



SNS COLLEGE OF TECHNOLOGY

Coimbatore-35

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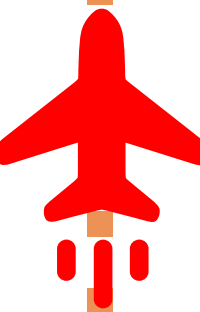
DEPARTMENT OF AEROSPACE ENGINEERING

19ASB201 Aero Mechanics of Solids

II YEAR III SEM

UNIT 1 – STRESS STRAIN DEFORMATION OF SOLIDS

TOPIC 1 – Rigid and Deformable bodies - Strength, Stiffness and Stability

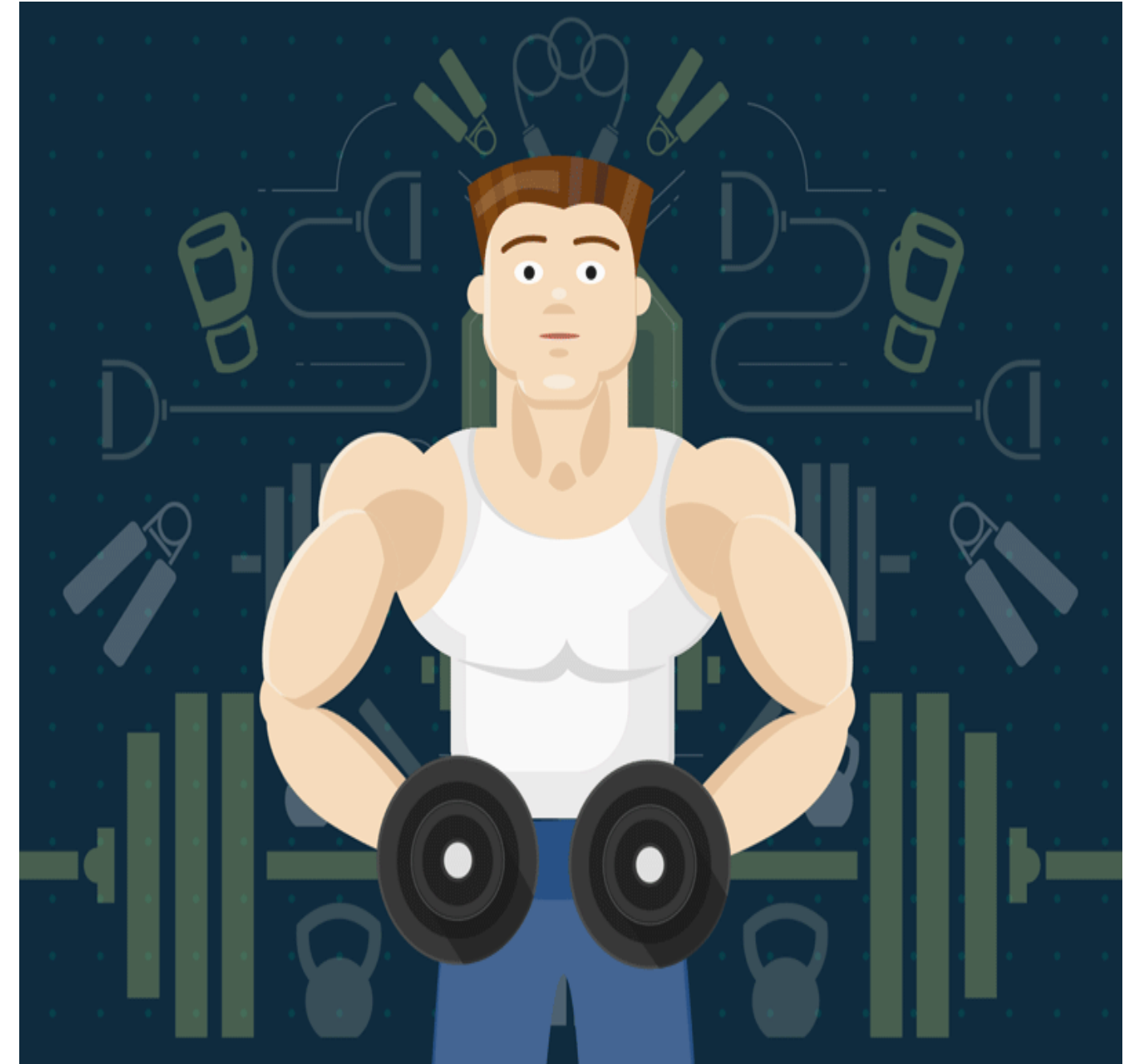




STRENGTH OF MATERIALS



- **Aero Mechanics of Solids** also called **Mechanics of materials**, is a subject which deals with the behavior of solid objects subject to stresses and strains.
- The study of strength of materials often refers to various methods of calculating the stresses and strains in structural members, such as beams, columns, and shafts.

