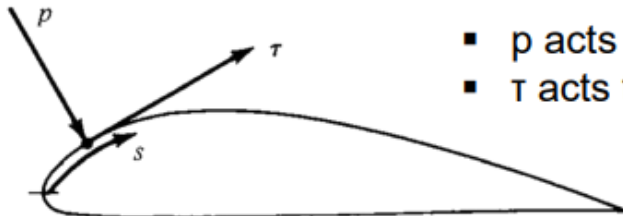




Aerodynamic forces and moments

- At first glance, the generation of the aerodynamic force may seem complex...
- However, in all cases, the aerodynamic forces and moments on the body are due to only two basic sources:
 1. **Pressure** distribution,
 2. **Shear stress** distribution over the body surface



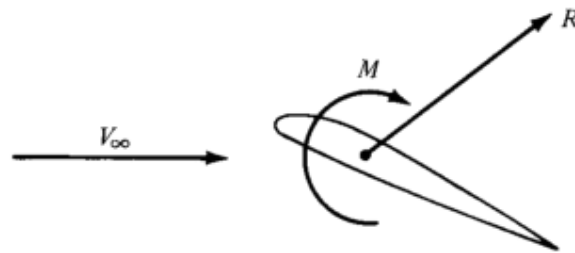
- p acts normal to the surface,
- τ acts tangential to the surface.

$p = p(s)$ = surface pressure distribution
 $\tau = \tau(s)$ = surface shear stress distribution

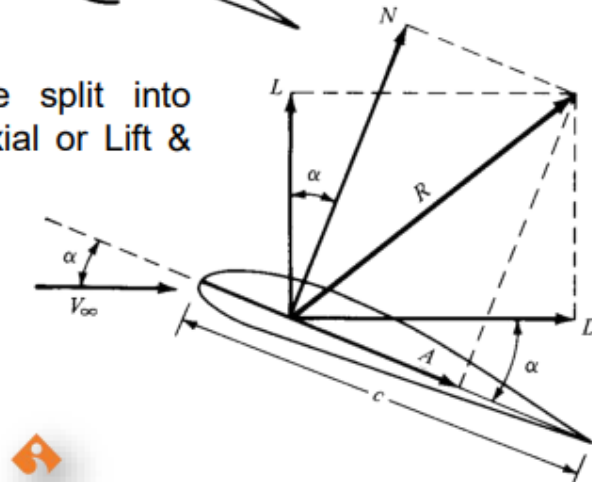


Aerodynamic forces and moments

- The net effect of the p and τ distributions integrated over the complete body surface is a resultant aerodynamic force R and moment M on the body.



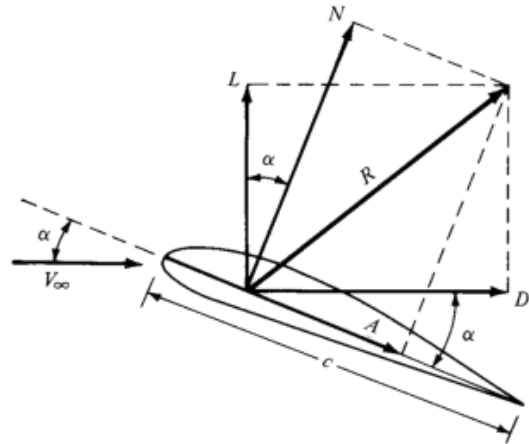
- The resultant R can be split into components, Normal & Axial or Lift & Drag forces.





Aerodynamic forces and moments

- The flow far away from the body is called the *freestream*, and hence V_∞ is also called the freestream velocity.
- The chord c is the linear distance from the leading edge to the trailing edge of the body.
- The angle of attack α is defined as the angle between c and V_∞ .
- The geometrical relation between these two sets of components is,



