

SNS COLLEGE OF TECHNOLOGY An Autonomous Institution Coimbatore-35

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DEPARTMENT OF ELECTRONICS & COMMUNICATION ENGINEERING 19ECB212 – DIGITAL SIGNAL PROCESSING

II YEAR/ IV SEMESTER

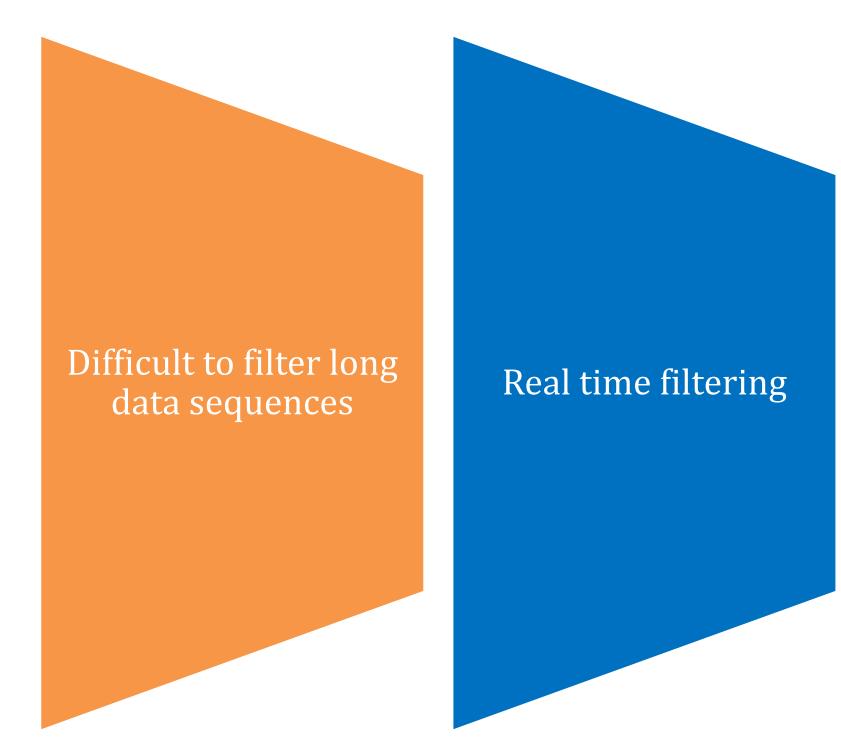
UNIT 1 – DISCRETE FOURIER TRANSFORM

TOPIC – Overlap Add Method









19/02/2023

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Filtering of long data sequence is Slow



SECTIONED CONVOLUTION

- The response of an LTI system for any arbitrary input is given by linear convolution of the input and the impulse response of the system
- The input sequence or impulse response sequence is very much larger than the other, then it is very difficult to compute the linear convolution for the following reasons:
- The entire sequence should be available before convolution can be carried out. This makes long delay in getting the output
- Large amounts of memory is required to store the sequences







SECTIONED CONVOLUTION

In this technique the larger sequence is sectioned (or splitted) into the

size of smaller sequence

- Then the linear convolution of each section of longer sequence and the smaller sequence is performed
- The output sequences obtained from the convolutions of all the sections are combined to get the overall output sequence







