



Two mark Questions and Answers

1. State Lagrange's interpolation formula.

Solution:

Let $y=f(x)$ be a function which takes the values $y_0, y_1, y_2, \dots, y_n$ corresponding to $x=x_0, x_1, x_2, \dots, x_n$.

Then, Lagrange's interpolation formula is

$$y = f(x) = \frac{(x - x_1)(x - x_2)\dots(x - x_n)}{(x_0 - x_1)(x_0 - x_2)\dots(x_0 - x_n)} y_0 + \frac{(x - x_0)(x - x_2)\dots(x - x_n)}{(x_1 - x_0)(x_1 - x_2)\dots(x_1 - x_n)} y_1 + \dots \dots \dots \\ + \frac{(x - x_0)(x - x_1)\dots(x - x_{n-1})}{(x_n - x_0)(x_n - x_1)\dots(x_n - x_{n-1})} y_n$$

2. What is Inverse interpolation?

Solution:

Inverse interpolation is the process of finding the value of x corresponding to a value of y , not present in the table.

3. Give the inverse of lagrange's interpolation formula.

Solution:

$$x = \frac{(y - y_1)(y - y_2)\dots(y - y_n)}{(y_0 - y_1)(y_0 - y_2)\dots(y_0 - y_n)} x_0 + \frac{(y - y_0)(y - y_2)\dots(y - y_n)}{(y_1 - y_0)(y_1 - y_2)\dots(y_1 - y_n)} x_1 + \dots \dots \dots \\ + \frac{(y - y_0)(y - y_1)\dots(y - y_{n-1})}{(y_n - y_1)(y_n - y_2)\dots(y_n - y_{n-1})} x_n$$

4. What is the advantage of Lagrange's formula?

Solution: Lagrange's interpolation formula can be used whether the values of x , the independent variable are equally spaced or not whether the difference of y become smaller or not.

5. Derive Newton's backward difference formula by using operator method. [Gregory Newton's backward difference interpolation formula].

Solution:

$$y(x) = f(x) = P_n(x)$$

$$= y_n + \frac{u}{1!} \nabla y_n + \frac{u(u+1)}{2!} \nabla^2 y_n + \frac{u(u+1)(u+2)}{3!} \nabla^3 y_n + \dots \dots \dots \\ + \frac{u(u+1)(u+2)\dots(u+(n-1))}{n!} \nabla^n y_n$$

$$\text{where } u = \frac{x - x_n}{h}$$

6. State Gregory Newton's forward difference interpolation formula.

Solution:

$$\begin{aligned}
 y(x) &= f(x) = P_n(x) \\
 &= y_0 + \frac{u}{1!} \Delta y_0 + \frac{u(u-1)}{2!} \Delta^2 y_0 + \frac{u(u-1)(u-2)}{3!} \Delta^3 y_0 + \dots \\
 &\quad + \frac{u(u-1)(u-2)\dots(u-(n-1))}{n!} \Delta^n y_0
 \end{aligned}$$

where $u = \frac{x-x_0}{h}$

7. Given $f(0)=-2, f(1)=2$ and $f(2)=8$. Find the polynomial using Newton's interpolation formula.

Solution:

x	y=f(x)	$\Delta f(x)$	$\Delta^2 f(x)$
0	-2	4	
1	2	6	2
2	8		

By Newton's forward difference interpolation

$$\begin{aligned}
 y(x) &= y_0 + \frac{u}{1!} \Delta y_0 + \frac{u(u-1)}{2!} \Delta^2 y_0 + \frac{u(u-1)(u-2)}{3!} \Delta^3 y_0 + \dots \\
 \text{formula} &\quad + \frac{u(u-1)(u-2)\dots(u-(n-1))}{n!} \Delta^n y_0 \\
 \text{where } u &= \frac{x-x_0}{h}
 \end{aligned}$$

Here

$$x_0 = 0, h = 1 \Rightarrow u = x$$

$$\begin{aligned}
 \therefore y(x) &= -2 + \frac{x}{1!}(4) + \frac{x(x-1)}{2!}(2) \\
 &= -2 + 4x + x(x-1) \\
 &= x^2 + 3x - 2.
 \end{aligned}$$

8. State the merits and demerits of Newton's forward and backward interpolation formula.

Merits:

Newton's forward and backward interpolation formula are applicable for interpolation near the beginning and end respectively of tabulated values.

