

SNS COLLEGE OF TECHNOLOGY COIMBATORE-35 DEPARTMENT OF MECHANICAL ENGINEERING



UNIT I INTRODUCTION & UNIT II ONE DIMENSIONAL PROBLEMS

16ME401 Finite Element Analysis

1	Why are polynomial types of interpolation functions preferred over	(May/June 2013)
	trigonometric functions?	
	Polynomial functions are preferred over trigonometric functions due to	
	the following reasons:	
	1. It is easy to formulate and computerize the finite element equations	
	2. It is easy to perform differentiation or integration	
	3. The accuracy of the results can be improved by increasing the order of	
	the polynomial.	
2.	Distinguish Natural & Essential boundary condition	(May/June 2009)
	There are two types of boundary conditions.	
	They are:	
	1. Primary boundary condition (or) Essential boundary condition	
	The boundary condition, which in terms of field variable, is known as	
	primary boundary condition.	
	2. Secondary boundary condition or natural boundary conditions	
	The boundary conditions, which are in the differential form of field	
	variables, are known as secondary boundary condition.	
	Example: A bar is subjected to axial load shown in fig.	
	In this problem, displacement u at node $1 = 0$.	
	that is primary boundary condition.	
	$AE\frac{du}{dx} = P$, that is secondary boundary	
	condition.	
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3.	What do you mean by Boundary value problem?	
	The solution of differential equation is obtained for physical problems,	
	which satisfies some specified conditions known as boundary conditions.	
	The differential equation together with these boundary conditions,	
	subjected to a boundary value problem.	
	Examples: Boundary value problem.	
	$\frac{d^2y}{dx^2} - a(x)\frac{dy}{dx} - b(x)y = 0$ with boundary conditions, y(m) = S and y(n) = T.	
4.	What do you mean by weak formulation? State its advantages.	(April/May 2015), (May/June
	A weak form is a weighted integral statement of a differential equation	2013)
	in which the differentiation is distributed among the dependent variable	
	and the weight function and also includes the natural boundary	
	conditions of the problem.	
	• A much wider choice of trial functions can be used.	

	• The weak form can be developed for any higher order differential	
	equation.	
	 Natural boundary conditions are directly applied in the differential 	
	equation.	
	 The trial solution satisfies the essential boundary conditions 	
5.	What is Rayleigh-Ritz method?	(NOV/DEC 2015)
	Rayleigh-Ritz method is a integral approach method which is useful for	
	solving complex structural problems, encountered in finite element	
	analysis. This method is possible only if a suitable functional is available.	
6.	What is meant by degrees of freedom?	
	When the force or reactions act at nodal point, node is subjected to	
	deformation. The deformation includes displacement, rotations, and/or	
	strains. These are collectively known as degrees of freedom.	
7.	What is "Aspect ratio"?	
	Aspect ratio is defined as the ratio of the largest dimension of the	
	element to the smallest dimension. In many cases, as the aspect ratio	
	increases, the inaccuracy of the solution increases. The conclusion of	
	many researches is that the aspect ratio should be close to unity as	
	possible.	
8.	What are 'h' and 'p' versions of finite element method?	
	h' versions and 'p' versions are used to improve the accuracy of the finite	
	element method.	
	In 'h' versions, the order of polynomial approximation for all elements is	
	kept constant and the numbers of elements are increased.	
	In 'p' version, the numbers of elements are maintained constant and the	
	order of polynomial approximation of element is increased.	
9.	What is Discretization?	(NOV/DEC 2015)
	The art of subdividing a structure into a convenient number of smaller	
10	components is known as Discretization.	
10.	During Discretization, mention the places where it is necessary to	
	place a node: The following places are personny to place a pode during Disorptization	
	The following places are necessary to place a node during Discretization	
	(i) Concentrated load acting point	
	(ii) Cross-section changing point	
	(iii) Different material inter junction point	
	(iv) Sudden change in load point.	
11.	What is natural co-ordinate?	(Nov/Dec 2014),
	A natural co-ordinate system is used to define any point inside the	
	element by a set of dimensionless numbers. whose magnitude never	
	exceeds unity, this system is useful in assembling of stiffness matrices.	
12.	Explain force method and stiffness method?	
	In force method, internal forces are considered as the unknowns of the	
	problem. In displacement or stiffness method, displacements of the	