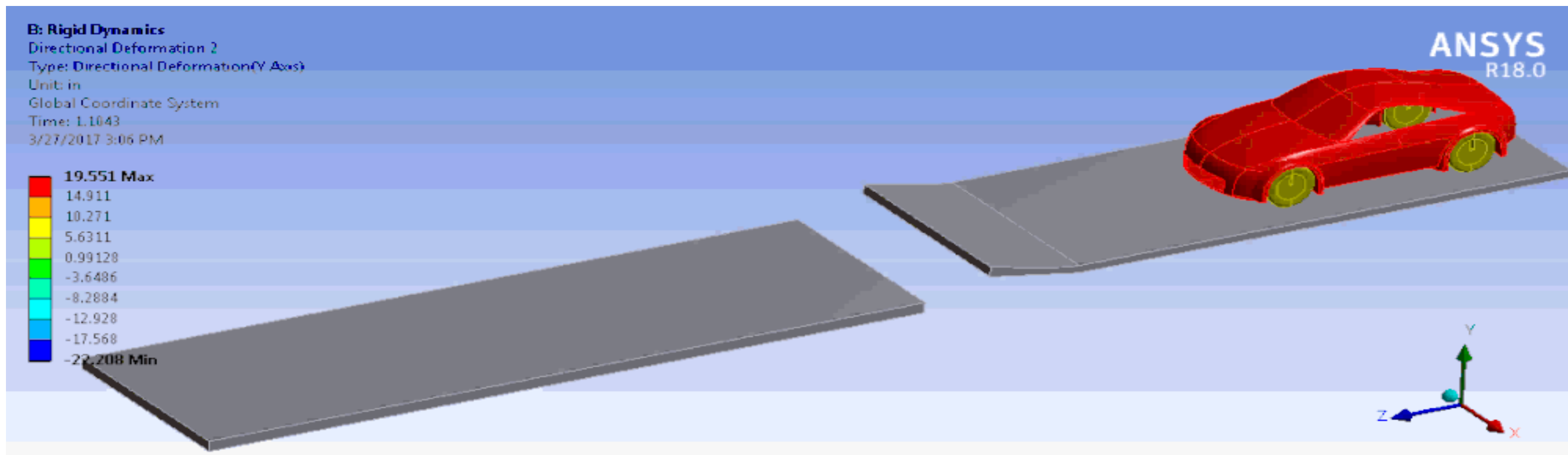




RIGID BODY



- A rigid body is defined as a body on which the distance between two points never changes whatever be the force applied on it.
- Practically, there is no rigid body.



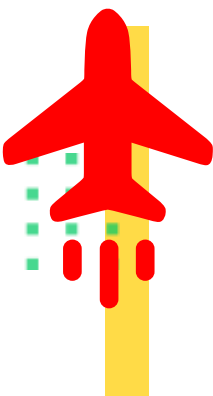


DEFORMABLE BODY



A deformable body is defined as a body on which the distance between two points changes under action of some forces when applied on it.

The study of the property of this body is called **Elasticity**

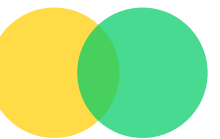
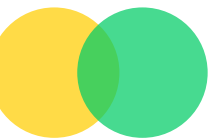
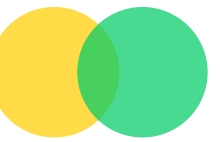




ELASTICITY

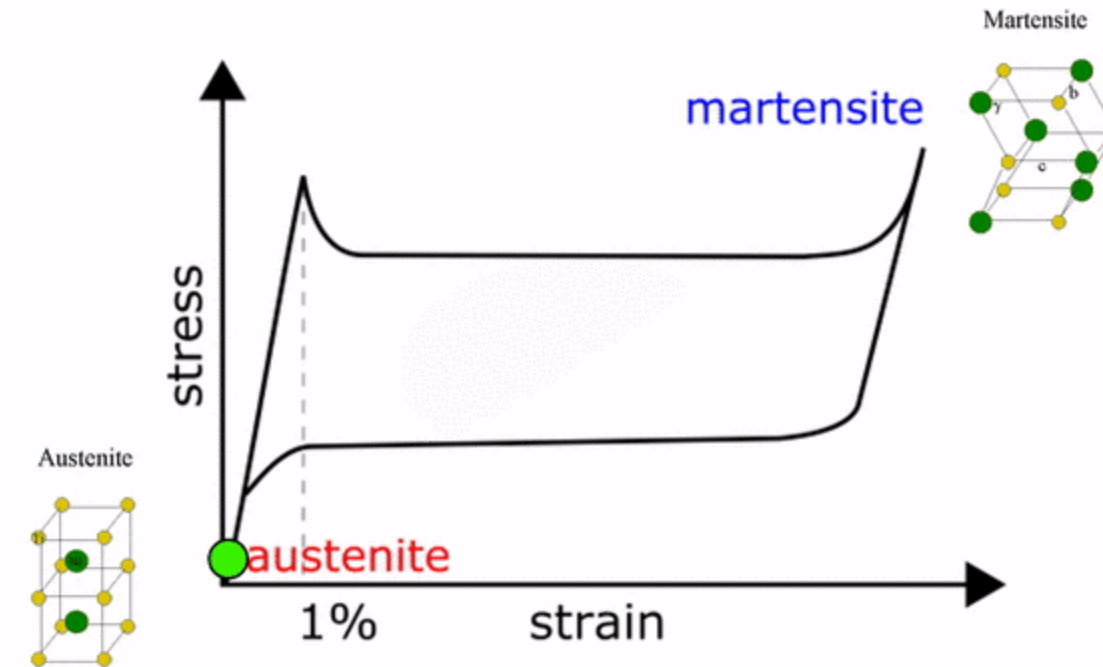


- The property of a body by virtue of which it tends to regain its original shape and size when deforming force is removed.
- All solids show the property of elasticity.

