



# Chapter 9: Memory Management

- Background
- Swapping
- Contiguous Allocation
- Paging
- Segmentation
- Segmentation with Paging



# Background

- Program must be brought into memory and placed within a process for it to be run.
- *Input queue* – collection of processes on the disk that are waiting to be brought into memory to run the program.
- User programs go through several steps before being run.





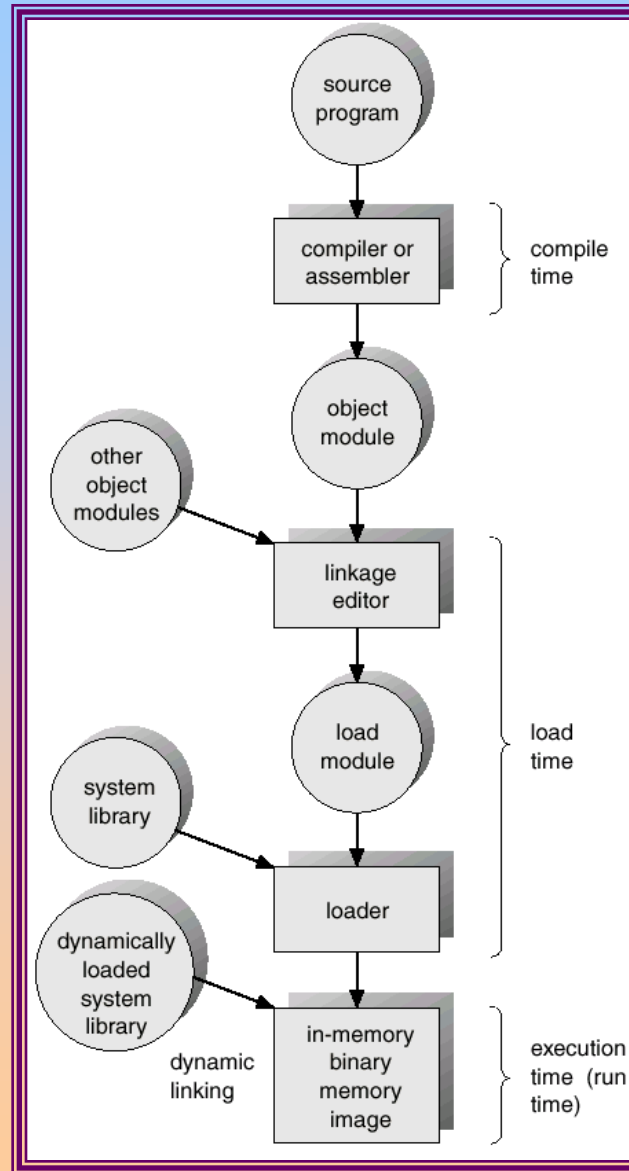
# Binding of Instructions and Data to Memory

Address binding of instructions and data to memory addresses can happen at three different stages.

- **Compile time:** If memory location known a priori, absolute code can be generated; must recompile code if starting location changes.
- **Load time:** Must generate *relocatable* code if memory location is not known at compile time.
- **Execution time:** Binding delayed until run time if the process can be moved during its execution from one memory segment to another. Need hardware support for address maps (e.g., *base* and *limit registers*).



# Multistep Processing of a User Program





# Logical vs. Physical Address Space

- The concept of a logical *address space* that is bound to a separate *physical address space* is central to proper memory management.
  - ☞ *Logical address* – generated by the CPU; also referred to as *virtual address*.
  - ☞ *Physical address* – address seen by the memory unit.
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme.



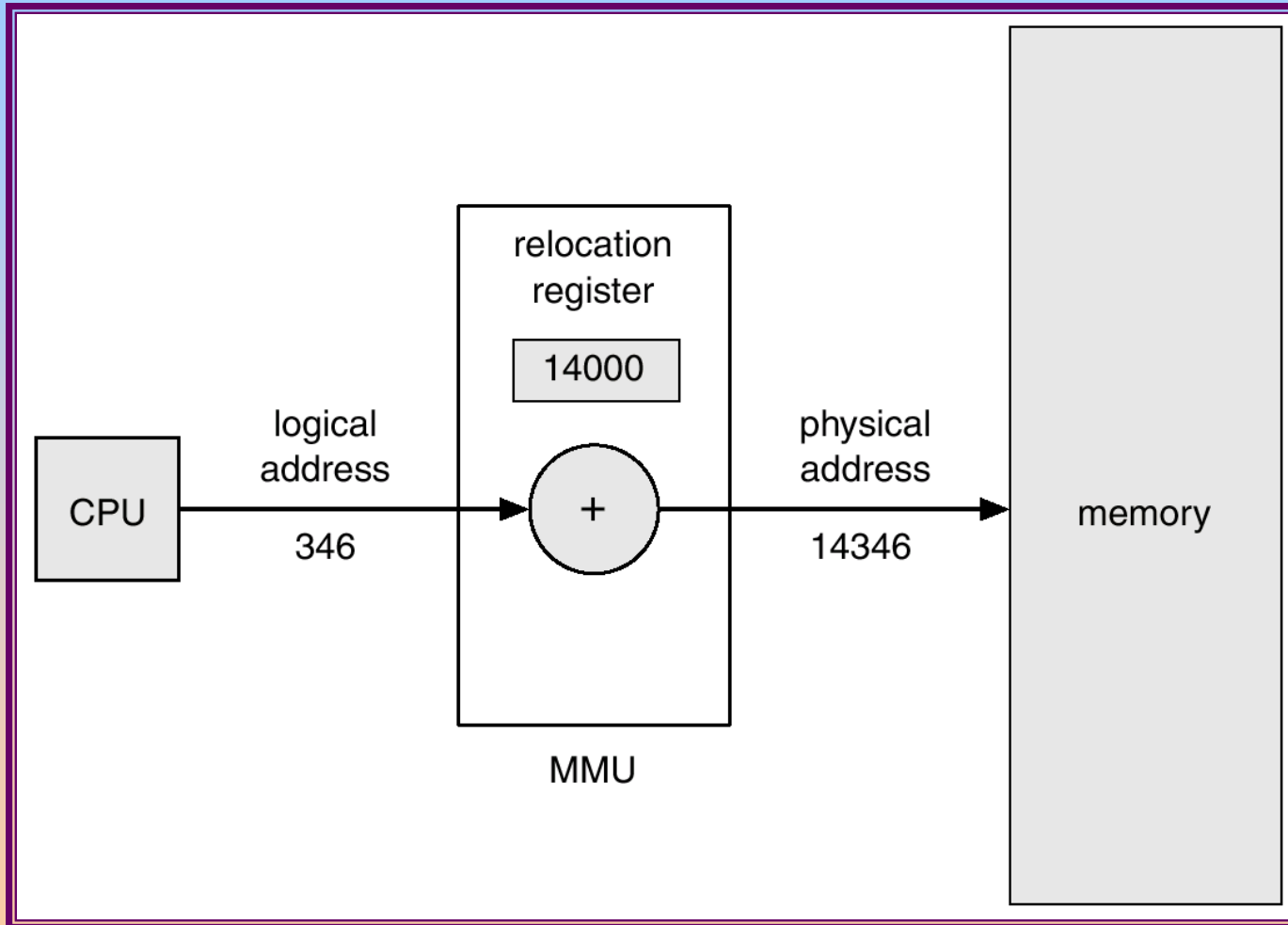


# Memory-Management Unit (MMU)

- Hardware device that maps virtual to physical address.
- In MMU scheme, the value in the relocation register is added to every address generated by a user process at the time it is sent to memory.
- The user program deals with *logical* addresses; it never sees the *real* physical addresses.



# Dynamic relocation using a relocation register



# Dynamic Loading

- Routine is not loaded until it is called
- Better memory-space utilization; unused routine is never loaded.
- Useful when large amounts of code are needed to handle infrequently occurring cases.
- No special support from the operating system is required implemented through program design.





# Dynamic Linking

- Linking postponed until execution time.
- Small piece of code, *stub*, used to locate the appropriate memory-resident library routine.
- Stub replaces itself with the address of the routine, and executes the routine.
- Operating system needed to check if routine is in processes' memory address.
- Dynamic linking is particularly useful for libraries.

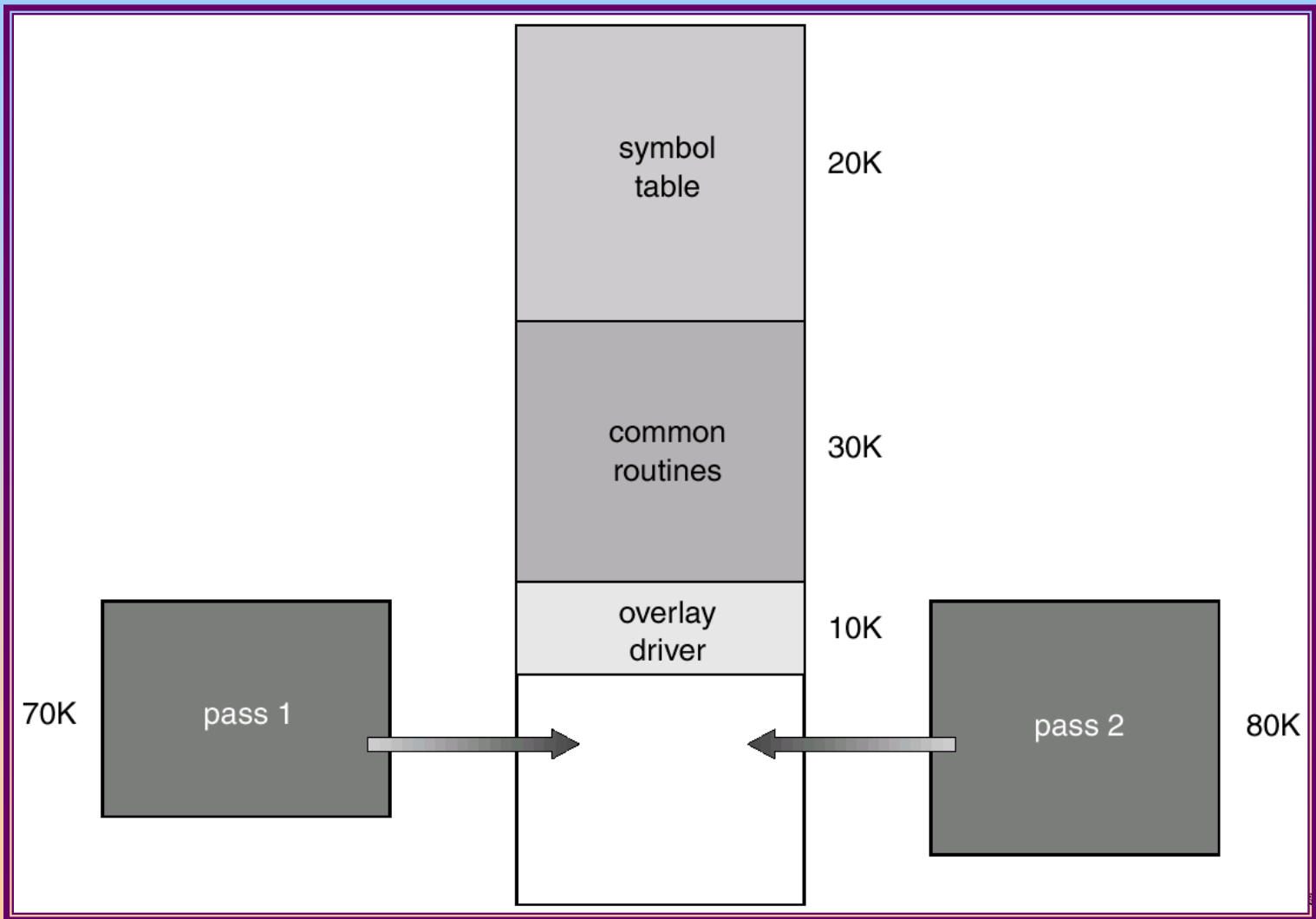


# Overlays

- Keep in memory only those instructions and data that are needed at any given time.
- Needed when process is larger than amount of memory allocated to it.
- Implemented by user, no special support needed from operating system, programming design of overlay structure is complex