	nodes are considered as the unknowns of the problem. Among them two	
	approaches, displacement method is desirable.	
13.	Define shape function. State its characteristics	(May/June 2014), (Nov/Dec 2014), (Nov/Dec 2012)
	In finite element method, field variables within an element are generally	
	expressed by the following approximate relation:	
	$u(x, y) = N_1(x, y)u_1 + N_2(x, y)u_2 + N_3(x, y)u_3$	
	Where u_1 , u_2 , u_3 are the values of the field variable at the nodes and N_1	
	N_2 , N_3 are interpolation function. N_1 , N_2 , N_3 is called shape functions	
	because they are used to express the geometry or shape of the element.	
	The characteristics of the shape functions are follows:	
	1. The shape function has unit value at one nodal point and zero value at	
	the other nodes.	
	2.The sum of the shape function is equal to one.	
14.	How do you calculate the size of the global stiffness matrix?	
	Global the matrix size=Number of nodes \times { <i>Degress of</i> freedom}	
15.	Give the general expression for element stiffness matrix.	(Nov/Dec 2015)
	stiffness matrix. $[K] = \int [B]^T [D] [B] dv$	
	$[B] \Rightarrow$ strain displacement matrix [Row matrix]	
	$[D] \Rightarrow$ stress, strain relationship matrix [Row matrix]	
16.	Write down the expression of stiffness matrix for one dimensional bar	
	element.	
	For 1D linear bar element $[k] = \frac{AE}{L} \begin{vmatrix} 1 & -1 \\ -1 & 1 \end{vmatrix}$	
	A-Area of the element mm ²	
	E-Young's Modulus of the element N/mm^2	
	L-length of the element	
17.	State the properties of a stiffness matrix.	[AU, Jan 2006]
	The properties of a stiffness matrix [K] are:	
	1. It is symmetric matrix.	
	2. The sum of elements in any column must be equal to zero.	
	3. It is an unstable element. So, the determinant is equal to zero	
18.	Write down the general finite element equation	
	General finite element equation is,	
	$\{F\} = [K] \{u\}$	
	where, $\{F\} \rightarrow$ Force vector [Column matrix].	
	$\{u\} \rightarrow \text{Degrees of freedom [Column metrix]}$	
19	Write down the finite element equation for one dimensional two	
15.	noded har element	
	The finite element equation for one dimensional two noded has element	
	is, $\frac{AE}{L}\begin{bmatrix} 1 & -1\\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1\\ u_2 \end{bmatrix} = \begin{bmatrix} F_1\\ F_2 \end{bmatrix}$	

20.	Define total potential energy.	
	The total potential energy 1t of an elastic body is defined as the sum of total strain energy U and the potential energy of the external forces, (W).	
	Total potential energy, π = Strain energy (U) + { Potential energy of the external forces (W) }	





The differential equation of physical phenomenon is given by $\frac{d^2y}{dx^2} + 500x^2 = 0, \ 0 \le x \le 1$,

Trial function, $y = a_1(x - x^4)$, Boundary condition are, y(0)=0, y(1)=0 calculate the value of the parameter arby the following methods. (i) Point collocation method (ii) Sub-domain collocation method (iii) least Square Method and (iv) Galerkin's method.

Viven: Differential equation Trial function, y = a, (x-x4) Boundary condition are, y(0)=0, y(0=0 To find: The value of parameter a, by, i. point collocation method, ii. Subdomain method, iii. Least Squares method, iv. Galerkin Solution: First we have to verify, whether the. trial function satisfies the boundary condition Trial function is, y = a, (x-x4) When pc := 0, $y = a_1(0-0) = 0$ $x = 1 - y = a_1 (1 - 14) = 0$ Hence it satisfies the boundary conditions, (i) point collocation method: $y = a_1 (x - x + y)$ r= 9;(1-4x3) el Il sado dac2= a, Co - 1202) Prepared by Dr.M. SUBRAMANIAN/Professor/Mechanical/16ME402/ Finite Element Analysis



