



# SNS COLLEGE OF TECHNOLOGY

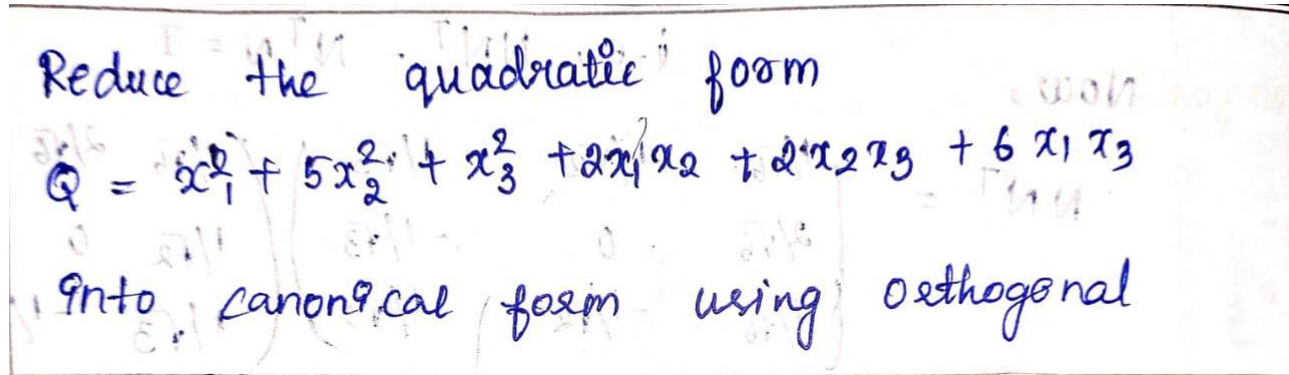
(An Autonomous Institution)

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UNIT 2- Orthogonal Transformation of a Real Symmetric Matrix

Reduction of QF to CF



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$\lambda^2 - \lambda - 6 = 0$   
 $(\lambda - 3)(\lambda + 2) = 0$   
 $\lambda = -2, 3$   
Eigen values are  $6, -2, 3$

Eigen vectors  
 $(A - \lambda I)x = 0$

$$\begin{pmatrix} 1-\lambda & 1 & 3 \\ 1 & 5-\lambda & 1 \\ 3 & 1 & 1-\lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Case:-1 When  $\lambda = -2$

$$\begin{pmatrix} 3 & 1 & 3 \\ 1 & 7 & 1 \\ 3 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
$$\begin{matrix} x_1 & x_2 & x_3 \\ 1 & 3 & 3 \\ 7 & 1 & 1 \end{matrix}$$
$$\frac{x_1}{(1-21)} = \frac{x_2}{(3-3)} = \frac{x_3}{(21-1)}$$
$$\frac{x_1}{-20} = \frac{x_2}{0} = \frac{x_3}{20}$$
$$\frac{x_1}{-1} = \frac{x_2}{0} = \frac{x_3}{1}$$
$$\therefore x_1 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

Case:-2 when  $\lambda = 3$



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## UNIT 2- Orthogonal Transformation of a Real Symmetric Matrix

## Reduction of QF to CF

$$\begin{pmatrix} -2 & 1 & 3 \\ 1 & 2 & 1 \\ 3 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 1 \\ -2 & 1 & 3 \\ 3 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\frac{x_1}{(1-6)} = \frac{x_2}{(3+2)} = \frac{x_3}{(-4-1)}$$

$$\frac{x_1}{-5} = \frac{x_2}{5} = \frac{x_3}{-5}$$

$$\frac{x_1}{-1} = \frac{x_2}{1} = \frac{x_3}{-1}$$

case :- 3

When  $\lambda = 6$

$$\begin{pmatrix} -5 & 1 & 3 \\ 1 & -1 & 1 \\ 3 & 1 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 & 1 \\ -5 & 1 & 3 \\ 3 & 1 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\frac{x_1}{(1+3)} = \frac{x_2}{(3+5)} = \frac{x_3}{(5+1)}$$

$$\frac{x_1}{4} = \frac{x_2}{8} = \frac{x_3}{4}$$

$$\frac{x_1}{1} = \frac{x_2}{2} = \frac{x_3}{1}$$

$$\therefore x_3 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$



Step:-3

$$x_1^T \cdot x_2 = (-1 \ 0 \ 1) \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} = -1 + 1 = 0$$

$$x_2^T \cdot x_3 = (-1 \ 1 \ -1) \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = -1 + 2 - 1 = 0$$

$$x_3^T \cdot x_1 = (1 \ 2 \ 1) \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = -1 + 0 + 1 = 0$$

∴ Eigen vectors are pairwise orthogonal.

Step:-4

Normalized eigen vectors

$$x_1 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad k(x) = \sqrt{(-1)^2 + (0)^2 + (1)^2} = \sqrt{2}$$

$$x_1 = \begin{pmatrix} -1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{pmatrix}$$

$$x_2 = \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix} \quad k(x) = \sqrt{(-1)^2 + (1)^2 + (-1)^2} = \sqrt{3}$$

$$x_2 = \begin{pmatrix} -1/\sqrt{3} \\ 1/\sqrt{3} \\ -1/\sqrt{3} \end{pmatrix}$$

$$x_3 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \quad k(x) = \sqrt{(1)^2 + (2)^2 + (1)^2} = \sqrt{6}$$

$$x_3 = \begin{pmatrix} 1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{pmatrix}$$

Step 5:-

Normalized modal matrix



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$$N = \begin{pmatrix} -1/\sqrt{2} & -1/\sqrt{3} & 1/\sqrt{6} \\ 0 & 1/\sqrt{3} & 2/\sqrt{6} \\ 1/\sqrt{2} & -1/\sqrt{3} & 1/\sqrt{6} \end{pmatrix}$$

Step :- 6

N should be orthogonal

i.e.,  $N^{-1}N^T = N^T N = I$

Now,

$$N N^T = \begin{pmatrix} -1/\sqrt{2} & -1/\sqrt{3} & 1/\sqrt{6} \\ 0 & 1/\sqrt{3} & 2/\sqrt{6} \\ 1/\sqrt{2} & -1/\sqrt{3} & 1/\sqrt{6} \end{pmatrix} \begin{pmatrix} -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ -1/\sqrt{3} & 1/\sqrt{3} & -1/\sqrt{3} \\ 1/\sqrt{6} & 2/\sqrt{6} & 1/\sqrt{6} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I$$

N is orthogonal

Step :- 7

$$D = N^T A N$$

$$= \begin{pmatrix} -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ -1/\sqrt{3} & 1/\sqrt{3} & -1/\sqrt{3} \\ 1/\sqrt{6} & 2/\sqrt{6} & 1/\sqrt{6} \end{pmatrix} \begin{pmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1/\sqrt{2} & -1/\sqrt{3} & 1/\sqrt{6} \\ 1/\sqrt{3} & 1/\sqrt{3} & 2/\sqrt{6} \\ 1/\sqrt{2} & -1/\sqrt{3} & 1/\sqrt{6} \end{pmatrix}$$

$$D = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

Step :- 8

canonical form (CF) =  $Y^T D Y$

$$CF = (y_1 \ y_2 \ y_3) \begin{pmatrix} -2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 6 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$= -2y_1^2 + 3y_2^2 + 6y_3^2$$

⇒ Rank = 3

⇒ signature = 1

⇒ Index = 2

⇒ Nature = Indefinite