

Differential equations:

Differential equations are used to represent continuous time LTI systems. The differential equations relates the i/p & o/p of the systems.

Solving differential equations using Fourier method.

$$y(t) = x(t) * h(t)$$

$$y(f) = x(f) \cdot h(f)$$

$$\therefore H(f) = \frac{y(f)}{x(f)} \quad \text{or} \quad H(\omega) = \frac{y(\omega)}{x(\omega)}$$

$H(f)$ (or) $H(\omega) \rightarrow$ system transfer function
(or) Frequency response

1. The system produces the o/p $y(t) = e^{-t} \cdot u(t)$ for an input $x(t) = e^{-2t} \cdot u(t)$. Determine the impulse response and frequency response of the system.

$$\text{i/p } x(t) = e^{-2t} u(t)$$

$$\text{o/p } y(t) = e^{-t} u(t)$$

$$X(f) = \frac{1}{2 + j2\pi f}$$

$$Y(f) = \frac{1}{1 + j2\pi f}$$

$$\therefore H(f) = \frac{Y(f)}{X(f)} = \frac{2 + j2\pi f}{1 + j2\pi f}$$

$$h(t) = F^{-1}[H(f)]$$

$$= F^{-1}\left[\frac{2 + j2\pi f}{1 + j2\pi f}\right]$$

$$= F^{-1}\left[\frac{1 + 1 + j2\pi f}{1 + j2\pi f}\right]$$

$$= F^{-1}[1] + F^{-1}\left[\frac{1}{1 + j2\pi f}\right]$$

$$h(t) = \delta(t) + e^{-t} u(t)$$

(2) The differential equation of the system is given as $\frac{d^2}{dt^2} y(t) + 5 \frac{d}{dt} y(t) + 6y(t) = -\frac{d}{dt} x(t)$
Determine freq. response and Impulse response by taking Fourier transform

$$(j\omega)^2 y(\omega) + 5j\omega y(\omega) + 6y(\omega) = (-j\omega)x(\omega)$$

$$y(\omega) [(j\omega)^2 + 5j\omega + 6] = -j\omega x(\omega)$$

$$H(\omega) = \frac{y(\omega)}{x(\omega)} = \frac{-j\omega}{(j\omega)^2 + 5j\omega + 6}$$

$$H(\omega) = \frac{-j\omega}{(j\omega+2)(j\omega+3)}$$

$$= \frac{2}{j\omega+2} - \frac{3}{j\omega+3}$$

$$H(\omega) = 2 \cdot \frac{1}{j\omega+2} - 3 \cdot \frac{1}{j\omega+3}$$

$$-j\omega = A(j\omega+3) + B(j\omega+2)$$

put $j\omega = -2$

$$2 = A$$

put $j\omega = -3$

$$+3 = -B$$

$$B = -3$$

Solving differential equation using Laplace transform shifting property of unilateral Laplace transform

$$L \left[\frac{d}{dt} x(t) \right] = s \cdot x(s) - x(0^-)$$

$$L \left[\frac{d^2}{dt^2} x(t) \right] = s^2 \cdot x(s) - s x(0^-) - x'(0^-)$$

$$L \left[\frac{d^3}{dt^3} x(t) \right] = s^3 \cdot x(s) - s^2 x(0^-) - s x'(0^-) - x''(0^-)$$

1. solve using differential equation

$\frac{d}{dt} y(t) + 5y(t) = x(t)$ with initial condition $y(0^-) = -2$ and i/p $x(t) = 3e^{-2t} u(t)$.

$$\frac{d}{dt} y(t) + 5y(t) = x(t)$$

$$s \cdot y(s) - y(0^-) + 5y(s) = x(s)$$

$$s \cdot y(s) + 2 + 5y(s) = \frac{3}{s+2}$$

$$y(s) [s+5] + 2 = \frac{3}{s+2}$$

$$y(s) [s+5] = \frac{3}{s+2} - 2$$

$$y(s) = \frac{3}{(s+2)(s+5)} - \frac{2}{s+5}$$

$$\frac{3}{(s+2)(s+5)} = \frac{A}{s+2} + \frac{B}{s+5}$$

$$3 = A(s+5) + B(s+2)$$

put $s = -5$

$$3 = -3B \Rightarrow \boxed{B = -1}$$

put $s = -2$

$$3 = 3A \Rightarrow \boxed{A = 1}$$

$$Y(s) = \left[\frac{1}{s+2} - \frac{1}{s+5} \right] - \frac{2}{s+5}$$

$$Y(s) = \frac{1}{s+2} - \frac{3}{s+5}$$

$$y(t) = e^{-2t} u(t) - 3 e^{-5t} u(t)$$

System Transfer function

$$y(t) = x(t) * h(t)$$

$$Y(s) = X(s) * H(s)$$

$$H(s) = \frac{Y(s)}{X(s)}$$

→ system transfer function.

Frequency Response

substitute $s = j\omega$

in $H(s)$, we

get frequency response $H(j\omega)$

1. The input, output relation of a system at initial state is given by

$$\frac{d^2}{dt^2} y(t) + 4 \frac{d}{dt} y(t) + 3 y(t) = \frac{d}{dt} x(t) + 2 x(t)$$

Find system transfer function, frequency response and impulse response.

$$s^2 y(s) + 4s y(s) + 3 y(s) = s x(s) + 2 x(s)$$

$$y(s) [s^2 + 4s + 3] = x(s) [s + 2]$$

$$H(s) = \frac{y(s)}{x(s)} = \frac{s+2}{s^2+4s+3}$$

Freq. response

$$H(j\omega) = \frac{y(j\omega)}{x(j\omega)} = \frac{j\omega + 2}{(j\omega)^2 + 4j\omega + 3}$$