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Substituting dry value in given differential equation (1), -> dry + 500x2=0 \Rightarrow Residual, $R = -12a_1x^2 + 500x^2$ In point collocation wetted, residuals are set to zero. R = -12a102 + 50002 = 0 ->3 In this problem, we have to find only one parameter, a, . so, only one Collocation point is needed. The point way be chosen between o and 1. Let us take 1/2, Substituting oc = 1/2 in equation 3 $R = -12 a_1 \left[\frac{1}{2} \right]^2 + 500 \left[\frac{1}{2} \right]^2 = 0$ $\Rightarrow -i2 a_1 \left[\frac{1}{4} \right] + 500 \left[\frac{1}{4} \right] = 0$ -3a1+125 =0 a1=41.66 Hence the trial functionis y=41.66 (x-x4)

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(i) Subdomain Collocation method: This method requires JRdx Substitute & Value $\begin{bmatrix} -12a_1x^2 + 500x^2 \end{bmatrix} dx = 0$ + 500 [2] 120, 1291 + 500 [1-12 ag 500 12a, 12.a, 500 a1 = 500 12 41.66 Trial functions is y = 41.66(x-2) (iii) Least squares method: This wettood nequire, I = It can callso be written ay R OR da 2

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ME402 Finite Element Analysis UNIT I INTRODUCTION We know that, R = -12a, x2 + 500x = -12,002 Substitute R and DR values in ⇒ <u>ƏT</u> Da, = [-12a, 22+50002] (-1202) doc The requirement is, $\frac{\partial I}{\partial a_1} = 0$. $\Rightarrow \left(\frac{1}{1 - 12a_1x^2} + 500x^2 \right) \left(-12x^2 \right) doc = 0$ [1449,24 - 6000x4) ol x =0 $1449, \left[\frac{x^5}{5}\right] - 6000 \left[\frac{x^5}{5}\right] = 0$ <u>144a</u> [1-0] - 6000 [1-0] = 0 $\frac{14491}{5} = \frac{6000}{5} = 0 \implies 9_1 = \frac{6000}{100} = 41.6b$ a1=41.66 a Director Prepared by Dr.M. SUBRAMANIAN/Professor/Mechanical/16ME402/ Finite Element Analysis



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(v) Galorkin's method: In this method, the trial function itselfs is considered as the weighting function, wi => [w; Rdx=0 Hore, the trial function is y= W; = a, Cx-x4) Substitute Wi and R values in equation® $\int (x - 2x^4) (-12a_1 x^2 + 500 x^2) dx = 0$ a) (2-24) (-12a, 22+500 22) doc =0 -12 ay 23 + 500x3 + 12 a12 - 500x dx=0 $\left[-12a, \left[\frac{x^{4}}{4}\right]^{1} + 500\left[\frac{x^{4}}{4}\right]^{1} + 12a, \left[\frac{3c^{7}}{4}\right]^{1} - 500\left[\frac{x^{7}}{4}\right]^{2}$ $\frac{-12a_{1}}{4}\left[1-0\right] + \frac{500}{4}\left[1-0\right] + \frac{12a_{1}}{2}\left(1-0\right) - \frac{500}{4}\left(1-0\right) - \frac{$ -39,+125+1-71AA1-71.428 =0 -1.286 Q1 = - 53.572 9,=41.66 --· (9) Torial function is y=4166(x-x4) From equation 4, 5,7, and 9, we know that the Value of parameter a is Same for all the four methods of parameter a is Same for all a by Dr.M. SUBRAMANTAN/Professor/Mechanical/16ME40\$/ Finite Element Analysis Result: parameter, a, [For all the four wethods] =41.66



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= 0.

Weighted residual techniques

Consider a uniform rod subjected to a uniform axial load as illustrated in figure . It can be readily shown that the deformation of the bar is governed by the differential equation

 $AE\frac{d^2u}{dx^2} + q_0 = 0$ with the boundary conditions u(0)=0, $\frac{du}{dx} = 0$, Estimate the deformation

of bar using the weighted residual method.



with the boundary conditions u(0) =

Weighted residual Methods

(i) Point collocation method:R(x)=0

(ii) Subdomain collocation method: $\int R(x)dx = 0$

(iii) Least square method:
$$\int R(x) \frac{dR}{dx} dx = 0, i = 0, 1, 2, 3, \dots$$