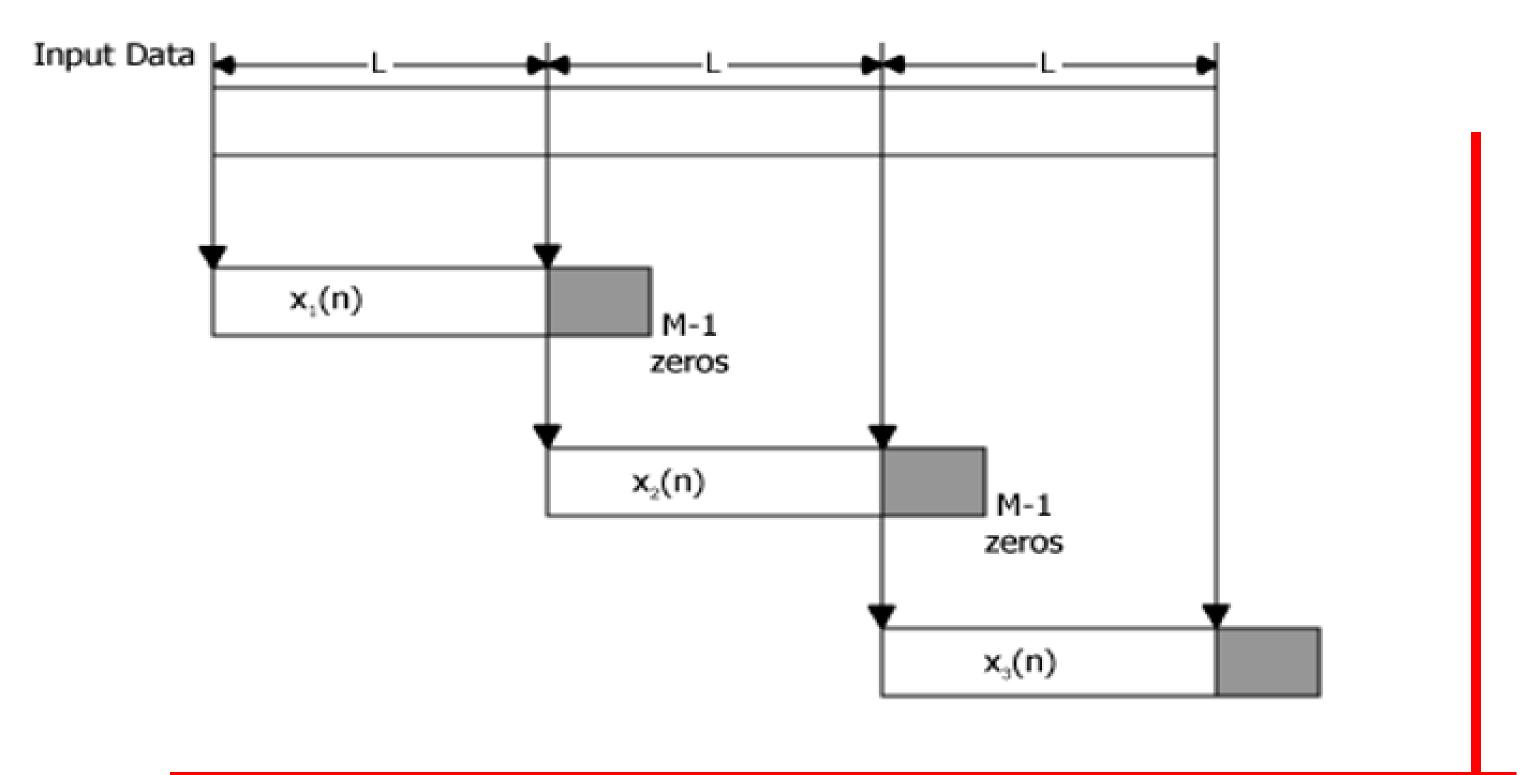
SECTIONED CONVOLUTION

- There are two methods of sectioned convolutions. They are ullet
- **Overlap add method** \bullet
- **Overlap save method** \bullet









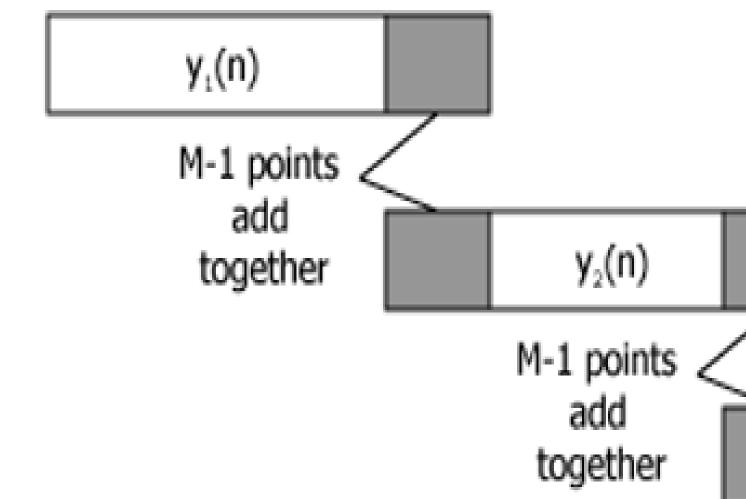
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Output Data