Demerits:

Newton's forward and backward interpolation formula used only for equal intervals (or) equidistant intervals.

9. Using Newton's forward difference formula, write the formula for the first, second and third order derivatives at $x=x_0$

Solution:

$$\begin{aligned}
 \left(\frac{dy}{dx} \right)_{x=x_0} &= \frac{1}{h} \left[\Delta y_0 - \frac{1}{2} \Delta^2 y_0 + \frac{1}{3} \Delta^3 y_0 - \frac{1}{4} \Delta^4 y_0 + \dots \right] \\
 \left(\frac{d^2 y}{dx^2} \right)_{x=x_0} &= \frac{1}{h^2} \left[\Delta^2 y_0 - \Delta^3 y_0 + \frac{11}{12} \Delta^4 y_0 - \frac{5}{6} \Delta^5 y_0 + \dots \right] \\
 \left(\frac{d^3 y}{dx^3} \right)_{x=x_0} &= \frac{1}{h^3} \left[\Delta^3 y_0 - \frac{3}{2} \Delta^4 y_0 + \dots \right]
 \end{aligned}$$

10. Construct an Newton difference table for the points (0,-1),(1,1),(2,1) and (3,-2).

Solution:

Difference table :

x	y	Δy	$\Delta^2 y$	$\Delta^3 y$
0	-1			
1	1	1+1:2	0-2:-2	
2	1	1-1:0	-3-0:-3	-3+2:-1
3	-2	-2-1:-3		

11. State Trapezoidal rule.

$$\int_{x_0}^{x_n} y dx = \frac{h}{2} [(y_0 + y_n) + 2(y_1 + y_2 + \dots + y_{n-1})] \text{ where } h = \frac{b-a}{n}$$

$$= \frac{h}{2} [A + 2B]$$

where A=sum of the first and last ordinates & B=sum of the remaining ordinates.

12. Using Newton's backward difference formula, write the formula for the first, second and third order derivatives at $x=x_n$

Solution:

$$\left(\frac{dy}{dx} \right)_{x=x_n} = \frac{1}{h} \left[\nabla y_n + \frac{1}{2} \nabla^2 y_n + \frac{1}{3} \nabla^3 y_n + \frac{1}{4} \nabla^4 y_n + \dots \right]$$

$$\left(\frac{d^2 y}{dx^2} \right)_{x=x_n} = \frac{1}{h^2} \left[\nabla^2 y_n + \nabla^3 y_n + \frac{11}{12} \nabla^4 y_n + \frac{5}{6} \nabla^5 y_n + \dots \right]$$

$$\left(\frac{d^3 y}{dx^3} \right)_{x=x_n} = \frac{1}{h^3} \left[\nabla^3 y_n + \frac{3}{2} \nabla^4 y_n + \dots \right]$$

13. Find $\frac{dy}{dx}$ at $x=1$ from the following table:

x	1	2	3	4
y	1	8	27	64

Solution:

y	Δ	Δ^2	Δ^3

1			
8	7	12	6
27	19	18	
64	37		

$$\left(\frac{dy}{dx}\right)_{x=x_0} = \frac{1}{h} \left[\Delta y_0 - \frac{1}{2} \Delta^2 y_0 + \frac{1}{3} \Delta^3 y_0 \right]$$

$$= (1) \left[7 - \frac{12}{2} + \frac{6}{3} \right] = 3$$

14. State Simpson's 3/8 rule.

$$\int_{x_0}^{x_n} y dx = \frac{3h}{8} [(y_0 + y_n) + 3(y_1 + y_2 + y_4 + y_5 + \dots + y_{n-1}) + 2(y_3 + y_6 + \dots + y_{n-3})] \text{ where } h = \frac{b-a}{n}$$

15. State Simpson's 1/3 rule.

$$\int_{x_0}^{x_n} y dx = \frac{h}{3} [(y_0 + y_n) + 4(y_1 + y_3 + \dots + y_{n-1}) + 2(y_2 + y_4 + \dots + y_{n-2})] \text{ where } h = \frac{b-a}{n}$$

$$= \frac{h}{3} [A + 4B + 2C]$$

where A = sum of the first and last ordinates.