(iv) Galerkin method: $\int R(x) w_i dx = 0$

Pr

Step 1: Assume a trial or guese Solution:

$$U(x) = C_0 + C_1 x + C_2 x^2$$

Where the constants C_0, C_1, C_2 area
yes to be determined.
Step 2: Satisfy the boundary Condition.
 $U(x) = C_0 + C_1 x + C_2 pe^2 \rightarrow \text{In order to}$
 $u(x) = C_0 + C_1 x + C_2 pe^2 \rightarrow \text{In order to}$
 $satisfy the first boundary condition
 $U(0) = C_0 + C_1(0) + C_2(0)^2 \rightarrow C_0 = 0$
To satisfy the Second boundary condition,
 $du = x = L \Rightarrow = C_1 + 2C_2 x$$

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Since the trial Solution contains only one free parameter Co, it is often referred Step 3: Find the domain residual. Substituting in the governing differential quali AE d20 + 90 =0 $u(x) = c_0 + q_x + c_2 x^2$ dv dæ = 9, + 2 2 2 = 7 de $R_1 \Rightarrow AE(2c_2) + q_0$ \$tep4: minimise the residual. Since those is one negideral to be minimised and one parameter to be determined. We can readily solve for the undetermined coefficien by setteing the regional to 2000; i.e. Rd 20, yielding. AE [202] + 2 =0 C2 = - 20/2AE The our trial solution is $u(x) = c_0 + c_1 pc + c_2 pc^2 \Rightarrow$ = @+[-2C2L] # [- 90/2AE] 2 - 20/2AE - 2 [- 2% AE] L 2 [9] To Care Prepared by Dr.M. SUBRAMANIAN/Professor/Mechanical/16ME401/ Finite Element Analysis





Use *Rayleigh Ritz method* determine the deflection at the center of the a simply supported beam of span length "L" subjected to uniformly distributed load through its length as shown in figure.

W/Unit length 000 1./2 L/2 According to Rayleigh-Ritz Method, When a displacement function make the total potential Enorgy minimum, that function may be considered as Approximate Consider a displacement function (i.e. deflection) y 2a, +a2 = + a3 x2 ----[1] The boundary anditions are y=0, atreo From equi (1) -> , BCO + x=0 y(0)=a, + 92(0)+93(0)2 a1 = 0 $B_{c}^{(2)} + \alpha = L_{1}^{2} = 0 + a_{2}L + a_{3}L^{2}$ $a_{2}L \oplus a_{3}L^{2} = 0 \quad a_{2}K = -a_{3}L^{2}$ = -931

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16ME401 Finite Element Analysis INTRODUCTION UNIT I Then the deflection y can be written as, $y = 0 + [-a_3 L]x + a_3 x^2$ $= -a_3 L x + a_3 x^2 = a_3 L x$ y=ag [x2-Lx] Diff. two times; we get = a3 [8x - L] [2] = 292 Strain norgy U= <u>EI</u> 2 i'da 203 2 = EI U 22E. -0 2 z 8 02 ET Work done, W= W.L.doc Wag[x2-La].da

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16ME401 Finite Element Analysis INTRODUCTION UNIT I I max = ? Maximum deflection at DC = 4/2 $\frac{-WL^2}{24EI} \left(\frac{L^2}{4} \right)$ = - WL2 24 EI -WL2 24EI W.L4 96 EI 96EI is the approximate Bolution.

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Att
in Find the deflection at the lawtre of a
simply supported beam of span length 1
subjected to a concentrated load P
at its mid point as shown in
figure. Use Rayleigh-Ritz method
A
The U-H work done by the external form
Strain energy for a beam,
$$U = EI \int (\frac{d^2y}{dx^2})^2 d\alpha$$

I -> area momens of Inertia.
 $J = a_1 + a_2 \alpha + a_3 \alpha^2 + a_4 \alpha^3 + \dots$ (1)
To simplify the problems, consider the first
three terms such as
 $J = a_1 + a_2 \alpha + a_3 \alpha^2 + \dots$ (2)
The boundary condition are
 $J = 0$ at $\alpha = 0$ of $\alpha = 1$
Hence equation $D \Rightarrow 0 = a_1$
and $0 = a_2 + a_3 \alpha^2 + a_4 \alpha^3 + \dots$ (3)

