

SNS COLLEGE OF TECHNOLOGY



(An Autonomous Institution) B.E/B.Tech- Internal Assessment -II Academic Year 2023-2024 (Odd Semester) Fifth Semester Electronics & Communication Engineering 19ECB301 Analog and Digital Communication ANSWER KEY IAE-2

	Part A								
	Inspect the use of RF amplifier in FM	I receiver.							
1.	RF amplifiers are used to amplify the low input radio frequency signals. We need to amplify because the RF signals are usually at low voltages. Because of low voltage they are prone to external disturbances. Boosting the signals usually means increasing the voltage and decreasing the current and vice versa.								
	Define Automatic Gain Control.								
2.	Automatic gain control (AGC) is a closed-loop feedback circuit present in radio receivers which helps to maintain a constant output, irrespective of the input variations. In communication systems, the inclusion of AGC regulates the system output to a constant value, even if the input voltage decreases or increases.								
3.	Summarize aliasing.								
	In signal processing and related disciplines, aliasing is the overlapping of frequency components resulting from a sample rate below the Nyquist rate.								
	Differentiate sampling and quantization.								
	Sampling	Quantization							
	Digitization of co-ordinate values.	Digitization of amplitude values.							
	x-axis(time) – discretized.	x-axis(time) – continuous.							
4.	y-axis(amplitude) – continuous.	y-axis(amplitude) – discretized.							
	Sampling is done prior to the quantization process.	Quantizatin is done after the sampling process.							
	It determines the spatial resolution of the digitized images.	It determines the number of grey levels in the digitized images.							
	It reduces c.c. to a series of tent poles over a time.	It reduces c.c. to a continuous series of stair steps.							





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				(or)					
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	Explain the oper	ration	of low	pass Sa	mpling	g theore	m with	n its i	ndividual	
	blocks.			•	I C	-				
(b)										
	A continuous sig	gnal o	r an ana	log sign	nal can	be repr	esente	d in t	he digital	
	version in the f	orm o	of sampl	es. Here	e. thes	e sampl	les are	also	called as	
	discrete points I	n sam	nling th	eorem f	he inn	ut signa	l is in a	an an	alog form	
	of signal and the	secor	nd input	signal is	a sam	nling si	onal u	which	is a nulse	
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	sampling signal	Ireque	ency sho		nore u	nan twi		ie inp	out analog	
	signal frequenc	y. If	this co	ndition	satisfi	ies, ana	alog si	gnal	perfectly	
	represented in di	screte	torm el	se analo	g signa	al may b	e losin	g its a	amplitude	
	values for certain	n time	interva	ls. How	many	times th	e samp	oling f	frequency	
	is more than the input analog signal frequency, in the same way, the									
	sampled signal i	s goin	ig to be	a perfec	t discr	ete forn	n of sig	gnal. A	And these	

types of discrete signals are well performed in the reconstruction process for recovering the original signal.

Sampling Theorem. If the highest frequency contained in an analog signal $x_a(t)$ is $F_{\text{max}} = B$ and the signal is sampled at a rate $F_s > 2F_{\text{max}} \equiv 2B$, then $x_a(t)$ can be exactly recovered from its sample values using the interpolation function

$$g(t) = \frac{\sin 2\pi Bt}{2\pi Bt}$$
 (1.4.22)

Thus $x_a(t)$ may be expressed as

$$x_a(t) = \sum_{n=-\infty}^{\infty} x_a\left(\frac{n}{F_s}\right) g\left(t - \frac{n}{F_s}\right)$$
(1.4.23)

where $x_a(n/F_s) = x_a(nT) \equiv x(n)$ are the samples of $x_a(t)$.

When the sampling of $x_a(t)$ is performed at the minimum sampling rate $F_s = 2B$, the reconstruction formula in (1.4.23) becomes

$$x_a(t) = \sum_{n=-\infty}^{\infty} x_a \left(\frac{n}{2B}\right) \frac{\sin 2\pi B(t-n/2B)}{2\pi B(t-n/2B)}$$
(1.4.24)

The sampling rate $F_N = 2B = 2F_{\text{max}}$ is called the Nyquist rate. Figure 1.19 illustrates the ideal D/A conversion process using the interpolation function in (1.4.22).