# Overlays for a Two-Pass Assembler

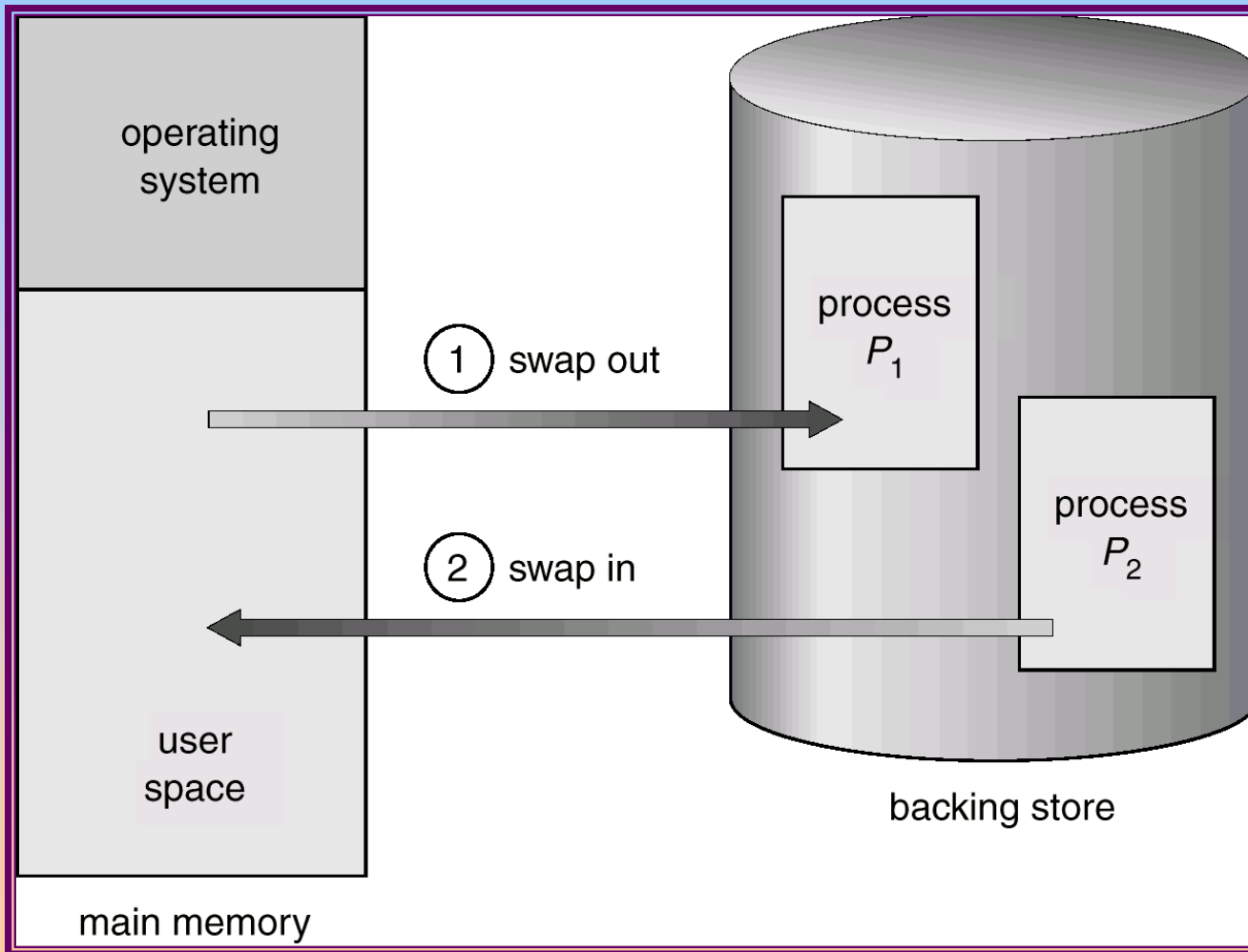


# Swapping

- A process can be *swapped* temporarily out of memory to a *backing store*, and then brought back into memory for continued execution.
- Backing store – fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images.
- *Roll out, roll in* – swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed.
- Major part of swap time is transfer time; total transfer time is directly proportional to the *amount* of memory swapped.
- Modified versions of swapping are found on many systems, i.e., UNIX, Linux, and Windows.



# Schematic View of Swapping

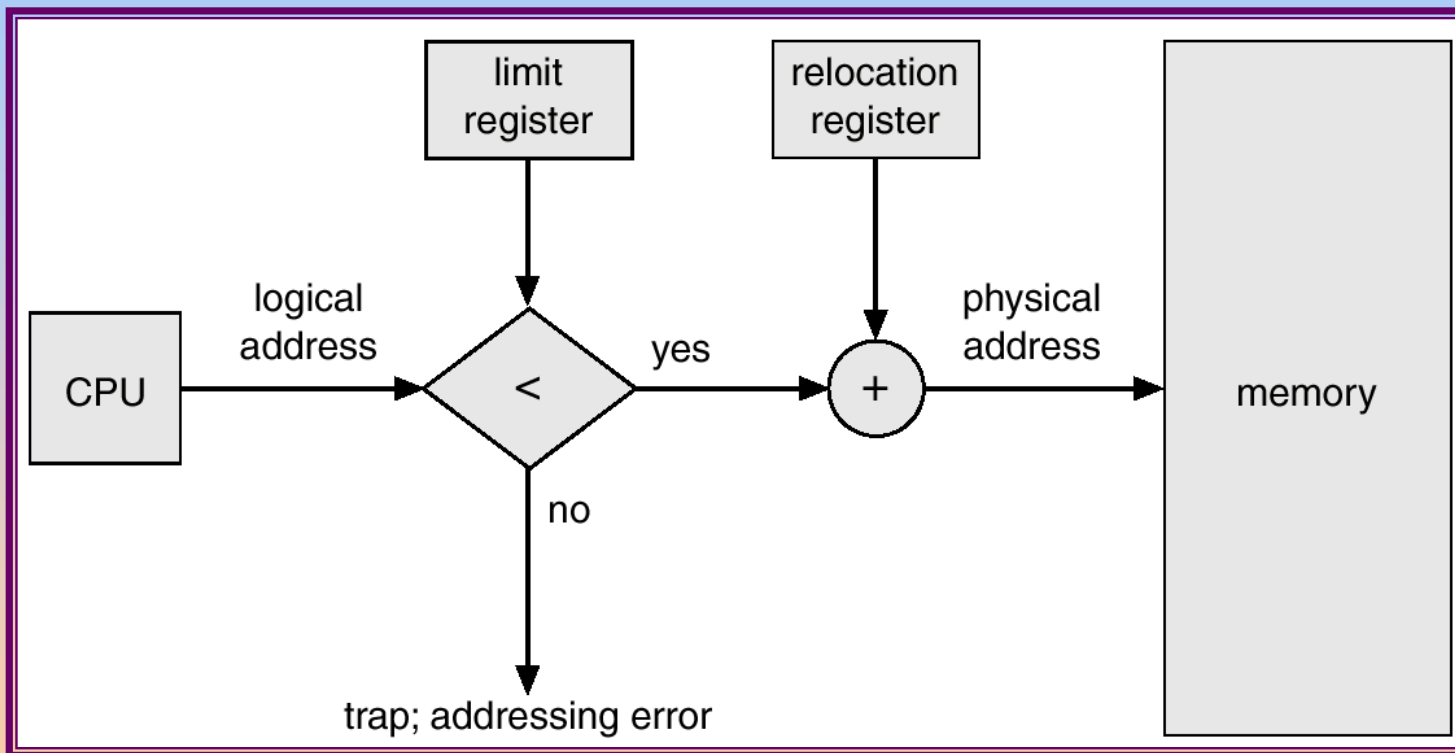


# Contiguous Allocation

- Main memory usually into two partitions:
  - ☞ Resident operating system, usually held in low memory with interrupt vector.
  - ☞ User processes then held in high memory.
- Single-partition allocation
  - ☞ Relocation-register scheme used to protect user processes from each other, and from changing operating-system code and data.
  - ☞ Relocation register contains value of smallest physical address; limit register contains range of logical addresses – each logical address must be less than the limit register.



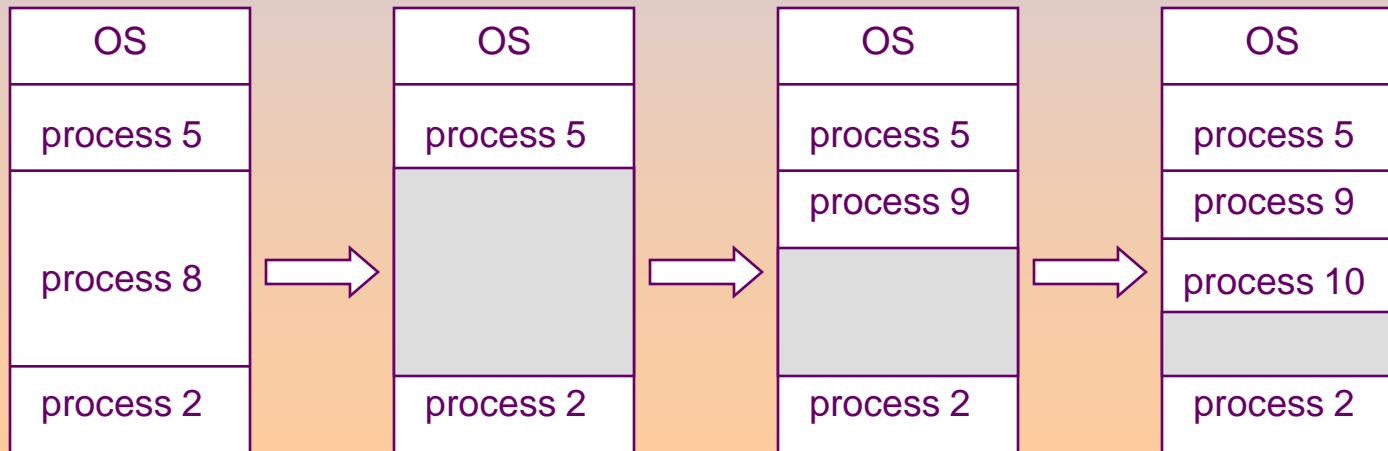
# Hardware Support for Relocation and Limit Registers



# Contiguous Allocation (Cont.)

## ■ Multiple-partition allocation

- ☞ *Hole* – block of available memory; holes of various size are scattered throughout memory.
- ☞ When a process arrives, it is allocated memory from a hole large enough to accommodate it.
- ☞ Operating system maintains information about:  
a) allocated partitions    b) free partitions (hole)







# Dynamic Storage-Allocation Problem

How to satisfy a request of size  $n$  from a list of free holes.