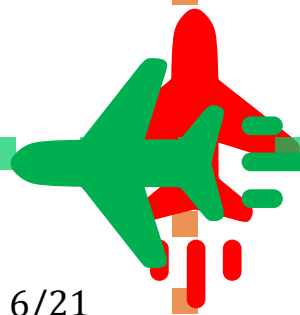




STRESS (σ)



Stress is the applied force or system of forces that tend to deform a body.





STRESS...



$$\text{Stress} = \frac{\text{External deforming force}}{F} = \frac{\text{Area}}{A}$$

- Dimensional formula of the stress = $\frac{[MLT^{-2}]}{L^2}$
 $\therefore [ML^{-1}T^{-2}]$

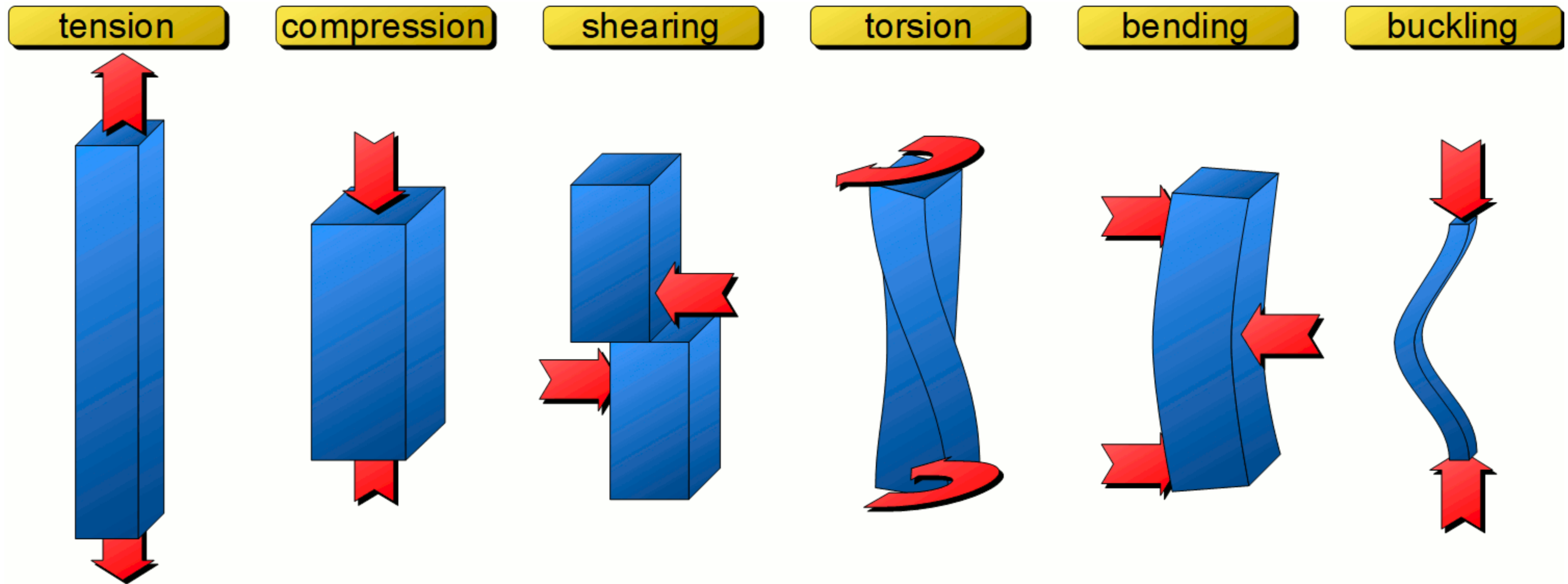
- The SI unit of stress is $Nm^{-2} = \text{Pascal}$