As can be observed from either (1.4.23) or (1.4.24), the reconstruction of $x_a(t)$ from the sequence x(n) is a complicated process, involving a weighted sum of the interpolation function g(t) and its time-shifted versions g(t-nT) for $-\infty < n < \infty$, where the weighting factors are the samples x(n). Because of the complexity and the infinite number of samples required in (1.4.23) or (1.4.24), these reconstruction



Figure 1.19 Ideal D/A conversion (interpolation).

formulas are primarily of theoretical interest. Practical interpolation methods are given in Chapter 9.

8. (a) Derive the expression of SNR input, post detection, pre detection of FM receiver.

Signal-to-Noise Ratio (SNR) is the ratio of the signal power to noise power. The higher the value of SNR, the greater will be the quality of the received output.

Signal-to-Noise Ratio at different points can be calculated using the following formulas.

AGIC R.F. Ampifier Descriminator Limitel. mites Local A.F ascellator De voltage Powel Omphasis Amplifiel Amplifig Loudereaker Relationship between i/p, predetection & Postdetection Signal to noise Ractio: when the detection takes place in FM Receiver, the Signal to noise ractio is improved. -> This employed Sive is also called FM Improvement. - The AM improvement, SNRs at the 1/p of the receiver and at the opp of receives are related as $\begin{pmatrix} S_{N} \\ Inprovement \end{pmatrix} = \begin{pmatrix} S \\ N \\ Postdotection \end{pmatrix} - \begin{pmatrix} S \\ N \\ Postdotection \end{pmatrix}$ 70 All the values must be in dra The overall receiver noise figure (F), 1/p SNR (S) 1/p and predetection sive (S) pudetection are related a $\left(\frac{S}{N}\right)_{\text{Taput}} = \left(\frac{S}{N}\right)_{\text{Rudetection}} + F - \frac{S}{\sqrt{2}}$ The minimum receiver i/p s/g to noise ratio is given as (S) Me, min = Vi(min) - n°(max) Here (S)/p.min & minimum vereiver P/p SAVR, Vi (min) is minimum receiver signal level of Micman) is maximum noise level.

	(or)	
(b)	Examine the drawbacks of Inter Symbol Interference and explain the use of Eye pattern with its working.	
	The eye pattern, also referred to as the eye diagram, is produced by the synchronized superposition of (as many as possible) successive symbol intervals of the distorted waveform appearing at the output of the receive filter prior to thresholding. As an illustrative example, consider the distorted, but noise-free, waveform shown. Part b of the figure displays the corresponding synchronized superposition of the waveform's eight binary symbol intervals. The resulting display is called an "eye pattern" because of its resemblance to a human eye. By the same token, the interior of the eye pattern is called the eye opening	
	Binary 0 1 1 0 1 1 0 0 1 0 Data \rightarrow T_b \leftarrow T_b \leftarrow T_b \leftarrow	14
	(a) (b) Figure 8.12 (a) Binary data sequence and its waveform. (b) Corresponding eye pattern.	
	From this diagram, we may infer three timing features pertaining to a binary data transmission system, exemplified by a PAM system:	
	1. Optimum sampling time. The width of the eye opening defines the time interval over which the distorted binary waveform appearing at the output of the receive filter in the PAM system can be uniformly sampled without decision errors. Clearly, the optimum sampling time is the time at which the eye opening is at its widest.	
	2. Zero-crossing jitter . In practice, the timing signal (for synchronizing the receiver to the transmitter) is extracted from the zero-crossings of the waveform that appears at the receive-filter output. In such a form of synchronization, there will always be irregularities in the zero-crossings, which, in turn, give rise to jitter and, therefore, nonoptimum sampling times.	
	3. Timing sensitivity. Another timing-related feature is the sensitivity of the PAM system to timing errors. This sensitivity is determined by the rate at which the eye pattern is closed as the sampling time is varied.	