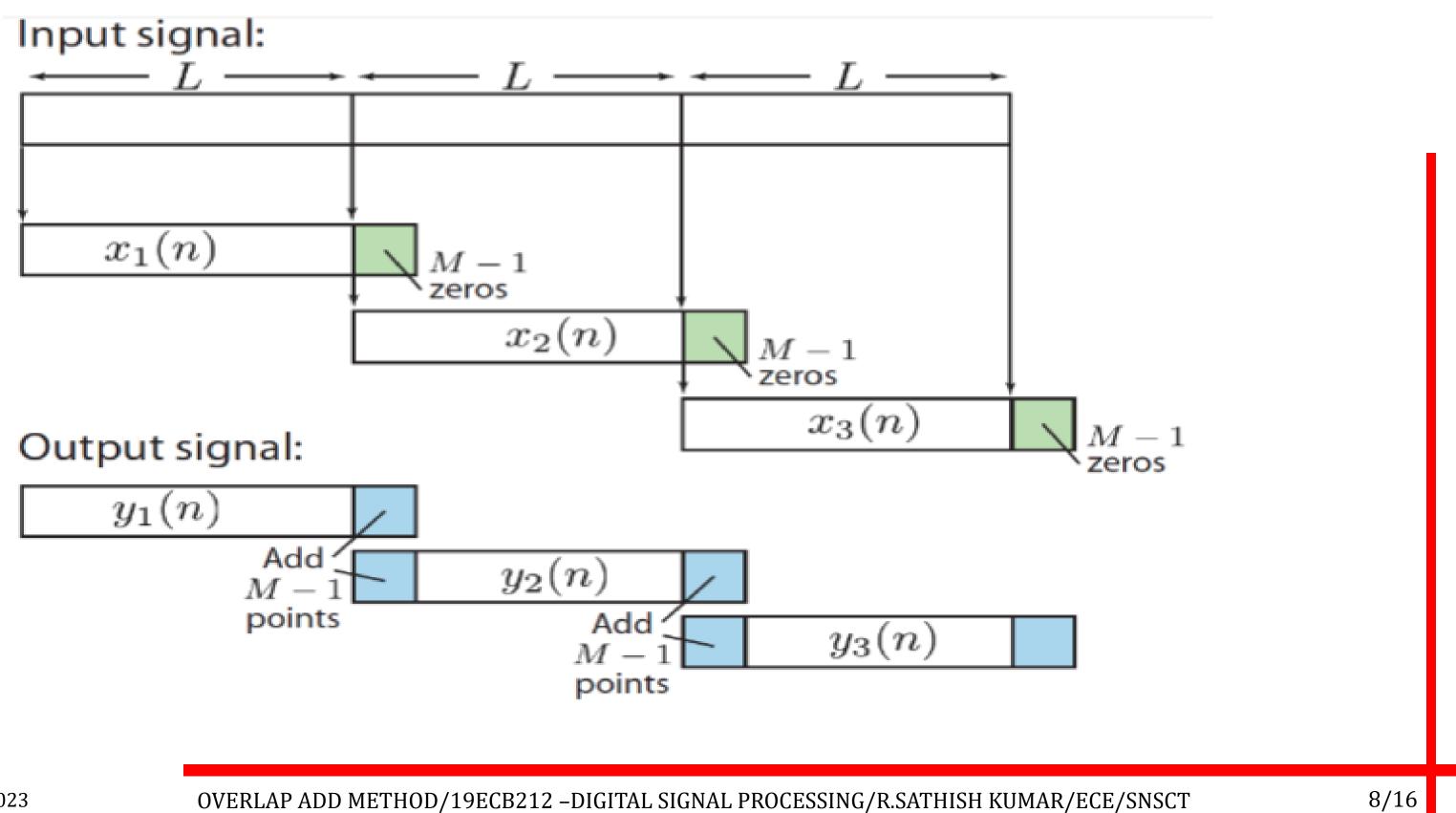
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y₃(n)	





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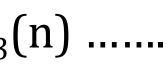




- Step 1: Divide the longer sequence into small sequences x(n) – Long sequence and h(n) – Small Sequence Then divide x(n) into $x_1(n)$, $x_2(n)$, $x_3(n)$
- Length of $x_1(n)$ (or) Length of $x_2(n)$ (or) Length of $x_3(n)$ = Length of h(n)....
- Step 2: Find $y_1(n)$ then $y_1(n) = x_1(n) * h(n)$
- Step 3: Find $y_2(n), y_3(n) \dots$
- Step 4: Combine all the outputs $y_1(n)$, $y_2(n)$, $y_3(n)$









- Find the linear convolution x(n) = {1,2,3,4,4,3,2,1} and h(n) = {-1,1} using Overlap Add Method:
- **Step 1:** Divide longer sequence into small subsequences
- x(n) = Longer sequence and h(n) = Small sequencelacksquare