Same as that of pressure





BEHAVIOR OF SOLID OBJECTS





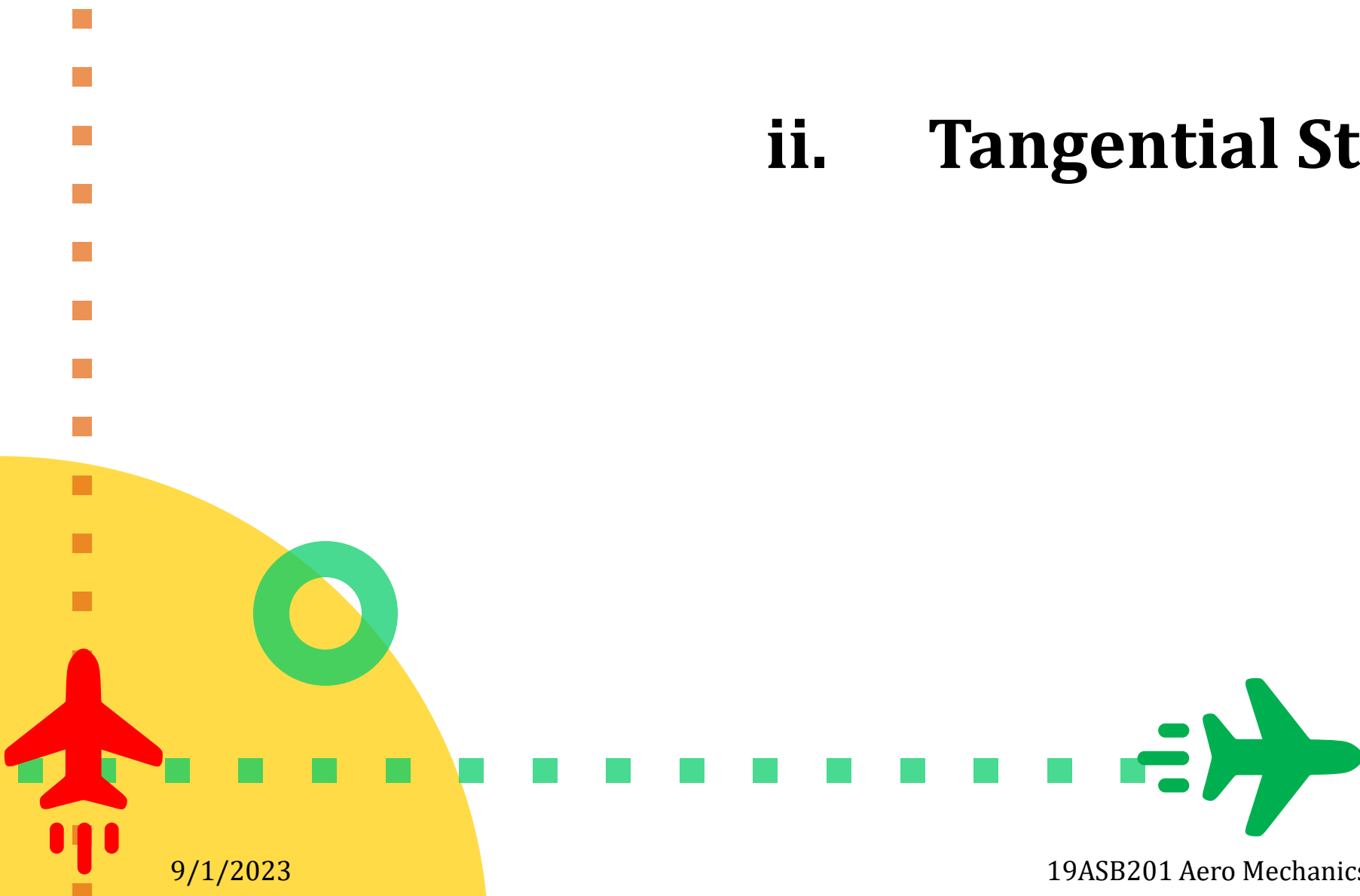
TYPES OF STRESS...



- The stress developed in a body depends upon how the external forces are applied over it. On this basis, there are two types of stress ,

