

Static Equilibrium.

- * Object is in rest and in equilibrium
- * Object has no velocity.

Conditions for static Equilibrium.

1. Algebraic sum of vertical forces = 0
$$\sum F_v = 0$$

2. Algebraic sum of horizontal forces = 0
$$\sum F_H = 0$$

3. Algebraic sum of Moments = 0
$$\sum M = 0$$

Dynamic Equilibrium.

- * Sum of vectorial forces is zero
- * Object has a velocity.

Equations of motion of linear system

$$v = u + at$$

$$v^2 = u^2 + 2as$$

$$s = ut + \frac{1}{2}at^2$$

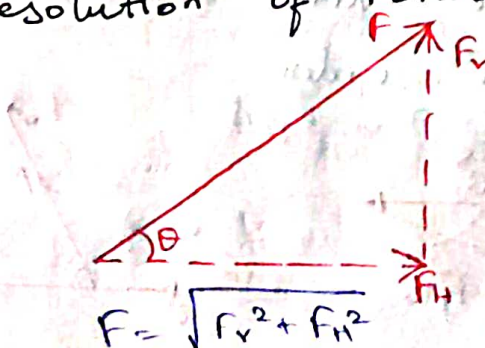
s = linear displacement, m

u = initial velocity, m/s

v = final velocity, m/s

a = linear acceleration, m/s²

Resolution of Forces:



Horizontal Component

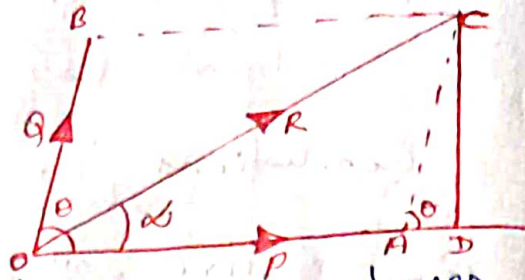
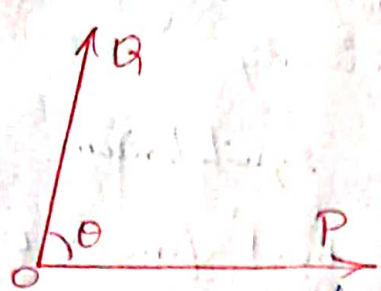
$$F_H = F \cos \theta$$

Vertical Component

$$F_V = F \sin \theta$$

$$F = \sqrt{F_V^2 + F_H^2}$$

PARALLELOGRAM LAW OF FORCES:



It states that "if two forces act simultaneously at a point be represented magnitude & direction, by the two adjacent sides of a parallelogram, then the resultant of these two forces is represented in magnitude and direction by the diagonal of that parallelogram originating from the point."

$$\vec{R} = \vec{P} + \vec{Q}$$

Mathematically: $R = \sqrt{P^2 + Q^2 + (2PQ \cos \theta)}$

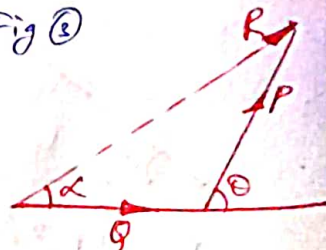
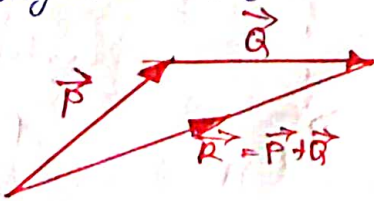
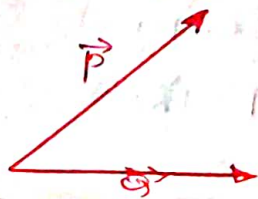
Inclination of the resultant force with force P

$$\alpha = \tan^{-1} \left[\frac{Q \sin \theta}{P + Q \cos \theta} \right]$$

TRIANGULAR LAW OF FORCES:

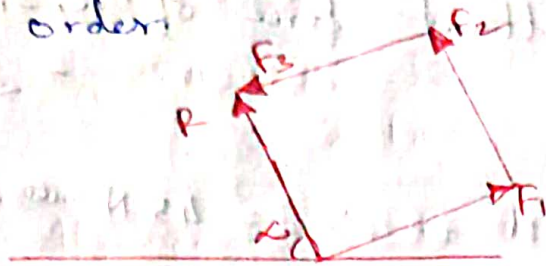
* It states that if two forces acting at a point are represented by the two sides of a triangle taken in order, then their resultant force is represented by the third side of the triangle taken in opposite order.

* Fig ① rearranged as Fig ② or Fig ③



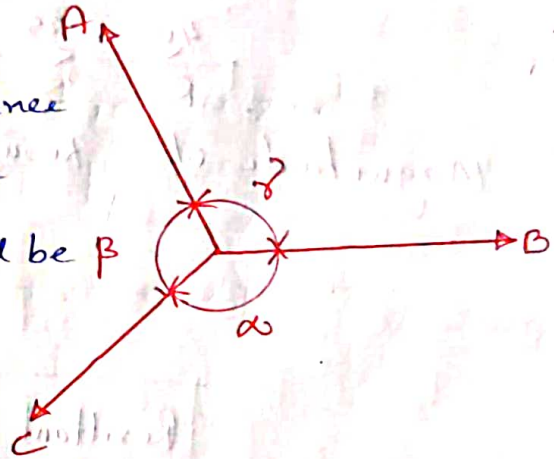
POLYGON LAW OF FORCES:

It states that if a number of coplanar concurrent forces are represented in magnitude & direction by the sides of a polygon taken in an order, then the resultant force is represented by the closing side of the polygon taken in opposite order.



LAMIS THEOREM:

It states that if three forces acting on a point at equilibrium, each force will be proportional to the sine of the angle between the other two forces.



$$\frac{A}{\sin \alpha} = \frac{B}{\sin \beta} = \frac{C}{\sin \gamma}$$

Moment: Measure of rotation about a point.
 $M = F \times r$

A couple consists of 2 equal, non-collinear, parallel forces of opposite signs.