Then y can be expressed as

$$y_2 - a_3 loc + a_3 c^2 = a_3 (bc^2 - lc) - @$$

Differentiating two times we get;
 $\frac{dy}{dx} = a_3 (ax - l)$
 $\frac{d^2y}{dx} = a_{a_3}$
They strain energy is given by
 $V = \frac{Er}{2} \int (2a_3)^4 dx$
 $= \frac{Er}{2} \int (2a_3)^4 dx$
 $= 2 Er a_3^2 l$
Work done $W = P \cdot y_{max}$
 $= P a_3 (a^2 - lx) \quad (from eq_3)$
 $= P a_3 \left[\frac{12}{4} - \frac{1}{2}\right]$
The Total pontential energy T is given
 $T = V - W$
 $= 9EI a_3^2 l + pa_3 l^2$
For minimum potential energy condition
 $= 4EIa_3 l = -\frac{pl^2}{4} \xrightarrow{a_{a_1} - pl_1} \frac{a_{a_2} - pl_1}{bEI}$

Substituting the Value of as in equation (3), we
$$[y = a_3(x^2 - bx)]$$

 $= -\frac{p!}{16EI}(x^2 - b)$
Maximum deflection occurs at $3c = b/2$
Hence $4 = -\frac{p!}{16EI}\left[\frac{1^2}{4} - b \cdot \frac{1}{2}\right]$
 $= -\frac{p!}{16EI}\left[-\frac{1^2}{4}\right]$
 $= \frac{p!^3}{64EI}$ which is the approximate soluction
But the exact soluctions (i.e. the exact value of maximum deflection for a simply supported beam to point load at the extra of $y = \frac{p!^3}{2}$
To get more accurate soluction by Raybigh Should contain more quember of Ritz

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Use the finite element method to calculate the displacements and stress of the bar in figure.1, and compare with theory.



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Assemble the element equation [K] [1]= [P] Apply Boundary condition is at node, displacement u, :00 At point load of 50H is acting at node 4 as shown in fig. So add. 50H in FA Vector. $\begin{array}{c|cccccc}
\hline 10 & 10 & 0 & 0 \\
\hline 10 & 14 & -4 & 0 & u_2 \\
0 & -4 & 6 & -2 & u_3 \\
0 & -2 & 2 & u_4 \\
\hline 0 & 0 & -2 & 2 \\
\hline 0 & 0 & -2 & 0 \\
\hline 0 & 0 & -2 & 0 \\
\hline 0 & 0 & -2 & 0 \\
\hline 0 & 0 & -2 & 0 \\
\hline 0 & 0 & 0 \\$ 105-In the above equation, $U_1 = 0$, So, neglect first row and first column of [H] matrix Hence the equation reduces to $10^5 \begin{bmatrix} 14 & -4 & 0 \end{bmatrix} \begin{bmatrix} 0_2 \\ 0 \\ -4 & 6 & -2 \end{bmatrix} \begin{bmatrix} 0_2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 50 \end{bmatrix}$

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 $(140_2 - 40_3 + 0) = 0$ $(0 + (-2)_3) + 2(1) = 5$ = 50 Solve U2 = 50 × 10 mm Ug= 175×10 = 425 x10 mm. train $= \left[\frac{U_2 - U_1}{1} \right] = \left[\frac{50 \times 10^{-6} - 0}{10} \right] = 5 \times 10^{-6}$ $\vec{\xi} = \begin{bmatrix} \underline{U_3} - \underline{U_2} \\ \underline{L_2} \end{bmatrix} = \begin{bmatrix} 1.75 \times 10^{-5} \\ 10 \end{bmatrix} = 12^{6} 5 \times 10^{-6}$ $= \left[\frac{U_4 - U_3}{L_3} \right] = \left[\frac{425 - 175}{L_3} \times 10^6 \right] = 25 \times 10^{-6}$ $5^{0} = 5^{0} \times E = 200 \times 10^{3} \times 5 \times 10^{6} = 1 \text{ H/mm}^{2}$ = ExE= 200×102×12.5×10-6=2.5×1/mm2 EXE= 200×103× 25×106= 5 N/mm2 = 50/50 = 1 N/mm2 A2 = 50/20 = 2.5 N/MM2 A2 = 50/10 = 5 N/MM2 AN/Professor/Mechanical/ME402/ Finite Element Analysis 3



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For the bar assemblage shown in Figure 0.0, determine the nodal displacements, the forces in each element, and the reactions. Use the direct stiffness method for these problems.