i. Normal Stress

ii. Tangential Stress





NORMAL STRESS

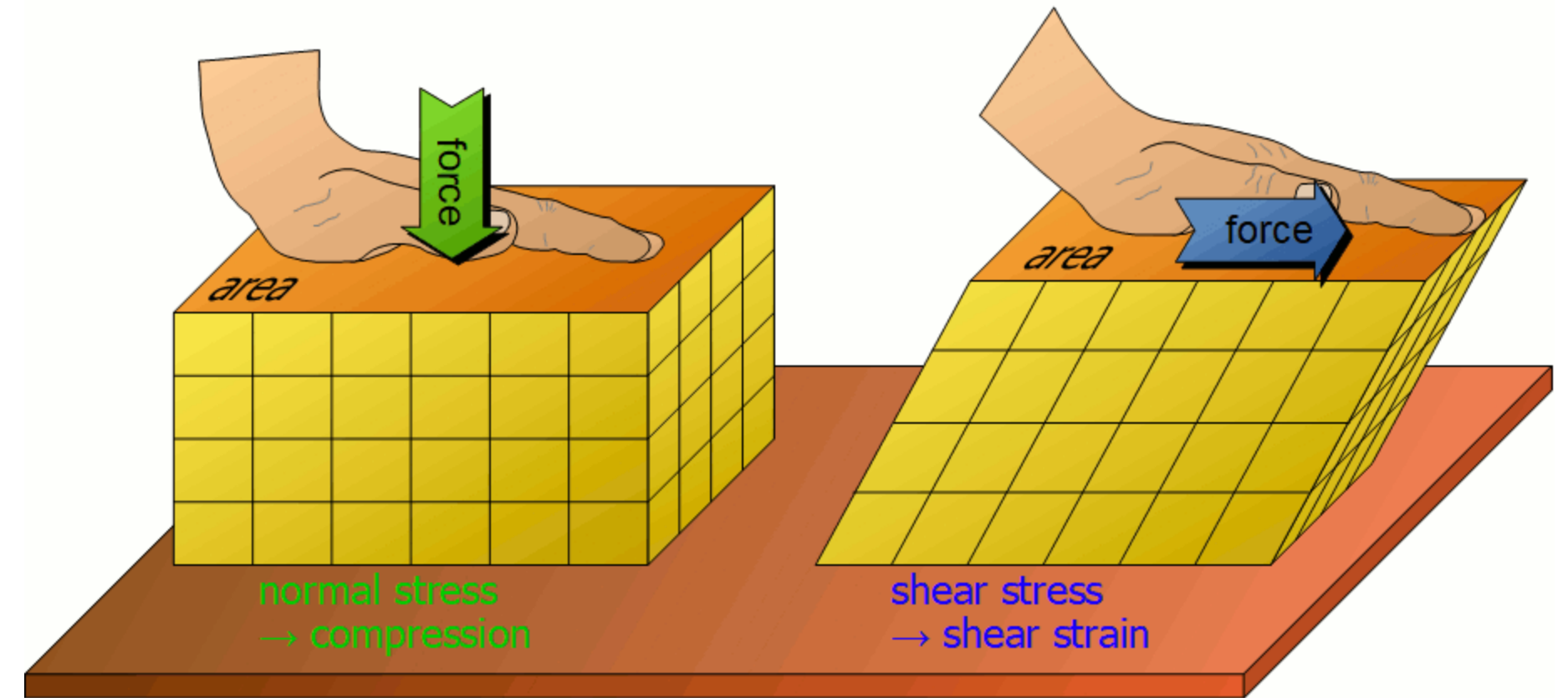
- Is a stress that occurs when the surface of the body is loaded by an axial force.

$$\sigma = \frac{P}{A}$$

σ – Normal Stress

P – Axial Force

A – Cross Sectional Area



- Normal stress is of two types;

