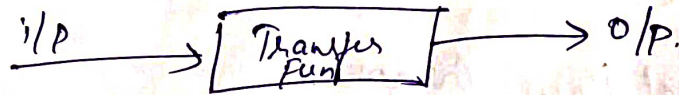


## Transfer Function of Control System.

Transfer function represents the relation b/w the output signal of a control system and the i/p signal, for all the possible i/p variable.



i/p is represented by  $R(s)$ .

o/p is represented by  $C(s)$ .

$$G(s) = \frac{C(s)}{R(s)} = R(s) \cdot G(s) = C(s)$$

Transfer function of s/m multiplied by the i/p function gives the o/p func of the s/m.

Procedure for determining the transfer function of the control system

1. we form the equations for the s/m.
2. Now we take Laplace transform of the s/m equations, assuming initial conditions as zero.
3. Specify s/m o/p and i/p.
4. Lastly take the ratio of Laplace transform of the output of the i/p and the Laplace transform which is required transfer function.



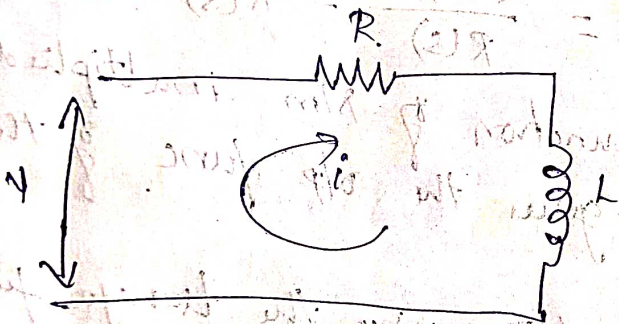
### Methods :-

#### \* Block diagram method

Block diagrams reduction techniques are applied to obtain the desired transfer function

#### \* Signal flow graph

- The modified form of a block diagram
- Further shorter method of control system



Voltage = i/p. Current = o/p.

$$V = Ri + L \frac{di}{dt}$$

apply Laplace transform, we get

$$V(s) = R I(s) + L [s I(s) - i(0^+)]$$

initially, inductor acts as open, hence  $i(0^+) = 0$

$$V(s) \Rightarrow \mathcal{I}(s) (R + Ls)$$



$$G(s) = \frac{I(s)}{V(s)} = \frac{1}{R+Ls}$$

$$= \frac{1/L}{s+R/L}$$

poles

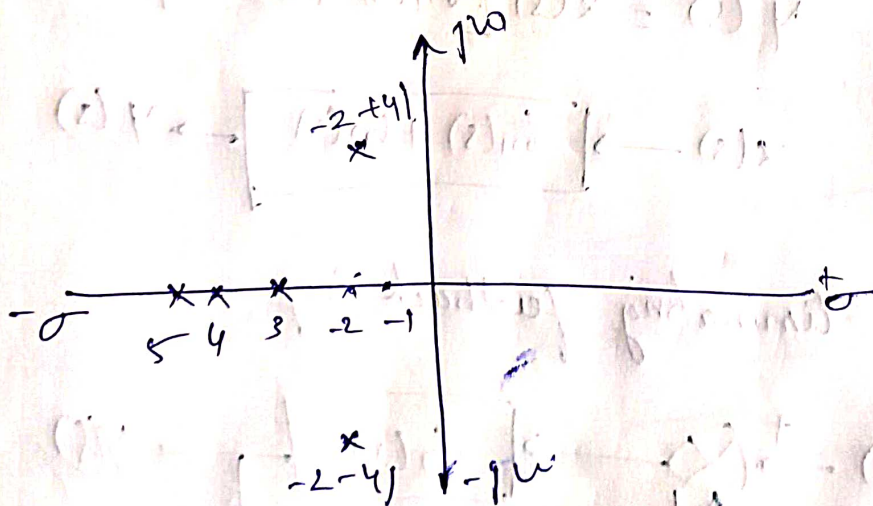
$$G(s) = \frac{(s+1)(s+2)}{(s+3)(s+4)(s+5)(s+2-4j)(s+2+4j)}$$

$$Zeros = \frac{(s+1)(s+2)}{0}$$

$$Zeros = -1, -2$$

$$poles = \frac{0}{(s+3)(s+4)(s+5)(s+2-4j)(s+2+4j)}$$

$$poles = -3, -4, -5, -2+4j, -2-4j$$



poles → x

Zeros → •