L ; component of R perpendicular to V_∞
 D ; component of R parallel to V_∞

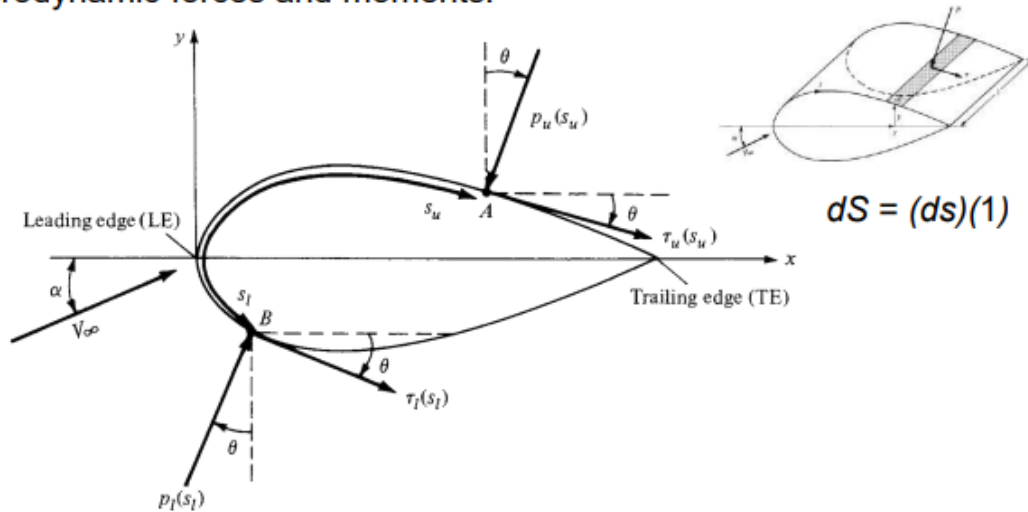
$$L = N \cos \alpha - A \sin \alpha$$

$$D = N \sin \alpha + A \cos \alpha$$



Aerodynamic forces and moments

- We can examine in more detail the integration of the pressure and shear stress distributions to obtain the aerodynamic forces and moments.



For the upper body surface,

$$dN'_u = -p_u ds_u \cos \theta - \tau_u ds_u \sin \theta$$

$$dA'_u = -p_u ds_u \sin \theta + \tau_u ds_u \cos \theta$$

For the lower body surface,

$$dN'_l = p_l ds_l \cos \theta - \tau_l ds_l \sin \theta$$

$$dA'_l = p_l ds_l \sin \theta + \tau_l ds_l \cos \theta$$





Aerodynamic forces and moments

- The total normal and axial forces *per unit span* are obtained by integrating equations from the leading edge (LE) to the trailing edge (TE):

$$N' = - \int_{LE}^{TE} (p_u \cos \theta + \tau_u \sin \theta) ds_u + \int_{LE}^{TE} (p_l \cos \theta - \tau_l \sin \theta) ds_l$$

$$A' = \int_{LE}^{TE} (-p_u \sin \theta + \tau_u \cos \theta) ds_u + \int_{LE}^{TE} (p_l \sin \theta + \tau_l \cos \theta) ds_l$$

- We can get lift and drag forces based on the previous equations;

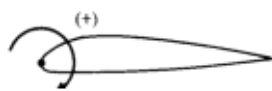
$$L = N \cos \alpha - A \sin \alpha$$

$$D = N \sin \alpha + A \cos \alpha$$



Aerodynamic forces and moments

- The aerodynamic moment exerted on the body depends on the point about which moments are taken.
- Lets consider moments taken about the leading edge.
- The moment per unit span about the leading edge due to p and τ on the elemental area dS on the upper and lower surface are



$$\begin{aligned}dM'_u &= (p_u \cos \theta + \tau_u \sin \theta)x ds_u + (-p_u \sin \theta + \tau_u \cos \theta)y ds_u \\dM'_l &= (-p_l \cos \theta + \tau_l \sin \theta)x ds_l + (p_l \sin \theta + \tau_l \cos \theta)y ds_l\end{aligned}$$

- By integrating from the leading to the trailing edges, we obtain the pitching moment about the leading edge per unit span

$$\begin{aligned}M'_{LE} &= \int_{LE}^{TE} [(p_u \cos \theta + \tau_u \sin \theta)x - (p_u \sin \theta - \tau_u \cos \theta)y] ds_u \\ &+ \int_{LE}^{TE} [(-p_l \cos \theta + \tau_l \sin \theta)x + (p_l \sin \theta + \tau_l \cos \theta)y] ds_l\end{aligned}$$





Aerodynamic forces and moments

- In Equations; θ , x , and y are known functions of s for a given body shape.
- A major goal of theoretical or experimental aerodynamics is to calculate $p(s)$ and $\tau(s)$ for a given body shape and freestream conditions.
- We get the aerodynamic forces and moments based on them.
- In aerodynamics, shape is probably the most important factor.
- We may eliminate the scale of the shape by defining some dimensionless coefficients.