- **First-fit:** Allocate the *first* hole that is big enough.
- **Best-fit:** Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size. Produces the smallest leftover hole.
- **Worst-fit:** Allocate the *largest* hole; must also search entire list. Produces the largest leftover hole.

First-fit and best-fit better than worst-fit in terms of speed and storage utilization.



# Fragmentation

- **External Fragmentation** – total memory space exists to satisfy a request, but it is not contiguous.
- **Internal Fragmentation** – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used.
- Reduce external fragmentation by compaction
  - ☞ Shuffle memory contents to place all free memory together in one large block.
  - ☞ Compaction is possible *only* if relocation is dynamic, and is done at execution time.
  - ☞ I/O problem
    - 📄 Latch job in memory while it is involved in I/O.
    - 📄 Do I/O only into OS buffers.



# Paging

- Logical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available.
- Divide physical memory into fixed-sized blocks called **frames** (size is power of 2, between 512 bytes and 8192 bytes).
- Divide logical memory into blocks of same size called **pages**.
- Keep track of all free frames.
- To run a program of size  $n$  pages, need to find  $n$  free frames and load program.
- Set up a page table to translate logical to physical addresses.
- Internal fragmentation.

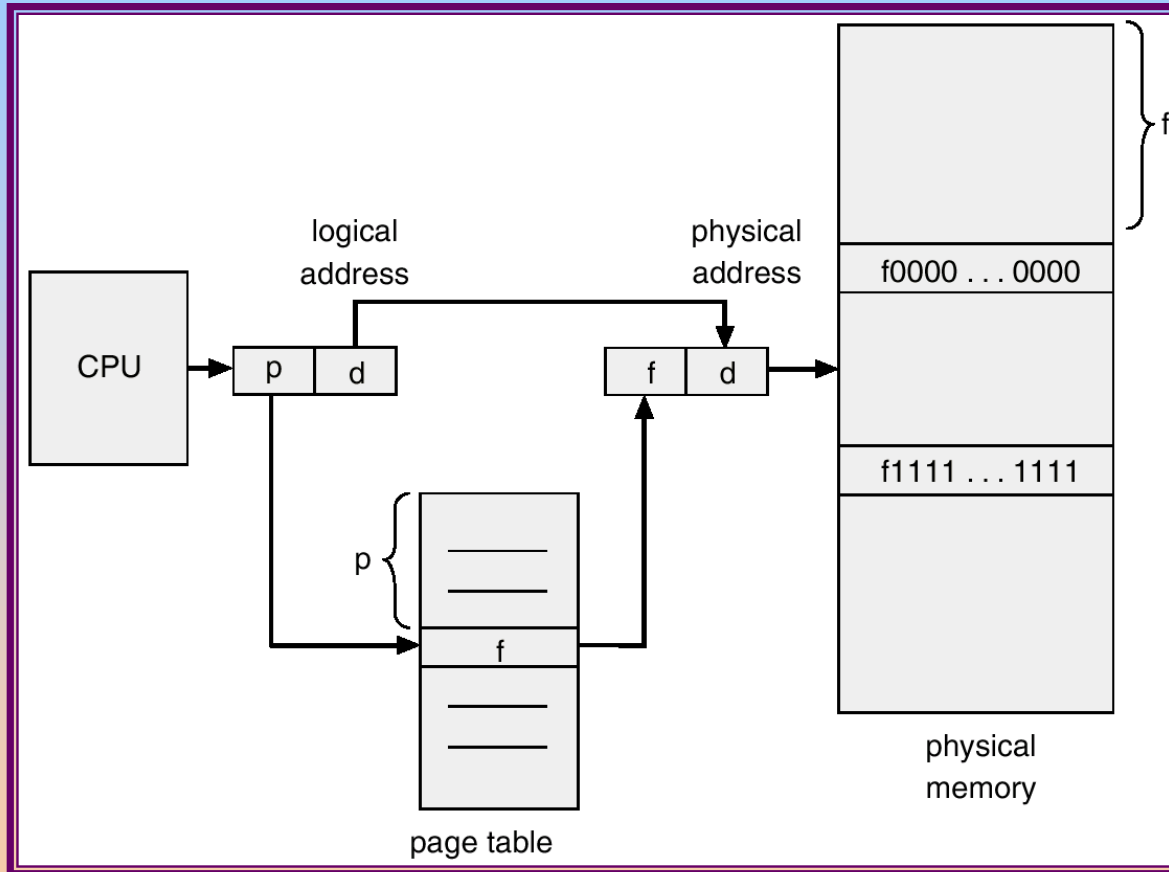


# Address Translation Scheme

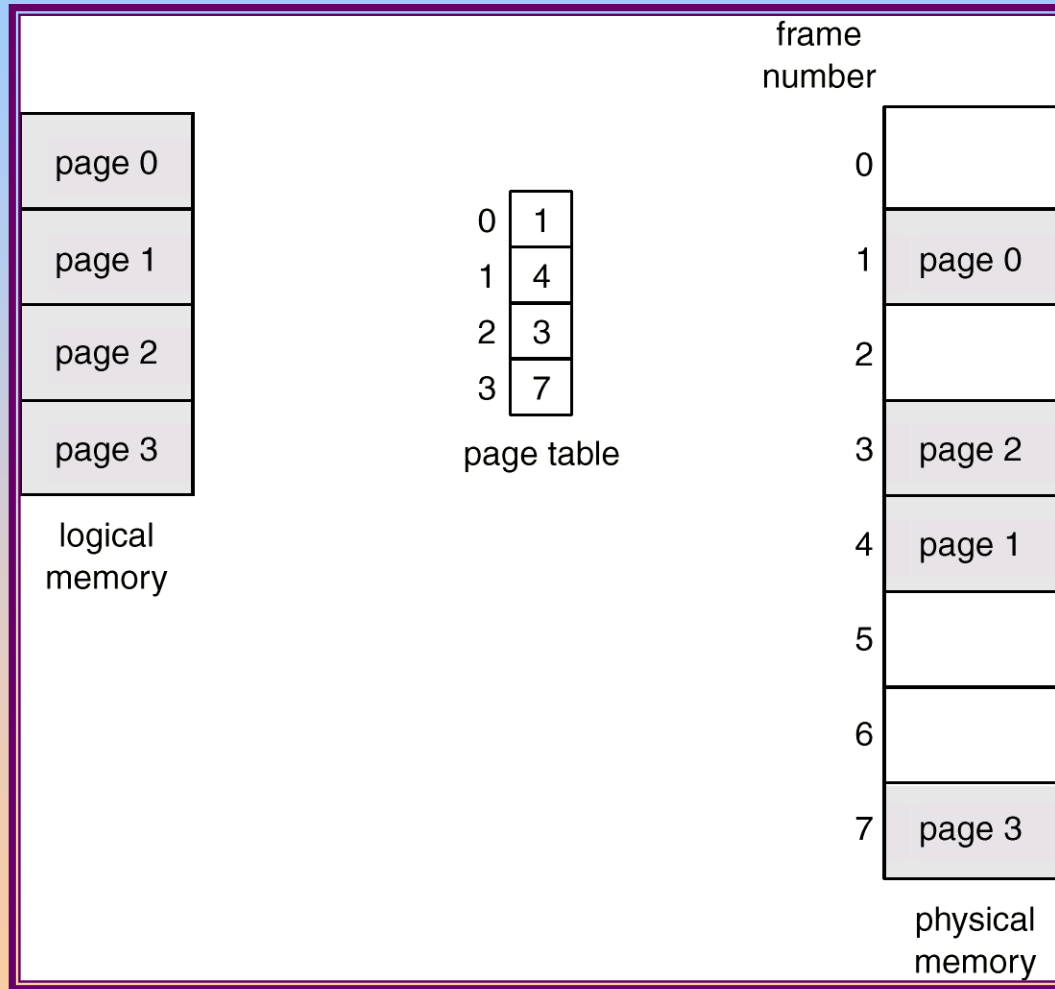
- Address generated by CPU is divided into:
  - ☞ *Page number (p)* – used as an index into a *page table* which contains base address of each page in physical memory.
  - ☞ *Page offset (d)* – combined with base address to define the physical memory address that is sent to the memory unit.