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UNIT II ONE DIMENSIONAL PROBLEMS
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Element Equation \Rightarrow (K) [U] = {F_1}
Slotal Stift of faccus Force Vector
 $U = \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix}$
For meelation of Element Equalition.
 $IO^2 \begin{bmatrix} 800 - 800 & 0 \\ -800 & 940 & -140 \\ 0 & -140 & 140 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix}$
Apply Boundary Ondistion. $U_1 = 0, F_1 = 0$
 $F_2 = 0, F_3 = -20$
 $IO^2 \begin{bmatrix} 800 - 800 & 0 \\ -800 & 940 & -140 \\ 0 & -140 & 140 \end{bmatrix} \begin{bmatrix} U_2 \\ U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -20 & KN \end{bmatrix}$
 $IO^2 \begin{bmatrix} 940 & -140 \\ -140 & 140 \end{bmatrix} \begin{bmatrix} U_2 \\ U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -20 & KN \end{bmatrix}$$$

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The structure shown in figure 's subjected to an increase in temperature of 80°C. Determine the displacements, stresses and Suppost reactions. Assume the following tata. Aluminian steel K Bron20 P= BOKN Pi-P2=75KN 12 800 mm + 600 - 01 + 100 mm L-3 1 AT= 80 C $\begin{array}{cccc} & & & & \\ \hline Bronze & & & \\ A_1 = 2400 \text{ mm}^2 & A_2 = & & A_3 = \\ \hline 1200 \text{ mm}^2 & & & 600 \text{ mm}^2 \end{array}$ E1= 836pa E2= 700pa E3=2000pa d = 18.9×10-6/0cd2=23×10-6/0c d3= 11.7×10-6/0c Solution: FEA Model, 0 @ 3 Finite element equation for one dimensional two noded bar dements is given by $\begin{cases} F_1 \\ F_2 \end{cases} = \frac{A_1 E_1}{L_1} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ [K]{UJ={Fy Stiffness materix 4 Element () Elawarto Element @ $K^{(1)} = 2400 \times 23 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \qquad K^{(2)} = 1200 \times 70 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \qquad K^{(3)} = 600 \times 300 \times 10^{3} \begin{bmatrix} -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 600 \times 200 \times 10^{3} \times 10$ $= 249 \times 10^{3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$ = 10³ $\begin{bmatrix} 249 \\ -249 \\ -249 \end{bmatrix}$

Colobal matrix [K] = K1)+ K2+ K3) Displacement Vertor $U = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix}$ Load Vector {F}= EAXAT {-12 Element⁽¹⁾ $\begin{cases} F_1 \\ F_2 \end{cases} = 83 \times 10^3 \times 2400 \times 189 \times 10^5 \times 80 \times 5^{-1} \\ 1 \end{cases}$ = 10³ [-301.1904]1 301.1904]2 Element⁽²⁾ $\begin{cases} F_2 \\ F_3 \\ F_3 \\ = 10^3 \int -154 \cdot 56 \\ 154 \cdot 56 \\ 3 \end{cases}$ Element⁽³⁾ $\begin{bmatrix} F_3 \\ F_4 \end{bmatrix} = 200 \times 10^3 \times 600 \times 11.7 \times 10^{-6} \times 800 \begin{bmatrix} -12 \\ 1 \end{bmatrix}$ = $10^3 \int -112 \cdot 32 \int 112 \cdot 32 \int 112$

$$\begin{bmatrix} 166bal & for co \ lackors \\ SF_{2} = F_{1} \\ F_{3} \\ F_{4} \end{bmatrix} = 10^{3} \times \begin{bmatrix} -301 \cdot 1904 \\ 301 \cdot 1904 \\ -154 \cdot 56 \\ 154 \cdot 56 \\ 112 \cdot 32 \\ 1249 \\ -301 \cdot 1904 \\ 1249 \\ 389 \\ -140 \\ 480 \\ -32 \cdot 76 \\ 112 \cdot 32 \\$$

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-140 -140 $\begin{bmatrix} u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 86.6304 \\ -.32.76 \end{bmatrix}$ 389 112 - 14043 = 86.6304 -14042 +44042 = -32076 Solving U2 = 0.2212 mm U3= -0.00345mm Thermal stress O= Edu - EdAT For element(1) $\overline{G_{1}} = \overline{E_{1}(u_{2}-u_{1})} - \overline{E_{1}} \propto 4\pi$ = 83 x10³ [0.2 212-0] L_{1} 800 - 83×103×1899×10×80 = -102.5455 N/mm2 [Compressive Stress] For elewer b(2) (2) = 70×103 [-0.00345-0.2212] 600 02 = - 155.009 N/mm² [compressive stras] For Elaward (3) (3) = 200×103 [0+0.00345] - 200×103×11.7×10×80 P(3) = -185.475 N/mm² [compressive stress]