i. Tensile stress

ii. Compressive stress

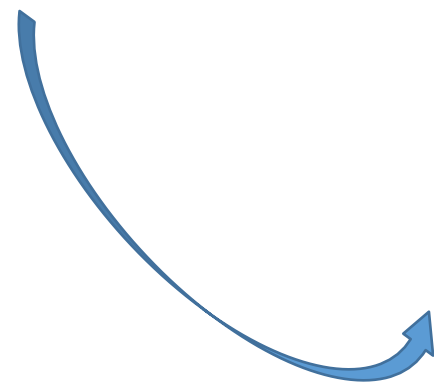




TENSILE STRESS



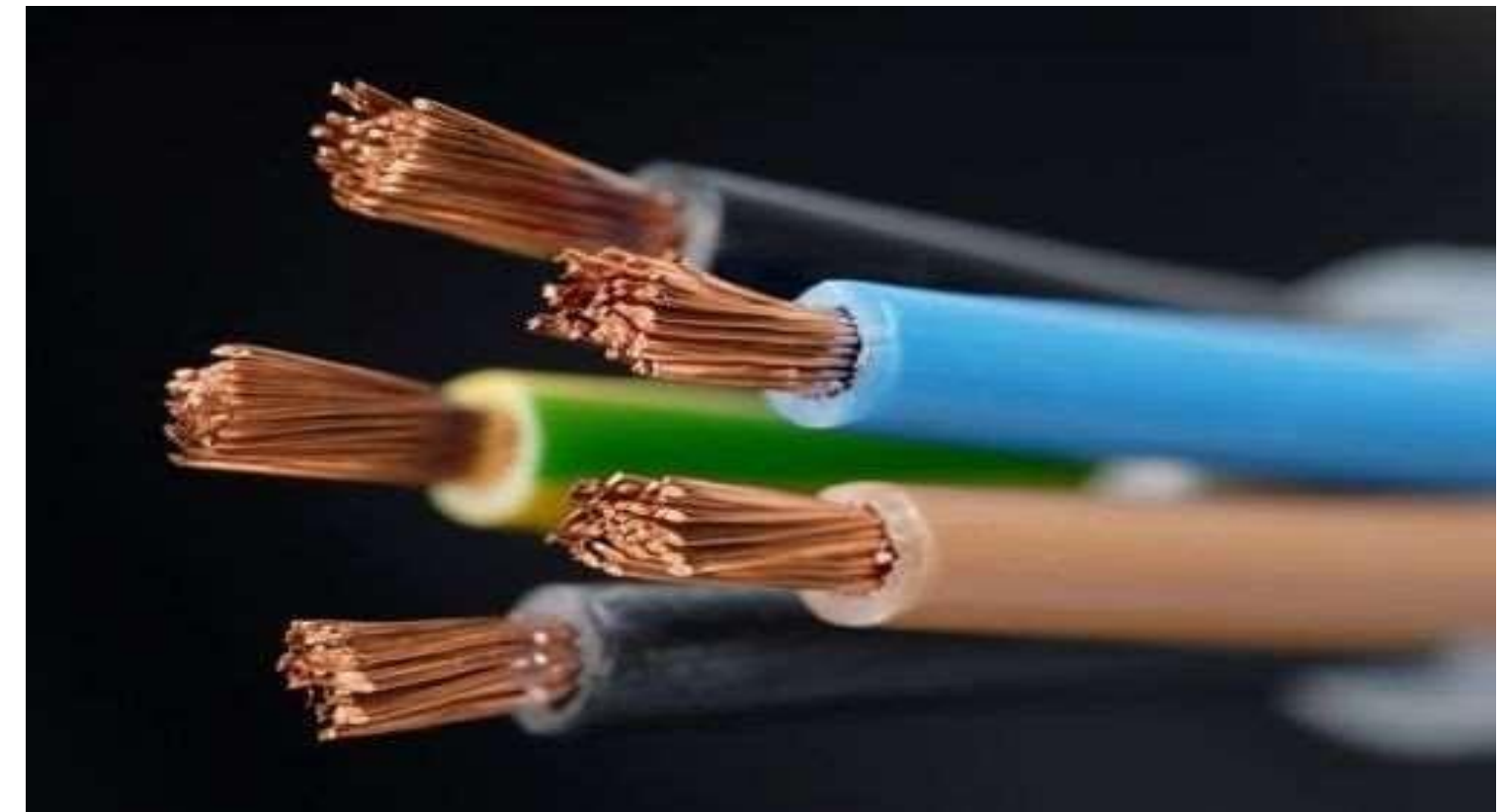
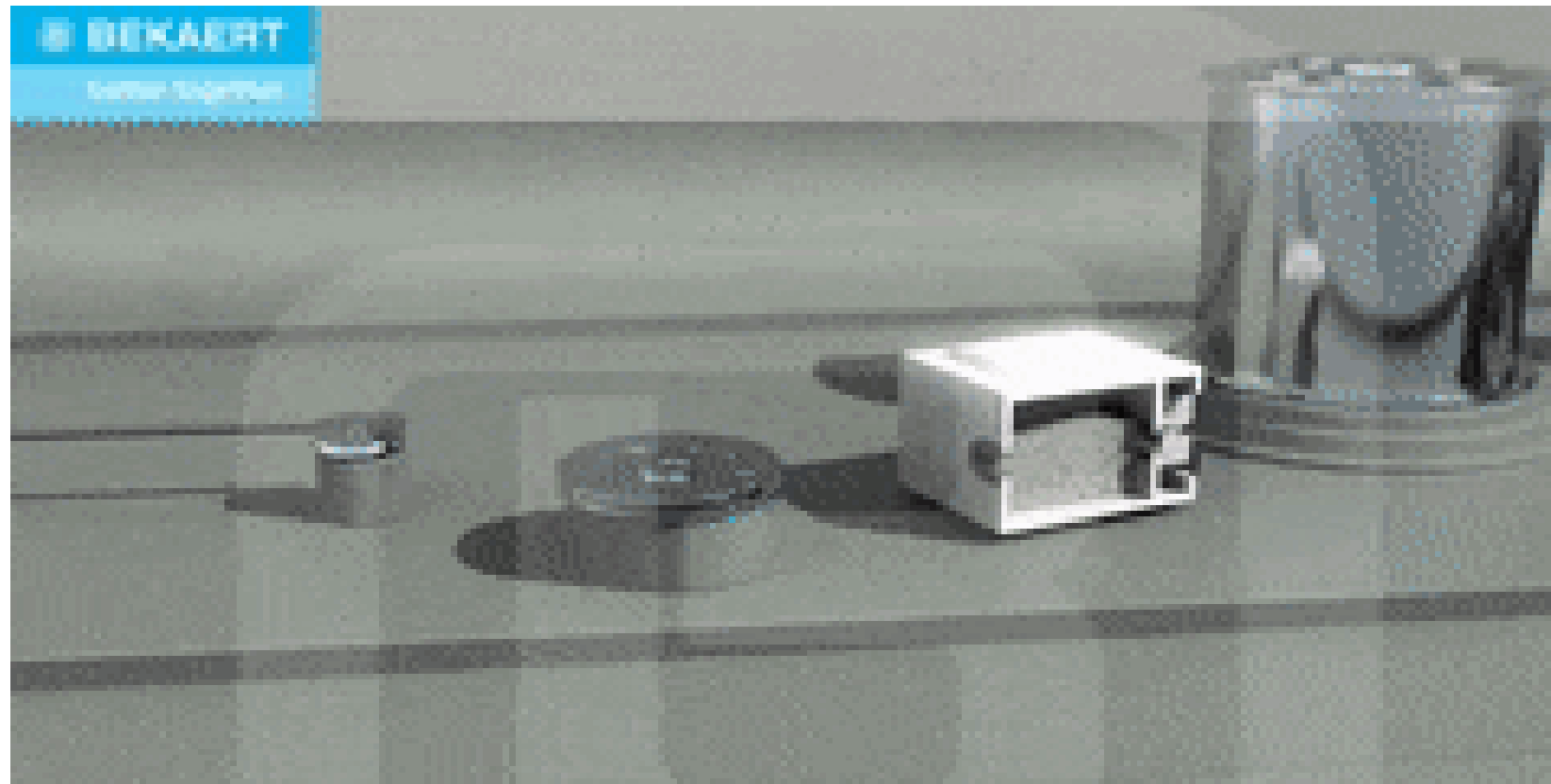
- Is the stress state leading to expansion; that is, the length of a material tends to increase in the tensile direction.
- This is an example of tensile stress tester (Universal Testing Machine)





DUCTILE BEHAVIOR

- Ductility is a solid material's ability to deform under tensile stress.