Aerodynamic forces and moments

- Let ρ - and V -be the density and velocity, respectively, in the freestream, far ahead of the body.
- We define a dimensional quantity called the freestream *dynamic pressure* as

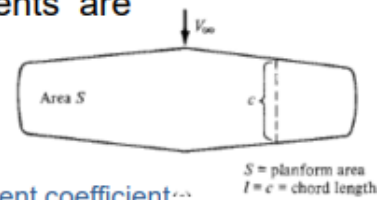
$$q_{\infty} \equiv \frac{1}{2} \rho_{\infty} V_{\infty}^2$$

- In addition, let S be a reference area and l be a reference length.
- The dimensionless force and moment coefficients are defined as follows:

$$C_L \equiv \frac{L}{q_{\infty} S} \quad \text{Lift coefficient}$$

$$C_D \equiv \frac{D}{q_{\infty} S} \quad \text{Drag coefficient}$$

$$C_M \equiv \frac{M}{q_{\infty} S l} \quad \text{Moment coefficient}$$





Aerodynamic forces and moments

- For two-dimensional bodies, it is conventional to denote the aerodynamic coefficients by lowercase letters; for example,

$$c_l \equiv \frac{L'}{q_\infty c} \quad c_d \equiv \frac{D'}{q_\infty c} \quad c_m \equiv \frac{M'}{q_\infty c^2}$$

- Two additional dimensionless quantities of immediate use are

Pressure coefficient $C_p \equiv \frac{p - p_\infty}{q_\infty}$

p local static pressure

p_∞ static free stream pressure

q_∞ dynamic free stream pressure

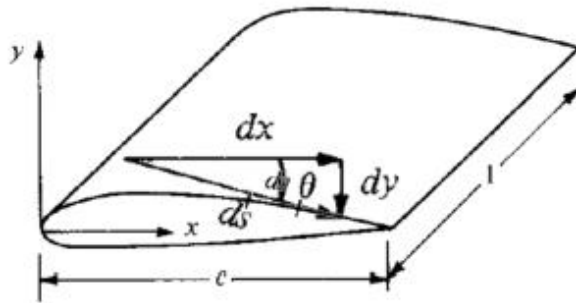
Skin friction coefficient $c_f \equiv \frac{\tau}{q_\infty}$

- From the geometry

$$dx = ds \cos \theta$$

$$dy = -(ds \sin \theta)$$

$$S = c(1)$$





Aerodynamic forces and moments

$$C_N \equiv \frac{N}{q_\infty S}$$

$$C_A \equiv \frac{A}{q_\infty S}$$

- We obtain the following integral forms for the force and moment coefficients

$$c_n = \frac{1}{c} \left[\int_0^c (C_{p,l} - C_{p,u}) dx + \int_0^c \left(c_{f,u} \frac{dy_u}{dx} + c_{f,l} \frac{dy_l}{dx} \right) dx \right]$$

$$c_a = \frac{1}{c} \left[\int_0^c \left(C_{p,u} \frac{dy_u}{dx} - C_{p,l} \frac{dy_l}{dx} \right) dx + \int_0^c (c_{f,u} + c_{f,l}) dx \right]$$

$$c_{m_{LE}} = \frac{1}{c^2} \left[\int_0^c (C_{p,u} - C_{p,l}) x dx - \int_0^c \left(c_{f,u} \frac{dy_u}{dx} + c_{f,l} \frac{dy_l}{dx} \right) x dx \right. \\ \left. + \int_0^c \left(C_{p,u} \frac{dy_u}{dx} + c_{f,u} \right) y_u dx + \int_0^c \left(-C_{p,l} \frac{dy_l}{dx} + c_{f,l} \right) y_l dx \right]$$

- The lift and drag coefficients can also be obtained:

$$c_l = c_n \cos \alpha - c_a \sin \alpha$$

$$c_d = c_n \sin \alpha + c_a \cos \alpha$$