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16ME401 Finite Element Analysis UNIT II ONE DIMENSIONAL PROBLEMS



C a

For a tapered plate of uniform thickness t=10mm as shown in Figure **A**, find the displacements at the nodes by meshing into two element model. The bar has mass density $\rho = 7800 kg/m^3$, $E = 2 \times 10^5 MN/m^2$. In addition to self-weight, the plate is subjected to a point load P=10kN at its center. Also determine the reaction force at the support.



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·· ME402 Finite Element Analysis ONE DIMENSIONAL PROBLEMS UNIT II Apply the boundary condition is at model A point load of lox103N is acting at node 2 , so add 19000 H in F2 105-= 10006 886 In the above equation U1=0. So neglect first row and first column of [K] matrix. The reduced equation is. $10^{5} \begin{bmatrix} 15.998 - 6.666 \\ -6.666 & 6.666 \end{bmatrix} \begin{bmatrix} 42 \\ 43 \end{bmatrix}$ = 10006.886 $\left[15.9980_2 - 6.6660_3\right]10^5 = 100006.886$ -6.66602 +6.66603 105= 2.869 Solve above equation U2= 0.01073 mm U3= 0.01073 mm

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METAL FINITE Element Analysis
UNIT II ONE DIMENSIONAL PROBLEMS
Fraction force
$$\{R\} = [K] \{U\} = \{F\}$$

$$= 10^{5} \begin{pmatrix} 9.332 - 9.332 & 0 \\ -9.332 & 15.998 & -6.6666 \\ 0 & -6.6666 & 6.6666 \\ 0 & -6.6666 & 6.6666 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 01073 & 0.8667 \\ 0 & 0007 & 0.8667 \\ 0 & 0 &$$

01-Solve the following system of equation using gauss elimination method.

 $x_1 - x_2 + x_3 = 1$, $-3x_1 + 2x_2 - 3x_3 = -6$, $2x_1 - 5x_2 + 4x_3 = 5$

In form matrix

$$\begin{bmatrix} 1 & -1 & 1 & 1 \\ -3 & 2 & -3 \\ 2 & -5 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -6 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 \\ -3 & 2 & -3 - 6 \\ 2 & -5 & 4 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & -1 & 0 & -3 \\ 0 & -3 & 2 & 3 \end{bmatrix} \xrightarrow{\Rightarrow R_2 = [R_2 + 3R_1]}$$

$$\Rightarrow R_3 = [R_3 - 2R_1]$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & -1 & 0 & -3 \\ 0 & 0 & 2 & 12 \end{bmatrix} \xrightarrow{\Rightarrow R_3 = [R_3 - 3R_2]}$$

$$\begin{bmatrix} 2x_3 = 12 \\ -x_2 = -3 \\ x_1 - x_2 + x_3 = 1 \end{bmatrix}$$
Result:

$$x_3 = 6, x_2 = 3, x_1 = -2$$

It is a method which is easily adapted to the computer and is based on triangularization of the coefficient matrix and evaluation of the unknowns by back- substitution starting from the last equation

02-Describe the step by step procedure of solving FEA.

GeneralStepstobefollowedwhilesolvingastructuralproblembyusingFEM: 1.Discretize and select the element type

2. *Choose a displacement function*

3. Define the strain/displacement and stress/ strain relationships

4.Derive the element stiffness matrix and equations by using direct or variational or Galerkin's approach

5.Assemble the element equations to obtain the global equations and introduce boundary conditions

6.Solve for the unknown degrees of freedom or generalized displacements 7.Solve for the element strains and stresses

8. Interpret the results

Step 1. Discretize and Select element type

- Dividing the body in to an equivalent system of finite elements with associated nodes
- Choose the most appropriate element type
- Decide what number, size and the arrangement of the elements
- The elements must be made small enough to give us able results and yet large enough to reduce computation effort

Step 2. Selection of the displacement function

- Choose displacement function within the element using nodal values of the element
- Linear, quadratic, cubic polynomials can be used
- The same displacement function can be used repeatedly for each element