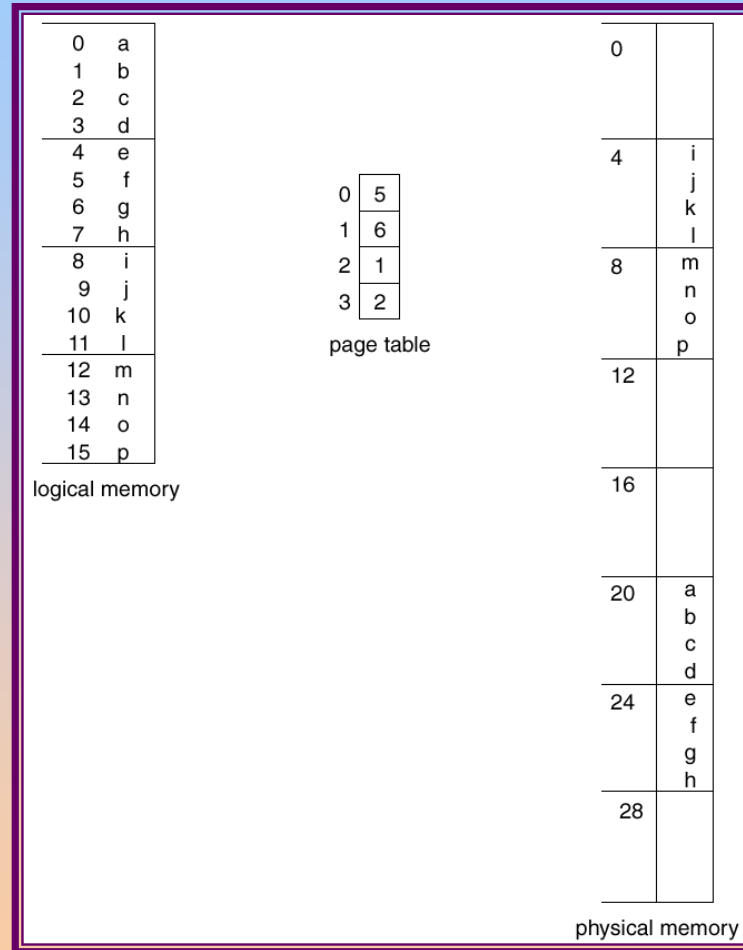
# Address Translation Architecture



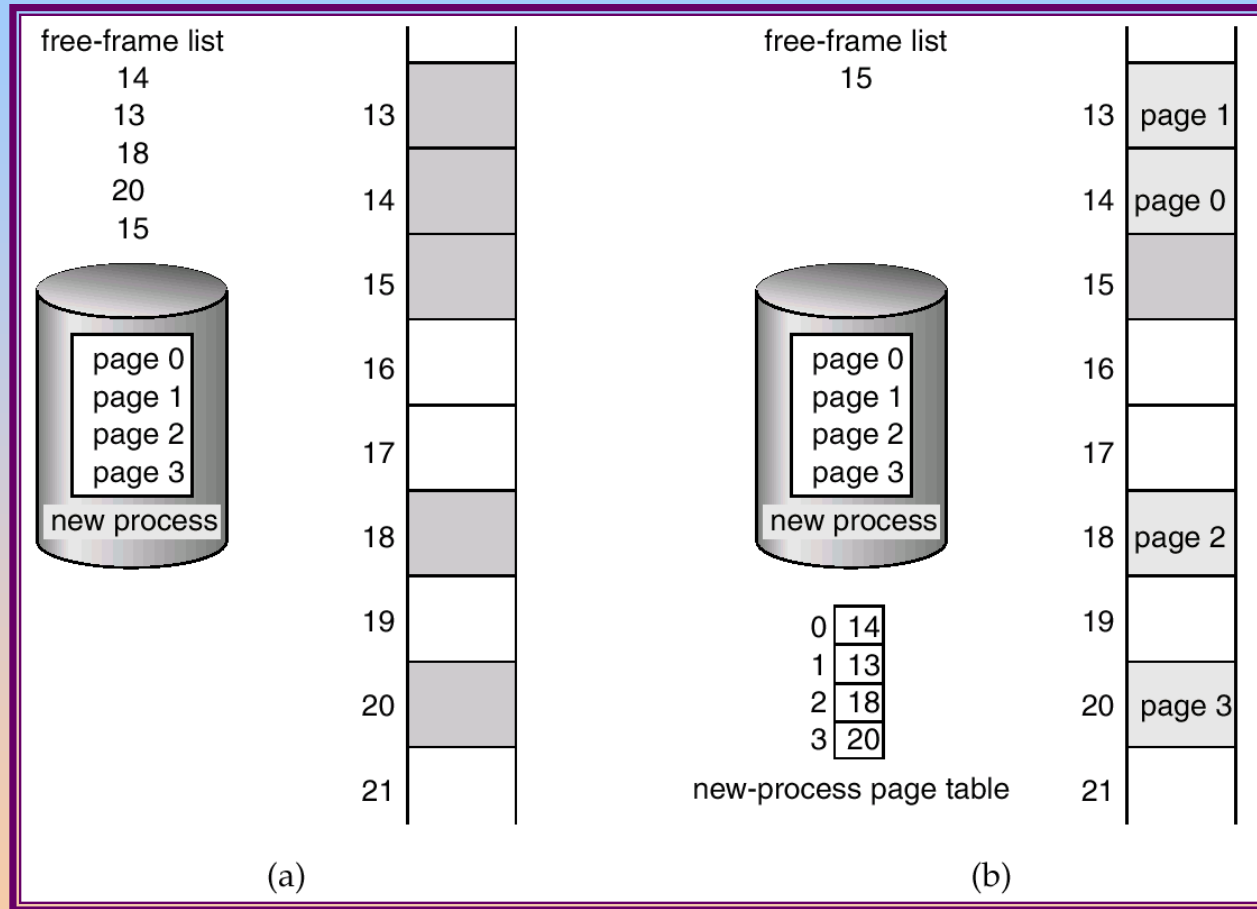
# Paging Example



# Paging Example



# Free Frames



Before allocation

After allocation







# Implementation of Page Table

- Page table is kept in main memory.
- *Page-table base register (PTBR)* points to the page table.
- *Page-table length register (PRLR)* indicates size of the page table.
- In this scheme every data/instruction access requires two memory accesses. One for the page table and one for the data/instruction.
- The two memory access problem can be solved by the use of a special fast-lookup hardware cache called *associative memory* or *translation look-aside buffers (TLBs)*



# Associative Memory

- Associative memory – parallel search

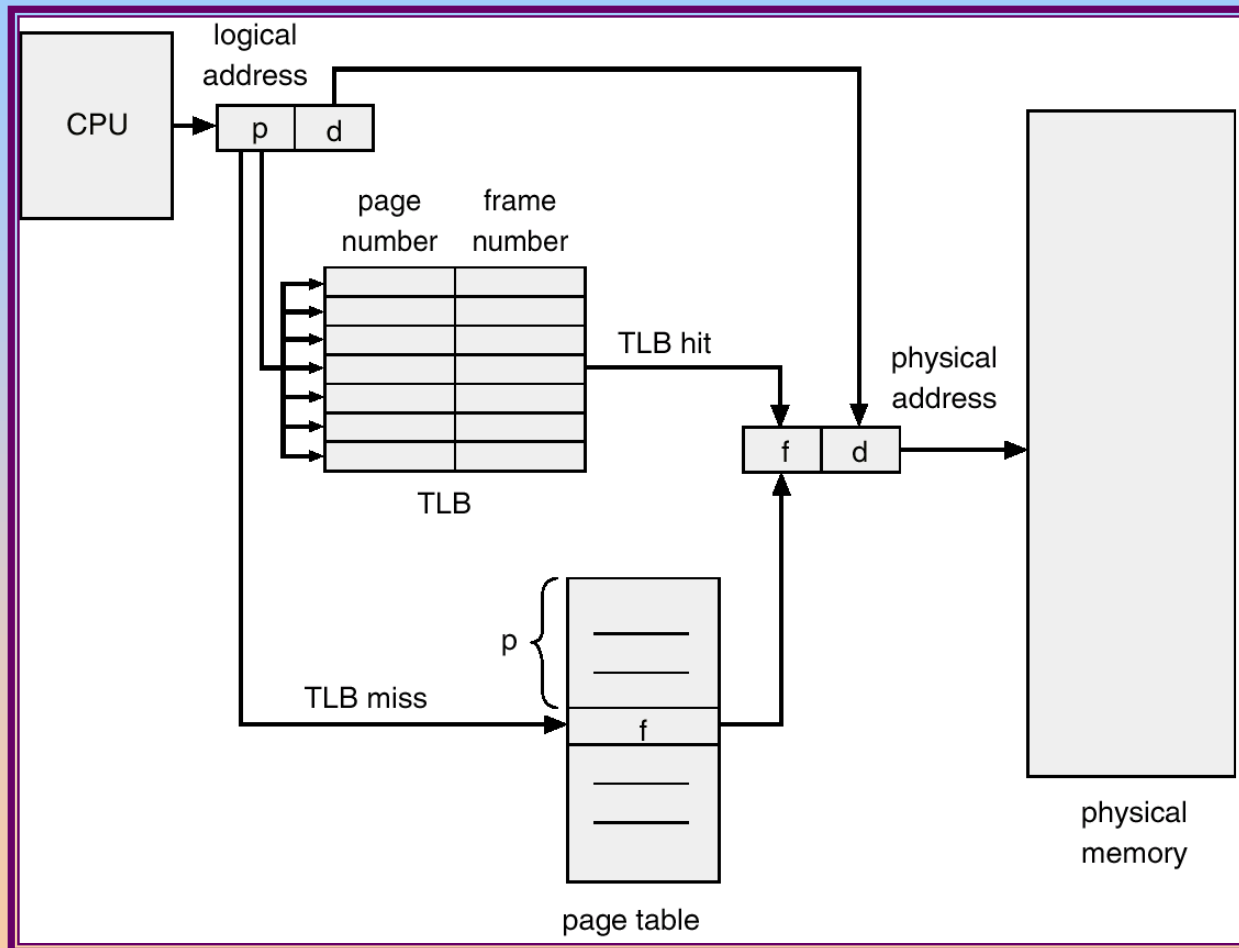
Page #	Frame #

Address translation ( $A'$ ,  $A''$ )

- ☞ If  $A'$  is in associative register, get frame # out.
- ☞ Otherwise get frame # from page table in memory



# Paging Hardware With TLB



# Effective Access Time

- Associative Lookup =  $\varepsilon$  time unit
- Assume memory cycle time is 1 microsecond
- Hit ratio – percentage of times that a page number is found in the associative registers; ration related to number of associative registers.
- Hit ratio =  $\alpha$
- Effective Access Time (EAT)

$$\begin{aligned} \text{EAT} &= (1 + \varepsilon) \alpha + (2 + \varepsilon)(1 - \alpha) \\ &= 2 + \varepsilon - \alpha \end{aligned}$$



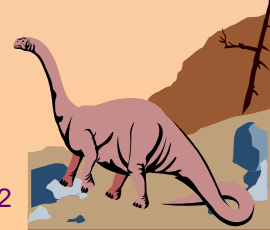
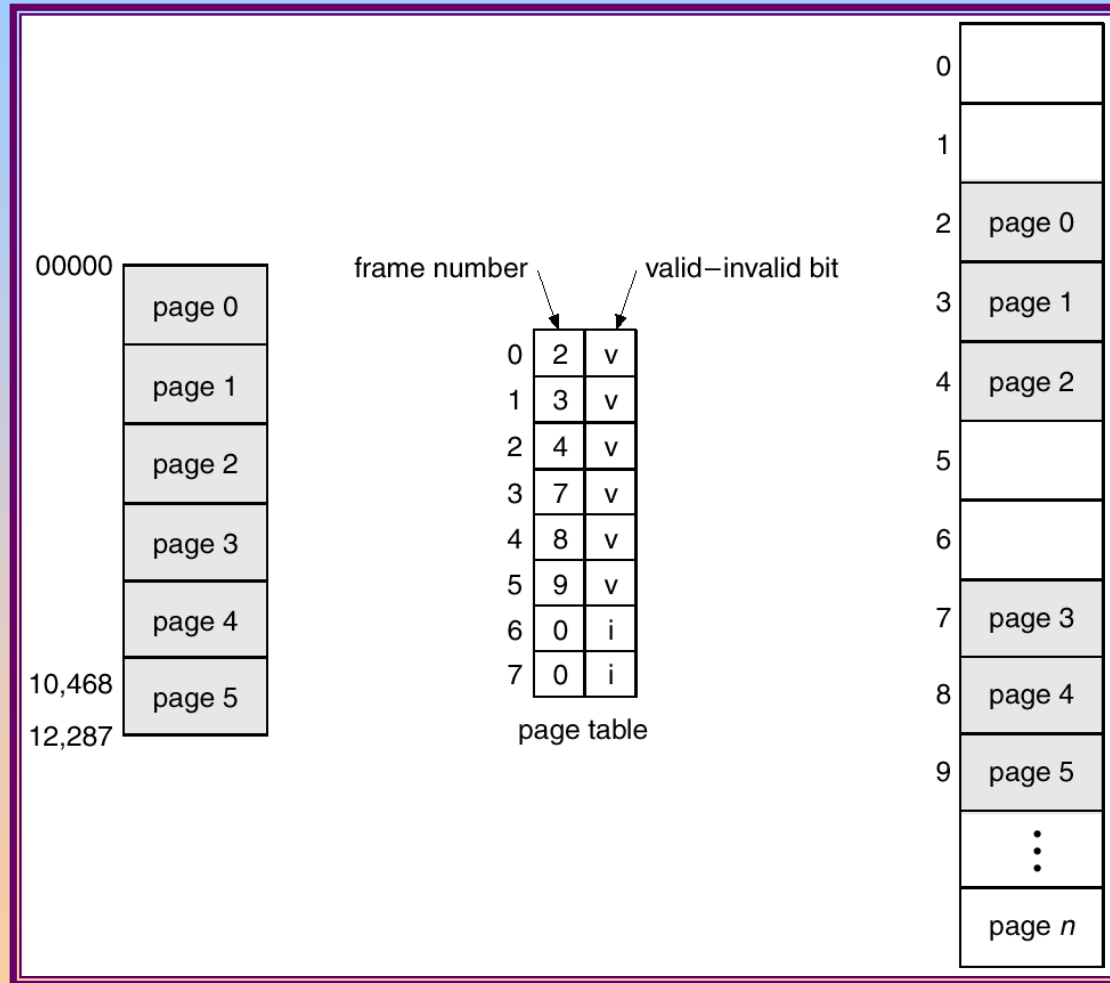
# Memory Protection

- Memory protection implemented by associating protection bit with each frame.
- *Valid-invalid* bit attached to each entry in the page table:
  - ☞ “valid” indicates that the associated page is in the process’ logical address space, and is thus a legal page.
  - ☞ “invalid” indicates that the page is not in the process’ logical address space.