Copper wires





COMPRESSIVE STRESS



- A force that attempts to squeeze or compress a material.

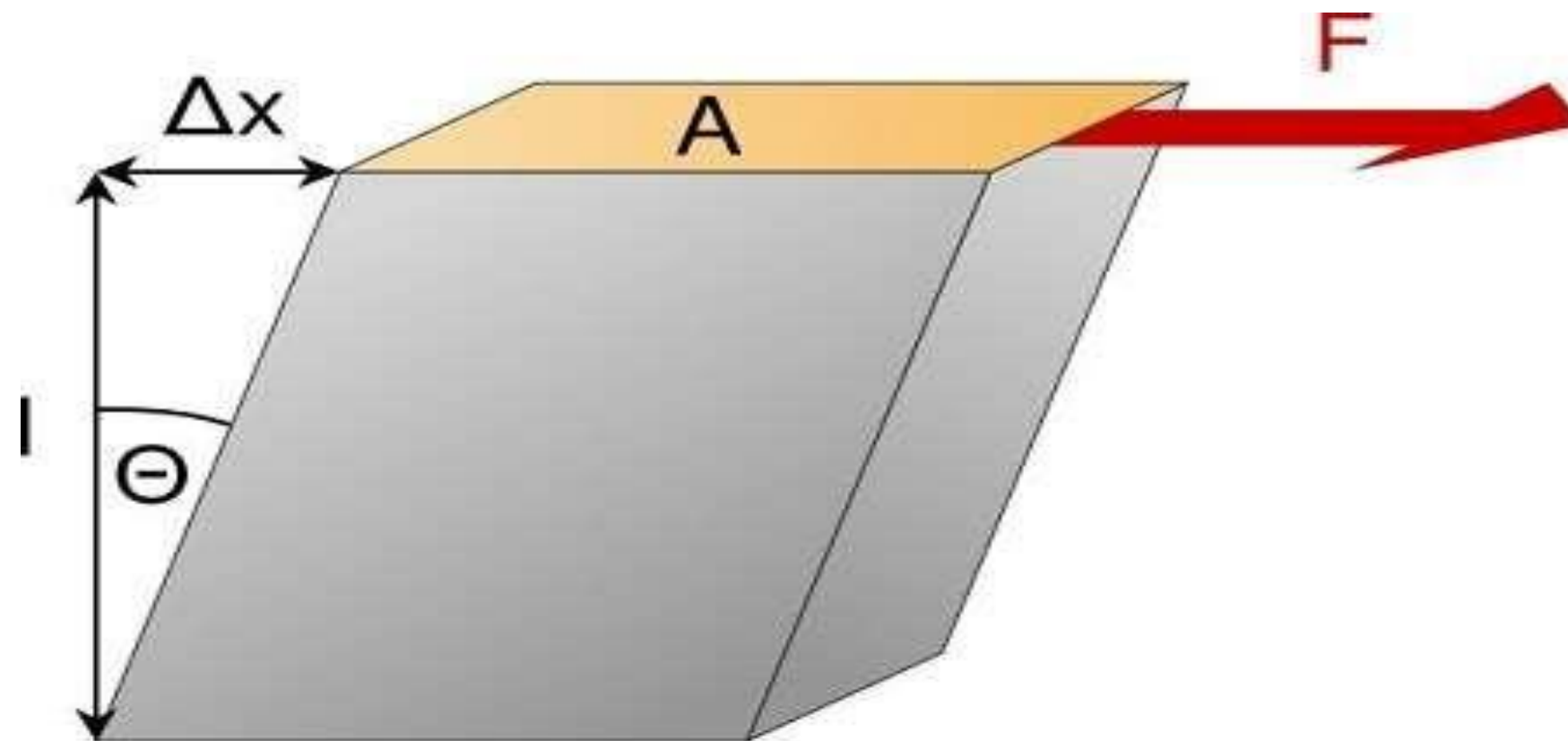


- Here, the Universal Testing Machine (UTM) is testing a concrete block.



TANGENTIAL STRESS

- A force acting in a generally horizontal direction; *especially* : a force that produces mountain folding and over thrusting





BRITTLE BEHAVIOR



- A material is brittle if, when subjected to stress, it breaks without insignificant deformation.
- Glass is a good example.





STRAIN (ϵ)



- Is the change in the size or shape of a body due to the deforming force. Type equation here.

$$\text{Strain,} = \frac{\text{Change in Dimension}}{\text{Original dimension}}$$

- i.e.