Step 3. Define the strain/displacement and stress/strain relationships

- Strain/displacement and stress/strain relationships are necessary for deriving the equations for each element
- In case of 1-D, deformation, say in x-direction is given by, $\varepsilon = \frac{du}{dx}$
- Stress / strain law is , Hooke's law given by, $\sigma_x = E\varepsilon_x$

Step 4. Derive element stiffness matrix and equations

Following methods can be used

- Direct equilibrium method
- Work or energy methods
- Method of weighted residuals such as Galerkin's method

Any one of the above methods will produce the equations to describe the behavior of an element

The equations are written conveniently in matrix form as, $\frac{AE}{L}\begin{bmatrix} 1 & -1\\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1\\ u_2 \end{bmatrix} = \begin{bmatrix} F_1\\ F_2 \end{bmatrix}$

Step 5. Assemble the element equations to obtain the global or total equations and introduce boundary conditions

- The element equations generated in the step 4 can be added together using the method of superposition
- The final assembled or global equations will be of the matrix form $[K]{u} = {F}$
- Now introduce the boundary conditions or supports or constraints

• Invoking boundary conditions results in a modification of the global equation Step 6. Solve for the unknown degrees of After introducing boundary conditions, we get a set of simultaneous algebraic equations and these equations can be written in the expanded form as

 $\begin{bmatrix} F_1 \\ F_2 \\ F_3 \\ F_n \end{bmatrix} = \begin{bmatrix} K_{11} & K_{12} & K_{13} - \dots - K_{1n} \\ K_{21} & K_{22} & K_{23} - \dots - K_{2n} \\ K_{31} & K_{32} & K_{33} - \dots - K_{3n} \\ K_{n1} - \dots - K_{nn} \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \\ d_3 \\ d_n \end{bmatrix}$

The above equations can be solved for unknown degrees of freedom by using an elimination method such as Gauss 's method or an iteration method such as the Gauss-Seidel method

Step7. Solve for the element strain and stress

Secondary quantities such as strain and stress, moment or shear force can now be obtained

Step 8. Interpret the results

- The final goal is to interpret and analyze the results for use in design / analysis process.
- Determine the locations where large deformations and large stresses occur in the structure
- Now make design and analysis decisions



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04-List the advantages, disadvantages and applications of FEM.

Applications of FEM:

• Equilibrium problems or time independent problems.

e. g. i) To find displacement distribution and stress distribution for a mechanical or thermal loading in solid mechanics. *ii)* To find pressure, velocity, temperature, and density distributions of equilibrium problems in fluid mechanics.

• Eigenvalue problems of solid and fluid mechanics.

e. g. i) Determination of natural frequencies and modes of vibration of solids and fluids. ii) Stability of structures and the stability of laminar flows.

Time-dependent or propagation problems of continuum mechanics. e.g. This category is composed of the problems that results when the time dimension is added to the problems of the first two categories.

Engineering applications of the FEM:

- Civil Engineering structures
- Air-craft structures
- Heat transfer
- Geomechanics
- Hydraulic and water resource engineering and hydrodynamics
- Nuclear engineering
- Biomedical Engineering

• Mechanical Design- stress concentration problems, stress analysis of pistons, composite materials, linkages, gears, stability of linkages, gears and machine tools. Cracks and fracture problems under dynamic loads etc

Advantages of Finite Element Method

- Model irregular shaped bodies quite easily
- Can handle general loading/ boundary conditions
- Model bodies composed of composite and multiphase materials because the element equations are evaluated individually
- Model is easily refined for improved accuracy by varying element size and type
- Time dependent and dynamic effects can be included
- Can handle a variety nonlinear effects including material behaviour, large deformation, boundary conditions etc.

Disadvantages:

- Needs computer programmes and computer facilities
- The computations involved are too numerous for hand calculations even when solving very small problems
- Computers with large memories are needed to solve large complicated problems

Computer Programmes for the FEM

- 1. Algor
- 2. ANSYS Engineering Analysis System
- 3. COSMOS/M
- 4. STARDYNE
- 5. IMAGES-3D
- 6. MSC/NASTRAN- NASA Structural Analysis
- 7. SAP90- Structural Analysis Programme
- 8. *GT-STRUDL Structural Design Language*
- 9. SAFE- Structural Analysis by Finite Elements
- 10. NISA- Non linear Incremental Structural Analysis etc.

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