# Valid (v) or Invalid (i) Bit In A Page Table



# Page Table Structure

- Hierarchical Paging
- Hashed Page Tables
- Inverted Page Tables





# Hierarchical Page Tables

- Break up the logical address space into multiple page tables.
- A simple technique is a two-level page table.

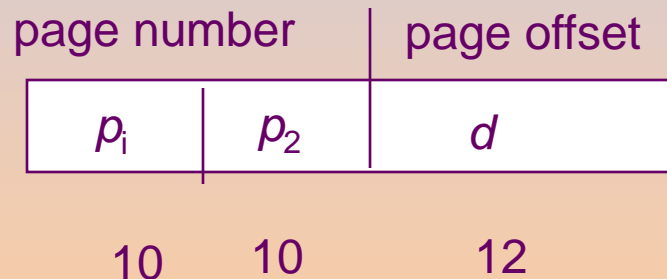






# Two-Level Paging Example

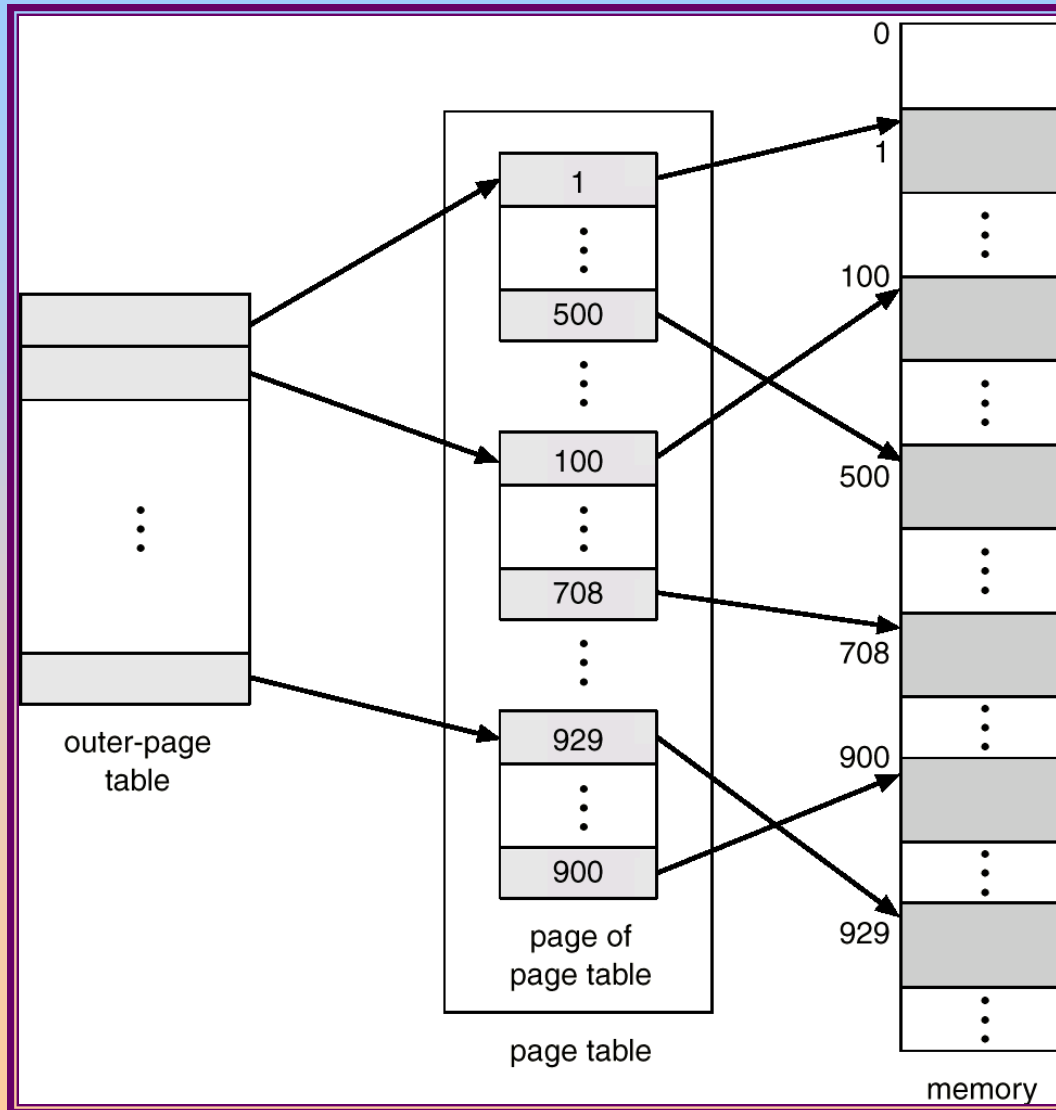
- A logical address (on 32-bit machine with 4K page size) is divided into:
  - ☞ a page number consisting of 20 bits.
  - ☞ a page offset consisting of 12 bits.
- Since the page table is paged, the page number is further divided into:
  - ☞ a 10-bit page number.
  - ☞ a 10-bit page offset.
- Thus, a logical address is as follows:



where  $p_1$  is an index into the outer page table, and  $p_2$  is the displacement within the page of the outer page table.