B = sum of the odd ordinates

C = sum of the even ordinates

16. Evaluate $\int_{1/2}^1 \frac{1}{x} dx$ by Trapezoidal rule, dividing the range into 4 equal parts.

Solution:

$$h = \frac{1 - \frac{1}{2}}{4} = \frac{1}{8}$$

x	1/2	5/8	6/8	7/8	8/8
f(x)	8/4	8/5	8/6	8/7	8/8

$$\therefore \int_{1/2}^1 \frac{1}{x} dx = \frac{1}{8} \cdot \frac{1}{2} \left[\left(\frac{8}{4} + \frac{8}{8} \right) + 2 \left(\frac{8}{5} + \frac{8}{6} + \frac{8}{7} \right) \right]$$

$$= \frac{1}{16} \left[3 + 2 \left(\frac{856}{210} \right) \right] = \frac{1171}{1680} = 0.6971$$

17. Evaluate $\int_0^1 \frac{dx}{1+x^2}$ with h=1/6 by Trapezoidal rule.

Solution:

Given $f(x) = \int_0^1 \frac{dx}{1+x^2}$, $h = 1/6$

x	0	1/6	2/6	3/6	4/6	5/6	6/6
f(x)	1	36/37	9/10	4/5	9/13	36/31	1/2

$$\therefore \int_0^1 \frac{dx}{1+x^2} = \frac{1}{12} \left[\left(1 + \frac{1}{2} \right) + 2 \left(\frac{36}{37} + \frac{9}{10} + \frac{4}{5} + \frac{9}{13} + \frac{36}{31} \right) \right] \\ = 0.7842$$

18. Using Simpson's rule (one-third) evaluate $\int_0^1 xe^x dx$ taking 4 intervals. Compare your result with actual value.

Solution:

Given $f(x) = xe^x$; $h = \frac{1}{4} = 0.25$

x	0	0.25	0.5	0.75	1
f(x)	1	0.321	0.824	1.588	2.718

By Simpson's 1/3 rule

$$\therefore \int_0^1 xe^x dx = \frac{0.25}{3} \left[(0 + 2.718) + 2(0.321 + 1.588) + 4(0.524) \right] \\ = 0.819 = 1$$

By actual integration

$$\int_0^1 xe^x dx = [xe^x - e^x]_0^1 = e^1 - e^0 - (0 - 1) = 1$$

19. Evaluate $\int_0^6 \frac{dx}{1+x^2}$ by Simpson's 3/8 rule & check by actual integration.

Solution:

Given $f(x) = \frac{1}{1+x^2}$; $h = \frac{6-0}{6} = 1$

x	0	1	2	3	4	5	6
f(x)	1	0.500	0.200	0.100	0.0588	0.0384	0.02702

By Simpson's 3/8 rule,

$$\therefore \int_0^6 \frac{dx}{1+x^2} = \frac{3h}{8} \left[(y_0 + y_n) + 3(y_1 + y_2 + \dots + y_{n-1}) + 2(y_3 + y_6 + \dots + y_{n-3}) \right] \\ = \frac{3}{8} \left[(1 + 0.2702) + 3(0.5 + 0.2 + 0.0588 + 0.0384) + 2(0.1) \right] \\ = 1.3570$$

By actual integration,

$$\int_0^6 \frac{dx}{1+x^2} = \left[\tan^{-1}(x) \right]_0^6 = \tan^{-1}(6) = 1.4056$$

20. What are the errors in Trapezoidal & Simpson's rules of numerical integration?

Solution:

Error in Trapezoidal rule $|E| < \frac{(b-a)}{12} h^2 M$; order is h^2

Error in Simpson's rule $|E| < \frac{(b-a)}{180} h^4 M$; order is h^4