

### **SNS COLLEGE OF TECHNOLOGY**



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#### **COURSE NAME : 19CST201 – OPERATING SYSTEMS**

#### **II YEAR/ IV SEMESTER**

### **UNIT – I OVERVIEW AND PROCESS MANAGEMENT**

**Topic: Multithreading Issues** 

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- Create a number of threads in a pool where they await work
- Advantages:
  - Usually slightly faster to service a request with an existing thread than create a new thread
  - Allows the number of threads in the application(s) to be
     **bound to the size of the pool**
  - Separating task to be performed from mechanics of creating task allows different strategies for running task
    - i.e.Tasks could be scheduled to run periodically



# **Threading Issues**



- Semantics of fork() and exec() system calls
- Signal handling

Synchronous and asynchronous

- Thread cancellation of target thread
  - Asynchronous or deferred
- Thread-local storage
- Scheduler Activations



# Semantics of fork() and exec()



- Does **fork()** duplicate only the calling thread or all threads?
  - Some UNIXes have two versions of fork
- exec() usually works as normal replace the running process including all threads







- n **Signals** are used in UNIX systems to notify a process that a particular event has occurred.
- n A signal handler is used to process signals
  - 1. Signal is generated by particular event
  - 2. Signal is delivered to a process
  - 3. Signal is handled by one of two signal handlers:
    - 1. default
    - 2. user-defined
- n Every signal has **default handler** that kernel runs when handling signal
  - User-defined signal handler can override default
  - For single-threaded, signal delivered to process
- n Where should a signal be delivered for multi-threaded?
  - Deliver the signal to the thread to which the signal applies
  - I Deliver the signal to every thread in the process
  - I Deliver the signal to certain threads in the process
  - Assign a specific thread to receive all signals for the process



## **Thread Cancellation**



- Terminating a thread before it has finished
- Thread to be canceled is target thread
- Two general approaches:
  - Asynchronous cancellation terminates the target thread immediately
  - Deferred cancellation allows the target thread to periodically check if it should be cancelled
- Pthread code to create and cancel a thread:

```
pthread_t tid;
/* create the thread */
pthread_create(&tid, 0, worker, NULL);
. . .
/* cancel the thread */
pthread_cancel(tid);
```







 Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Туре
Off	Disabled	_
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous

- If thread has cancellation disabled, cancellation remains pending until thread enables it
- Default type is deferred
  - Cancellation only occurs when thread reaches cancellation point
    - I.e. pthread\_testcancel()
    - Then cleanup handler is invoked
- On Linux systems, thread cancellation is handled through signals







- Thread-local storage (TLS) allows each thread to have its own copy of data
- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
- Different from local variables
  - Local variables visible only during single function invocation
  - TLS visible across function invocations
- Similar to **static** data
  - TLS is unique to each thread



### **Scheduler Activations**



- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Typically use an intermediate data structure between user and kernel threads lightweight process (LWP)
  - Appears to be a virtual processor on which process can schedule user thread to run
  - Each LWP attached to kernel thread
  - How many LWPs to create?
- Scheduler activations provide upcalls a communication mechanism from the kernel to the upcall handler in the thread library
- This communication allows an application to maintain the correct number kernel threads

   <sup>2</sup> - user thread