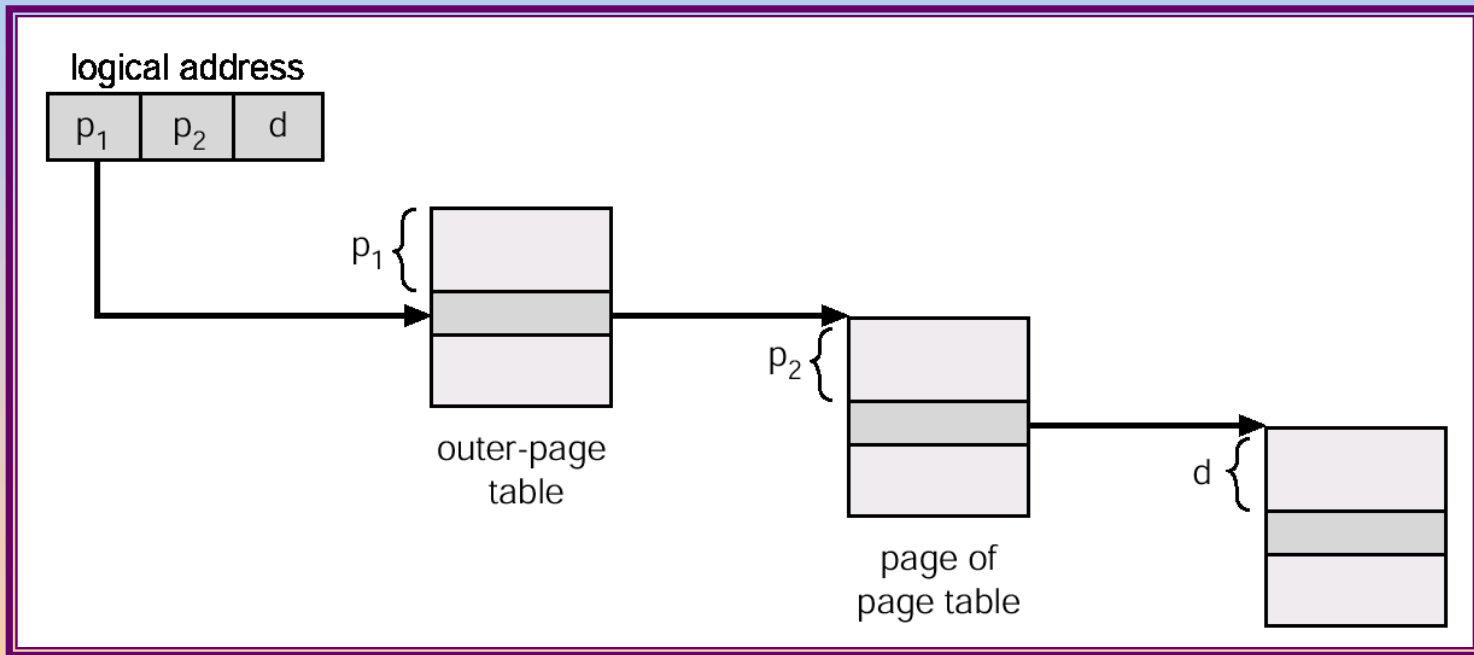


# Two-Level Page-Table Scheme



# Address-Translation Scheme

- Address-translation scheme for a two-level 32-bit paging architecture

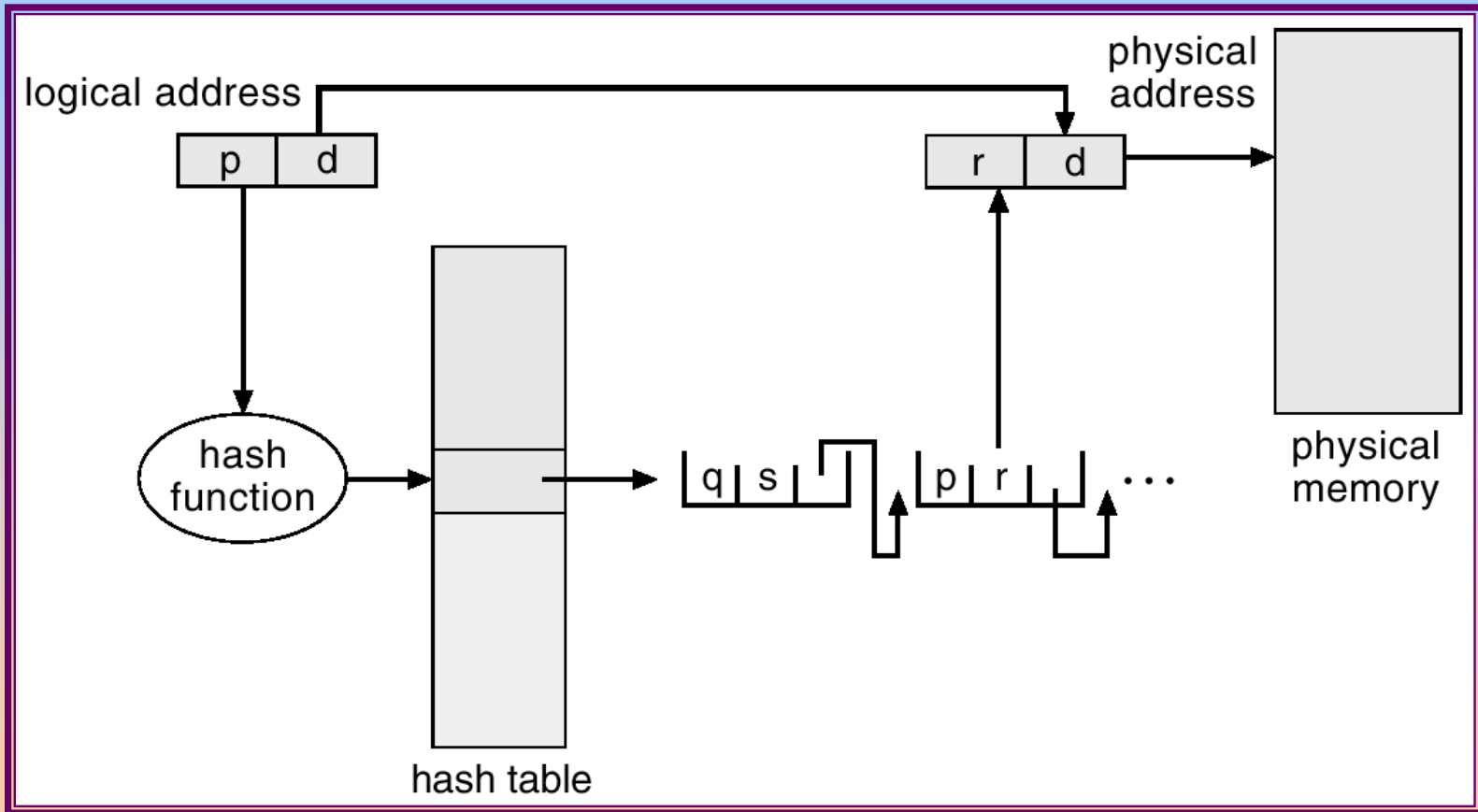


# Hashed Page Tables

- Common in address spaces  $> 32$  bits.
- The virtual page number is hashed into a page table. This page table contains a chain of elements hashing to the same location.
- Virtual page numbers are compared in this chain searching for a match. If a match is found, the corresponding physical frame is extracted.



# Hashed Page Table



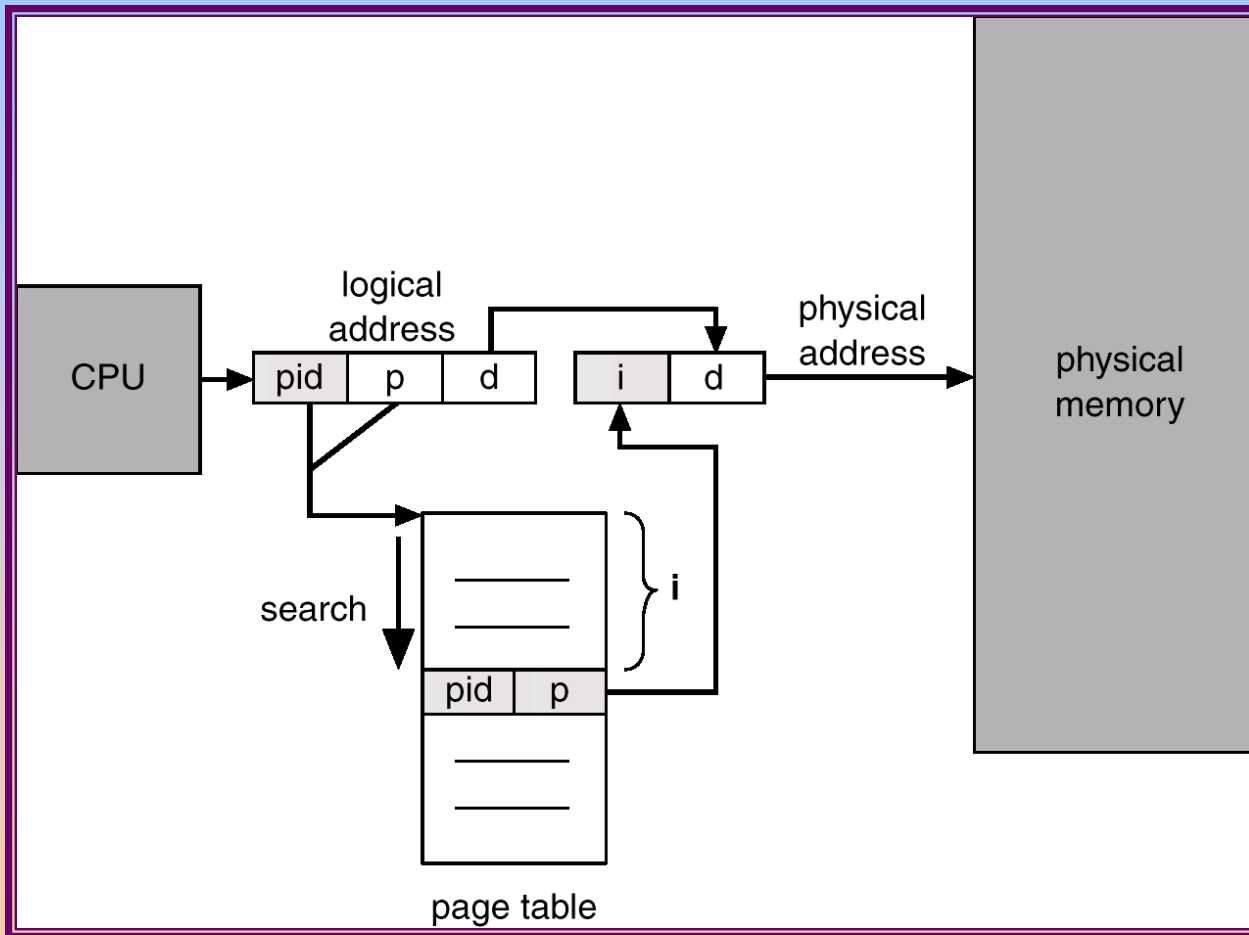
# Inverted Page Table

- One entry for each real page of memory.
- Entry consists of the virtual address of the page stored in that real memory location, with information about the process that owns that page.
- Decreases memory needed to store each page table, but increases time needed to search the table when a page reference occurs.
- Use hash table to limit the search to one — or at most a few — page-table entries.





# Inverted Page Table Architecture





# Shared Pages

## ■ Shared code

- One copy of read-only (reentrant) code shared among processes (i.e., text editors, compilers, window systems).
- Shared code must appear in same location in the logical address space of all processes.

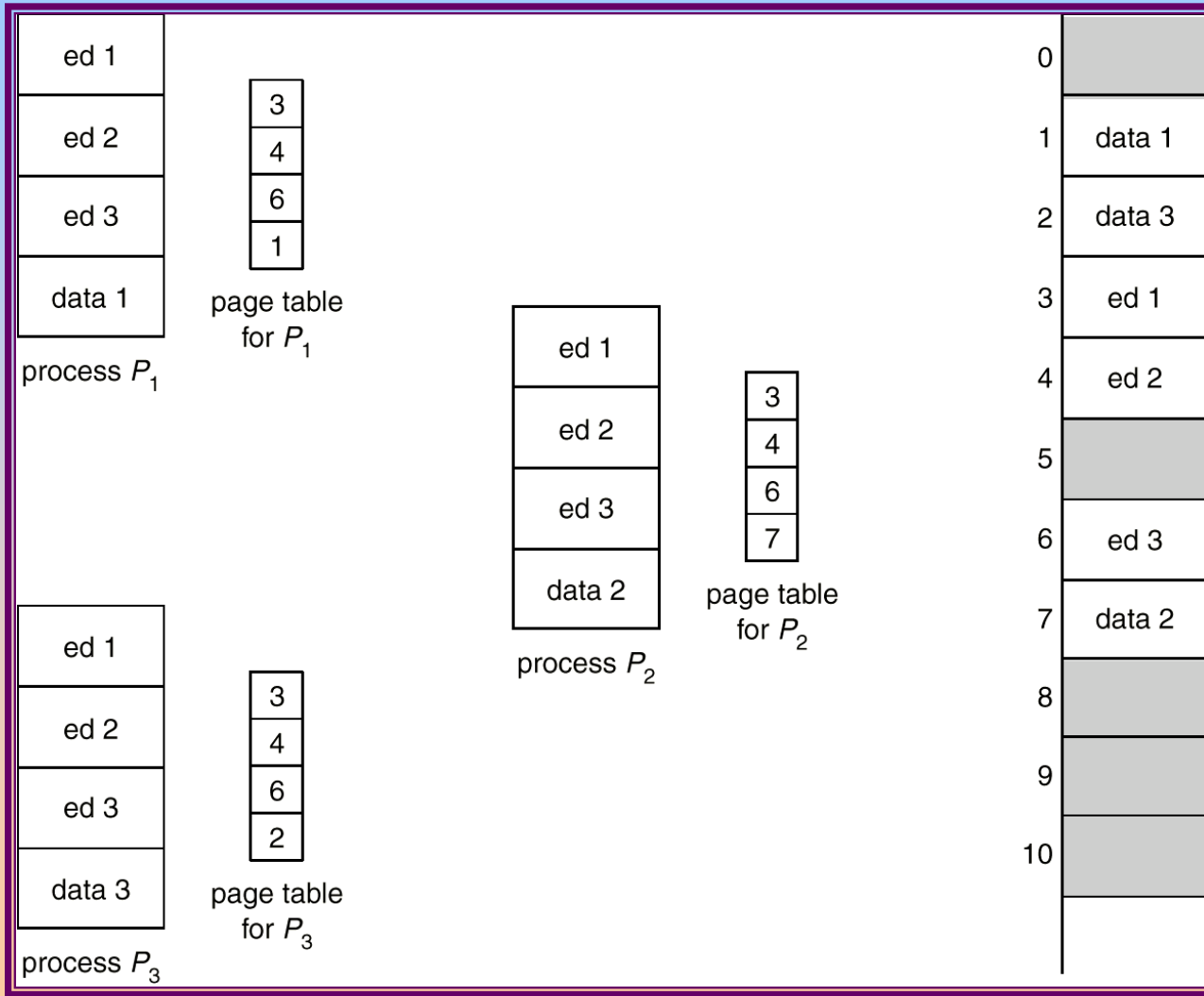
## ■ Private code and data

- Each process keeps a separate copy of the code and data.
- The pages for the private code and data can appear anywhere in the logical address space.