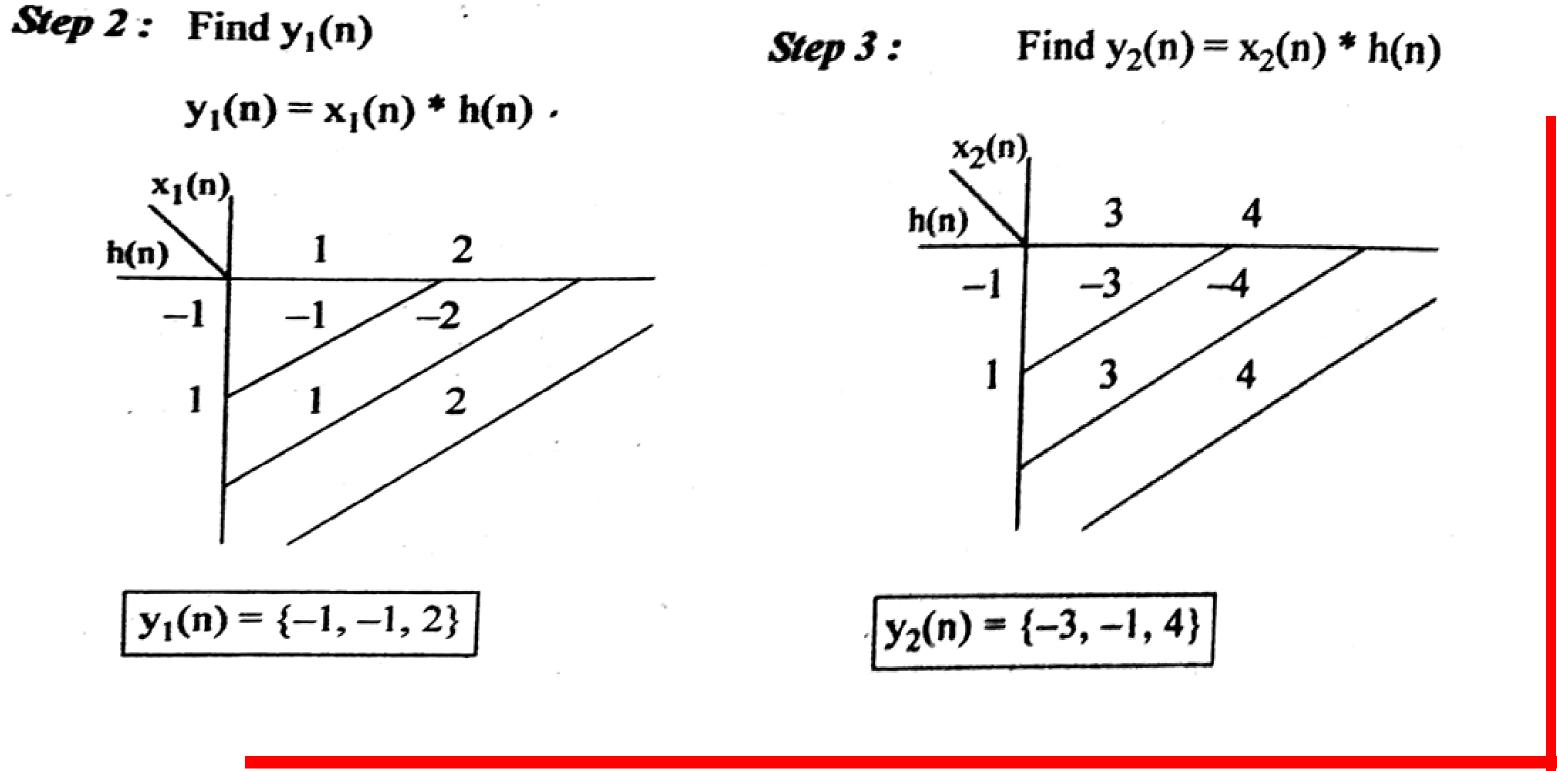
x(n) is divided as below

- $x_1(n) = \{1,2\}, x_2(n) = \{3,4\}, x_3(n) = \{4,3\}, x_4(n) = \{2,1\}$
- Length of $x_1(n)$ or $x_2(n)$ or $x_3(n)$ or $x_4(n) =$ Length of h(n)