- **Strain is Dimensionless hence no unit**



TYPES OF STRAIN

- Since the deforming force can produce three of deformations (i.e. Change in length, or volume or shape) in a body, there are three types of strain;
 - i. Longitudinal strain
 - ii. Volumetric strain
 - iii. Shearing strain





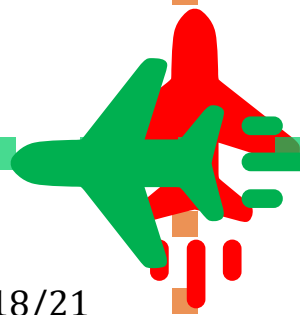
LONGITUDINAL STRAIN



- Is when the deforming force produces change in length.

- *Longitudinal Strain* =
$$\frac{\text{Change in Length}}{\text{Original Length}} = \frac{l}{L}$$

$$\therefore \epsilon_{\text{long}} = \frac{l}{L}$$





VOLUMETRIC STRAIN

- Is when the deforming force produces change in the volume.

$$\text{Volumetric Strain} = \frac{\text{Change in Volume}}{\text{Original Volume}} = \frac{\Delta V}{V}$$

$$\therefore \epsilon_{\text{vol}} = \frac{\Delta V}{V}$$





SHEARING STRAIN

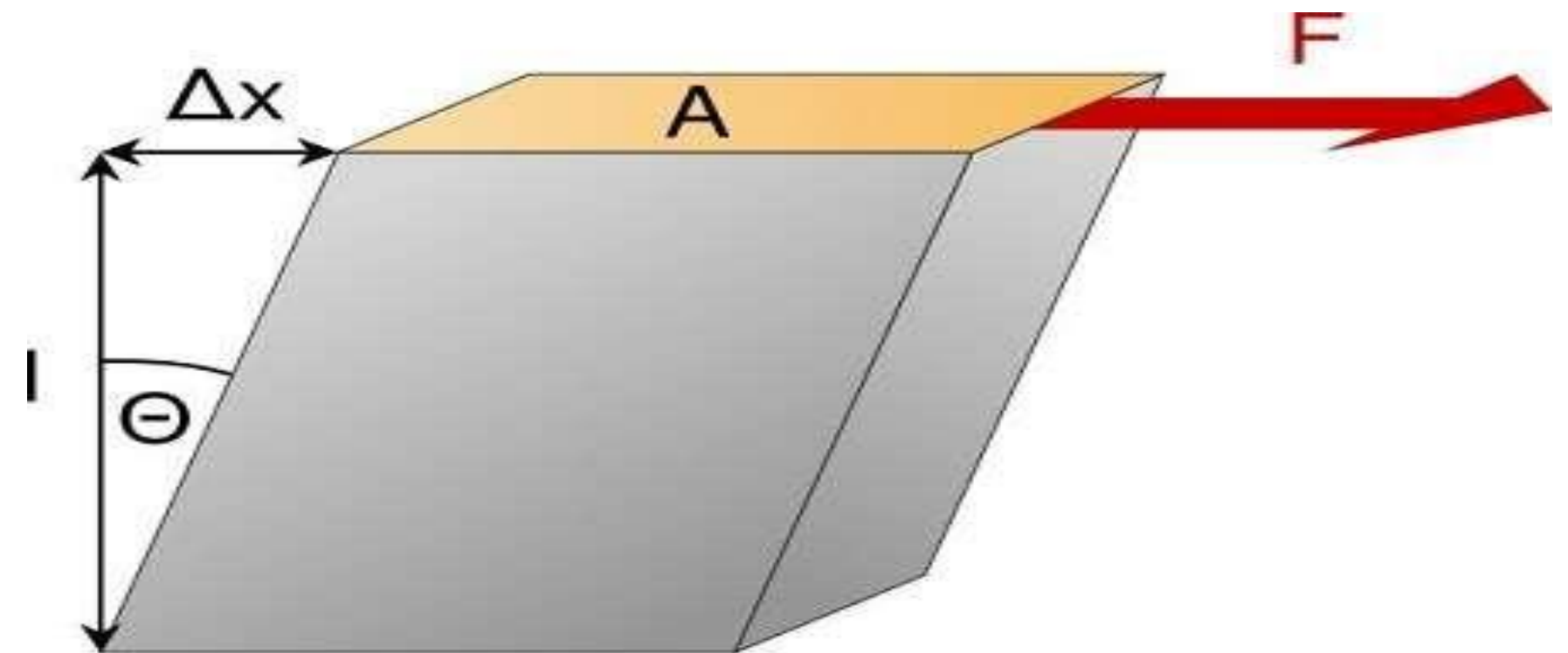
- Is when the deforming force produces change in the shape of the body.
- It is measured by the angle θ (in radian) through which a line originally perpendicular to the fixed face is turned due to the application of the tangential force.

- Shearing strain = θ

$$= \tan \theta$$

$$= \frac{\Delta x}{l}$$

- The figure below is said to be sheared through an angle θ .





S.NO	QUESTION	ANSWER
1	The ability to resist applied load is called	
2	The force required to produce unit deflection is called	
3	The materials having same properties in all directions are called	

OPTION	A	Isotropic materials
	B	Strength
	C	Stiffness