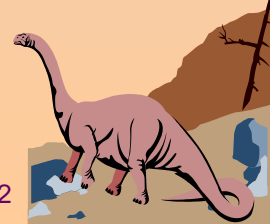
# Shared Pages Example



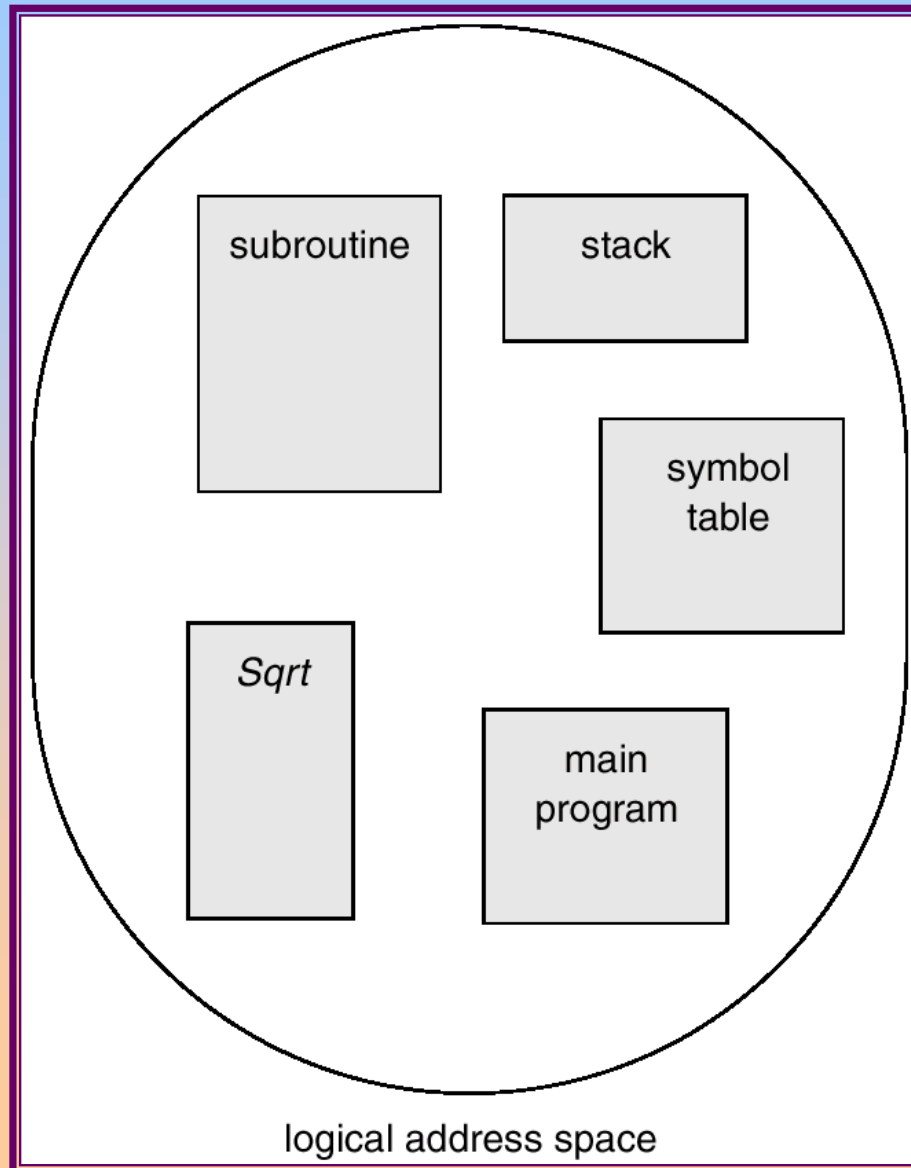


# Segmentation

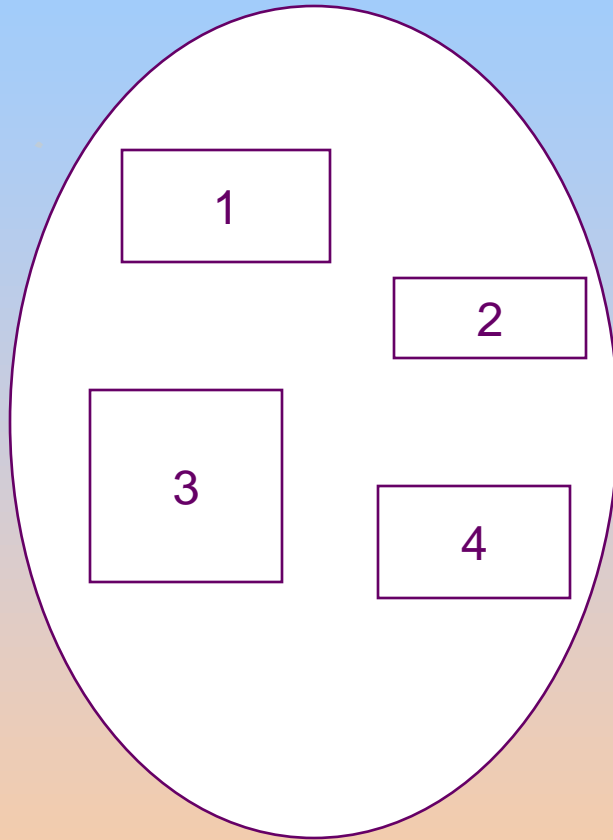
- Memory-management scheme that supports user view of memory.
- A program is a collection of segments. A segment is a logical unit such as:
  - main program,
  - procedure,
  - function,
  - method,
  - object,
  - local variables, global variables,
  - common block,
  - stack,
  - symbol table, arrays



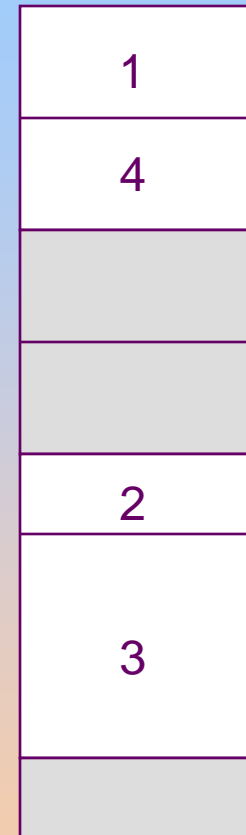
# User's View of a Program



# Logical View of Segmentation



user space



physical memory space



# Segmentation Architecture

- Logical address consists of a two tuple:  
     $\langle \text{segment-number}, \text{offset} \rangle$ ,
- *Segment table* – maps two-dimensional physical addresses; each table entry has:
  - ☞ *base* – contains the starting physical address where the segments reside in memory.
  - ☞ *limit* – specifies the length of the segment.
- *Segment-table base register (STBR)* points to the segment table's location in memory.
- *Segment-table length register (STLR)* indicates number of segments used by a program;  
    segment number  $s$  is legal if  $s < \text{STLR}$ .



# Segmentation Architecture (Cont.)

- Relocation.
  - ☞ dynamic
  - ☞ by segment table
  
- Sharing.
  - ☞ shared segments
  - ☞ same segment number
  
- Allocation.
  - ☞ first fit/best fit
  - ☞ external fragmentation



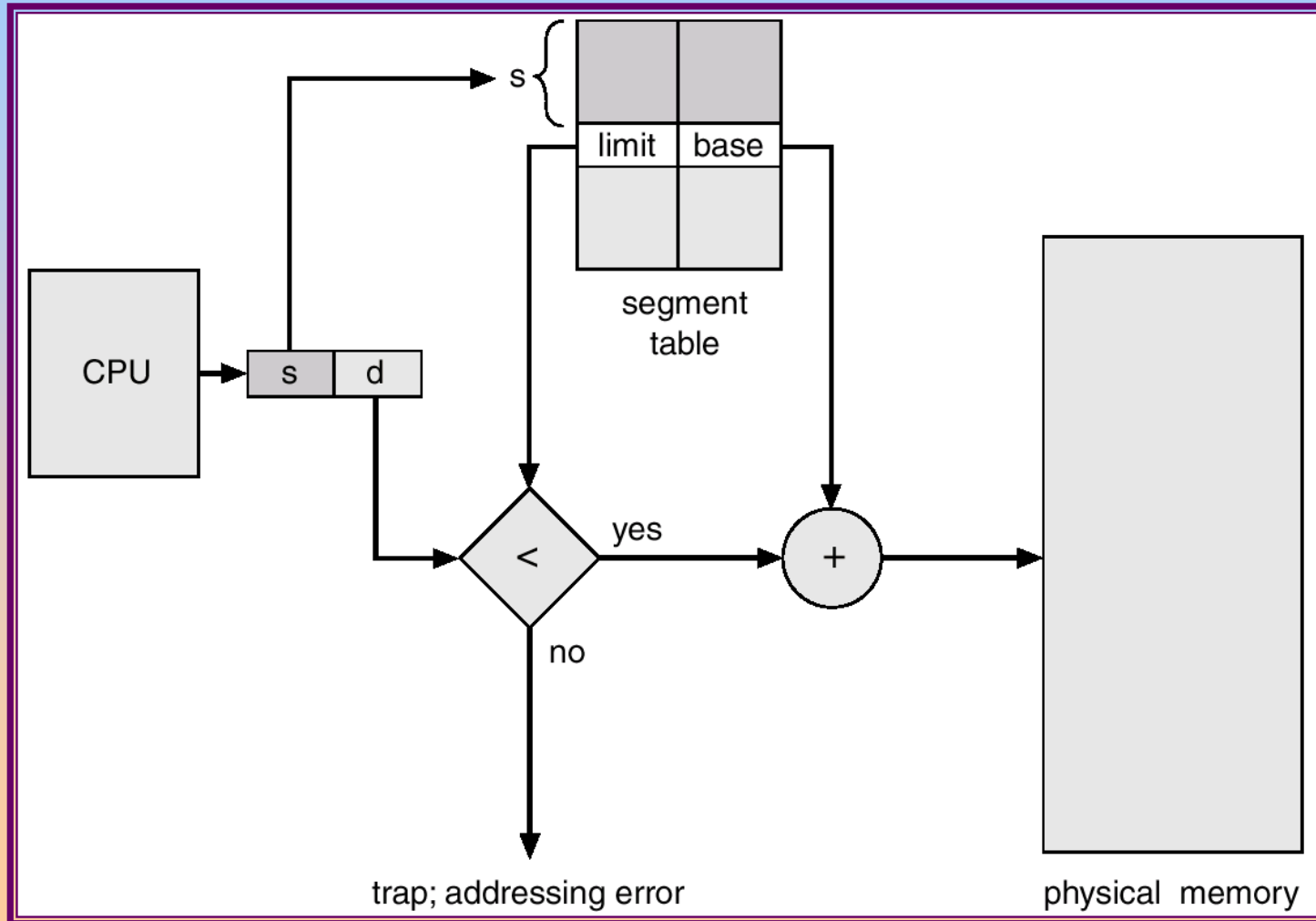


# Segmentation Architecture (Cont.)

- Protection. With each entry in segment table associate:
  - ☞ validation bit = 0  $\Rightarrow$  illegal segment
  - ☞ read/write/execute privileges
- Protection bits associated with segments; code sharing occurs at segment level.
- Since segments vary in length, memory allocation is a dynamic storage-allocation problem.
- A segmentation example is shown in the following diagram