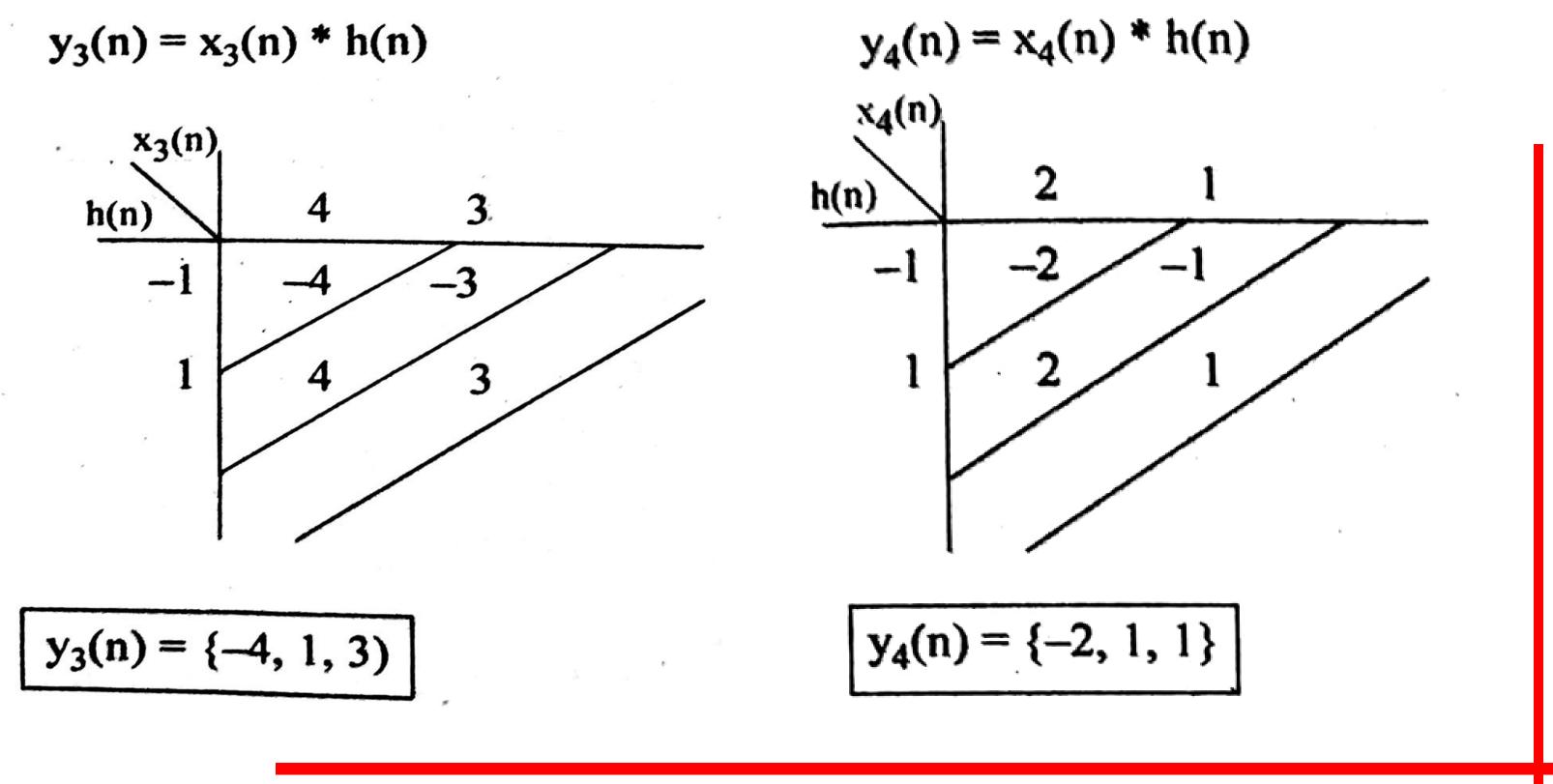




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Step 4 : Combine all the outputs :

n	0	1	2 ·	3	4	5	6	7	8
y _l (n)	. –1	-1	2						
y ₂ (n)			-3	-1	4				
y ₃ (n)					4	1	3		
y ₄ (n)							-2	1	1
	-1	-1	-1	-1	0	1	1	1	1

 $y(n) = \{-1, -1, -1, -1, 0, 1, 1, 1, 1\}$

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APPLICATIONS





Communication Signal Processing

To remove noise which are added during transmission can be removed * using filter where the operation involved is convolution

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ASSESSMENT

- List the methods involved to compute sectioned convolution.
- Mention some applications of sectioned Convolution. 2.
- What is meant by sectioned Convolution. 3.
- 4. Determine linear convolution $x(n) = \{1, 2, 3, 4, 4, 3, 2, 1\}$ and $h(n) = \{-1, 1\}$ using Overlap Add Method
- The output sequences obtained from the convolutions of all the sections 5. are combined to get the overall ------ sequence





THANK YOU

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