

# **SNS COLLEGE OF TECHNOLOGY**

**Coimbatore-35 An Autonomous Institution** 

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# **DEPARTMENT OF ELECTRONICS & COMMUNICATION** ENGINEERING

## **19ECT312 – EMBEDDED SYSTEM DESIGN**

III YEAR/ VI SEMESTER

**UNIT 4 : EMBEDDED OPERATING SYSTEM AND MODELING** 

**TOPIC 4.2** Inter Process Communication





## **INTER PROCESS COMMUNICATION**

### What is Inter process communication in embedded system?

Interprocess communication is the mechanism provided by the operating system that allows processes to communicate with each other. This communication could involve a process letting another process know that some event has occurred or the transferring of data from one process to another









## **INTER PROCESS COMMUNIC ATION Synchronization**

 $\succ$ Synchronization is a necessary part of interprocess communication

 $\succ$ It is either provided by the interprocess control mechanism or handled by the communicating processes Examples:

## Semaphore

 $\succ$  A semaphore is a variable that controls the access to a common resource by multiple processes

 $\succ$ The two types of semaphores are binary semaphores and counting semaphores.

### **Mutual Exclusion**

 $\succ$  Mutual exclusion requires that only one process thread can enter the critical section at a time

 $\succ$ This is useful for synchronization and also prevents race conditions.





## **INTER PROCESS COMMUNIC ATION Synchronization**

## **Barrier**

 $\triangleright$ A barrier does not allow individual processes to proceed until all the processes reach it

Many parallel languages and collective routines impose barriers

### Spinlock

 $\succ$ This is a type of lock. The processes trying to acquire this lock wait in a loop while checking if the lock is available or not

 $\succ$ This is known as busy waiting because the process is not doing any useful operation even though it is active.





## **Interprocess Communication Approaches**

Approaches to Interprocess Communication



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## **Interprocess Communication Approaches**

## Pipe

 $\triangleright$  A pipe is a data channel that is unidirectional

>Two pipes can be used to create a two-way data channel between two processes

This uses standard input and output methods. Pipes are used in all POSIX systems as well as Windows operating systems.

## Socket

 $\succ$ The socket is the endpoint for sending or receiving data in a network  $\succ$ This is true for data sent between processes on the same computer or data sent between different computers on the same network ≻Most of the operating systems use sockets for communication.

### File

 $\triangleright$ A file is a data record that may be stored on a disk or acquired on demand by a file server

>Multiple processes can access a file as required. All operating systems use files for data storage.



### interprocess



## **Interprocess Communication Approaches**

Signal

 $\succ$ Signals are useful in interprocess communication in a limited way They are system messages that are sent from one process to another  $\succ$  Normally, signals are not used to transfer data but are used for remote commands between processes

## **Shared Memory**

 $\succ$ Shared memory is the memory that can be simultaneously accessed by multiple processes

 $\succ$ This is done so that the processes can communicate with each other. All POSIX systems, as well as Windows operating systems use shared memory.

### **Message Queue**

 $\succ$  Multiple processes can read and write data to the message queue without being connected to each other

 $\geq$  Messages are stored in the queue until their recipient retrieves them. Message queues are quite useful for interprocess communication and are used by most operating systems





## **THANK YOU**

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