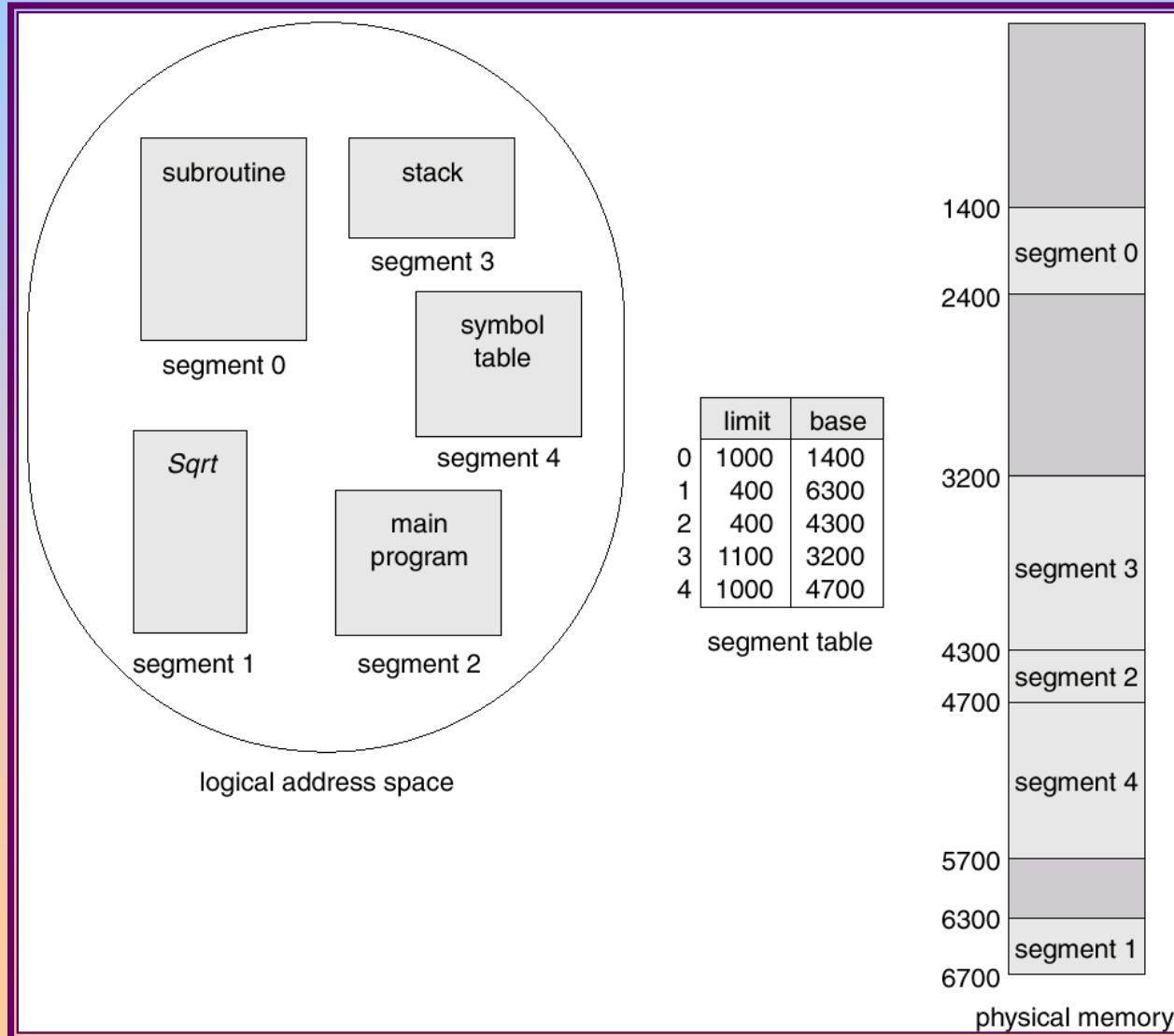


# Segmentation Hardware

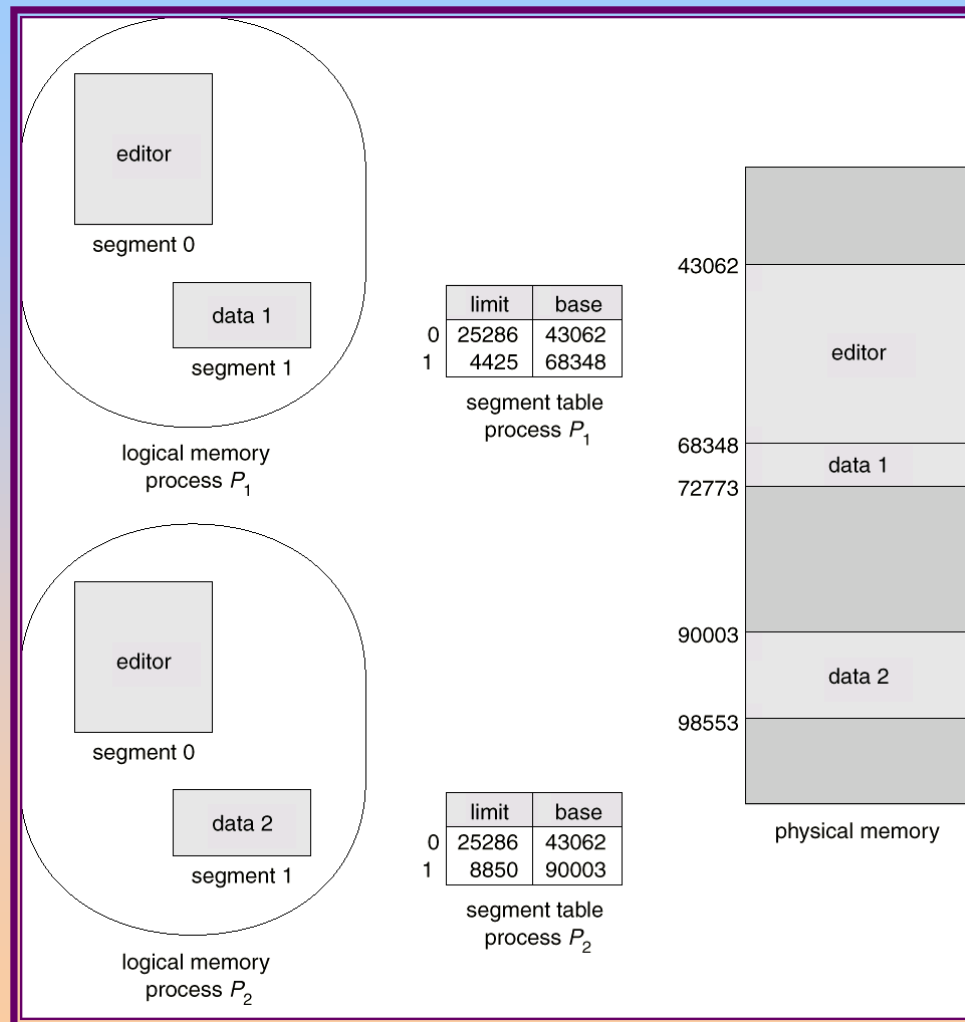




# Example of Segmentation



# Sharing of Segments



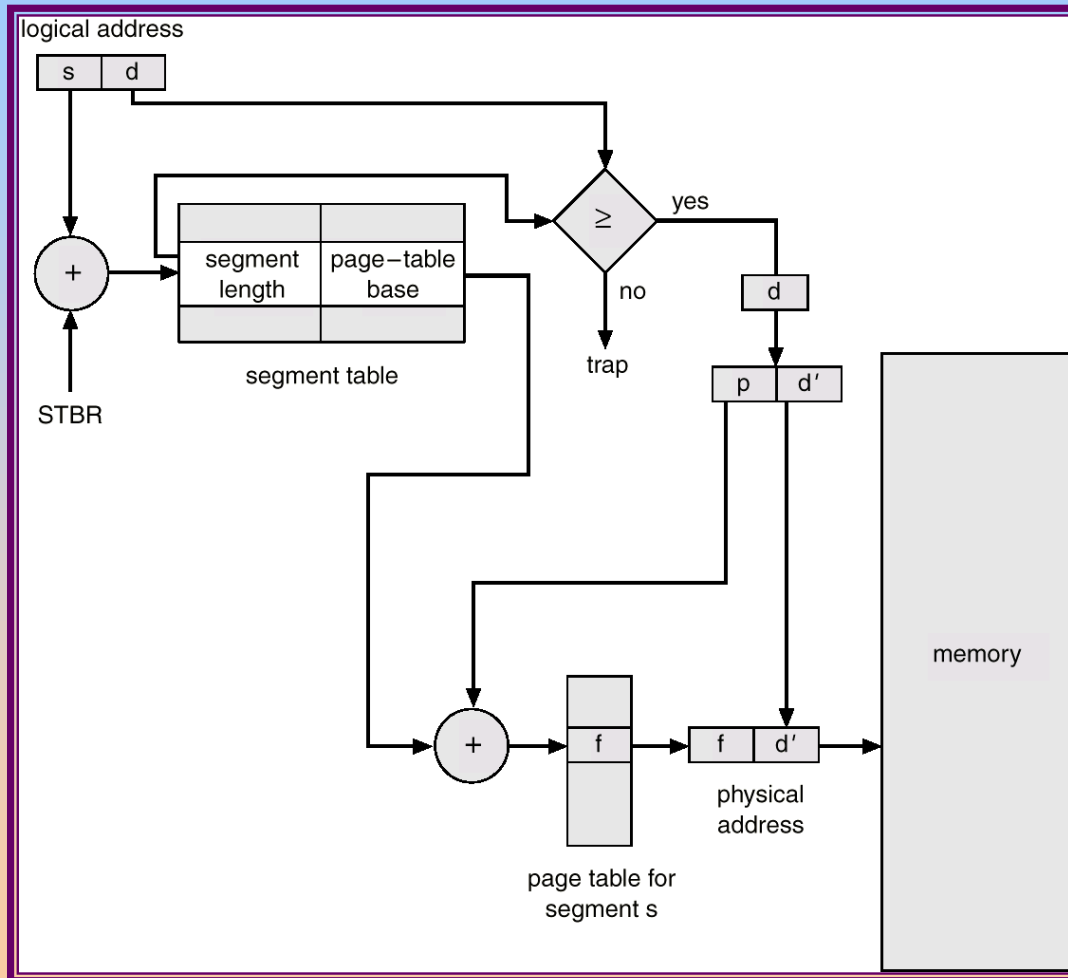


# Segmentation with Paging – MULTICS

- The MULTICS system solved problems of external fragmentation and lengthy search times by paging the segments.
- Solution differs from pure segmentation in that the segment-table entry contains not the base address of the segment, but rather the base address of a *page table* for this segment.



# MULTICS Address Translation Scheme





# Segmentation with Paging – Intel 386

- As shown in the following diagram, the Intel 386 uses segmentation with paging for memory management with a two-level paging scheme.



# Intel 30386 Address Translation

