



# **SNS COLLEGE OF TECHNOLOGY**

**Coimbatore-35**  
**An Autonomous Institution**



Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A+' Grade  
Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai

## **DEPARTMENT OF MECHANICAL ENGINEERING**

### **19MET303 – DESIGN OF Transmission System**

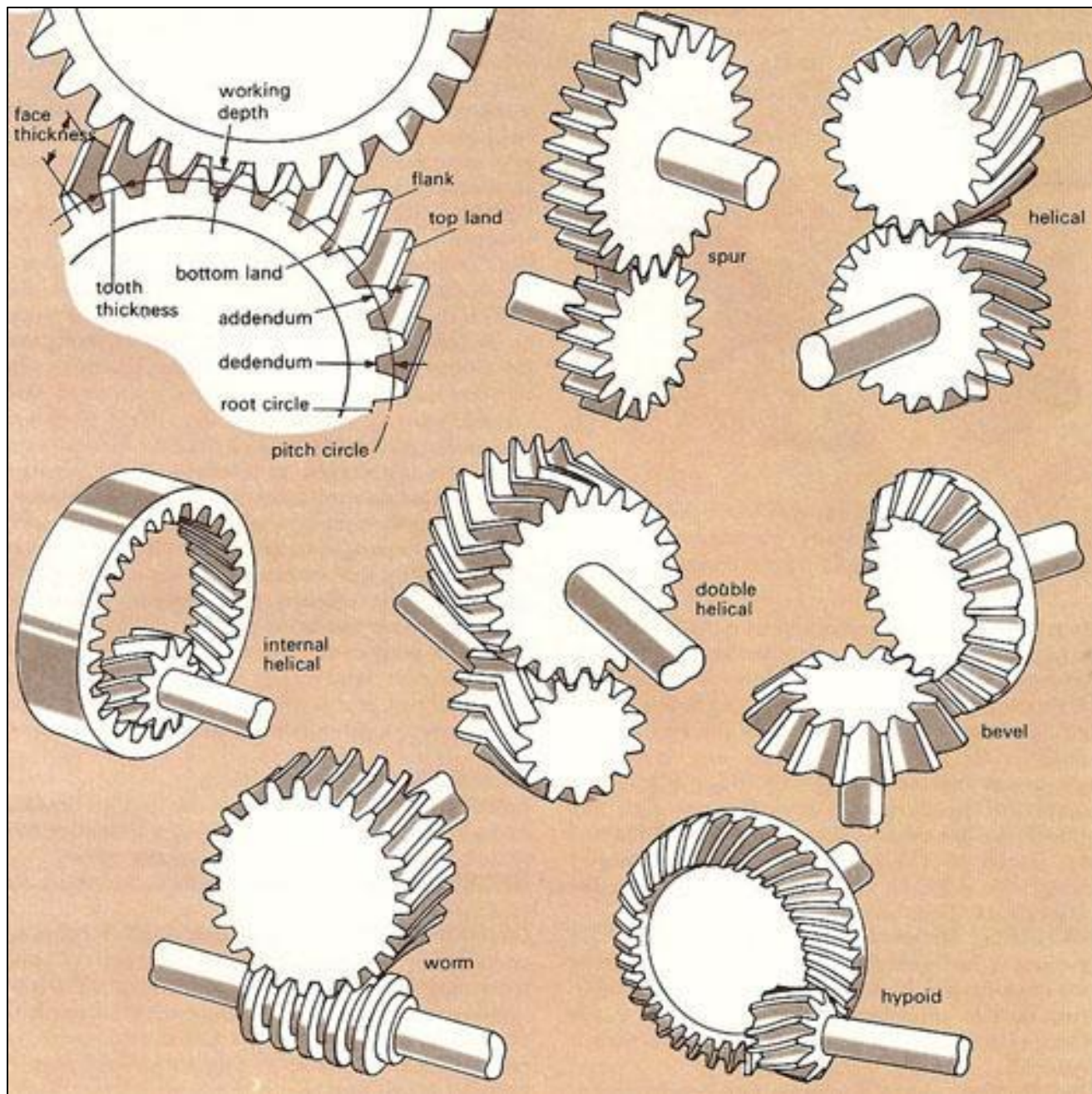
III YEAR VISEM

UNIT 3-Worm and Bevel Gear

**TOPIC:Worm Gear**



# GEAR TYPES





# WORM GEAR

1. Used to connect non parallel and non intersecting shafts – **hypoid, crossed helical gears**
2. Quiet and noiseless operation – more teeth are in contact
3. High speed ratios for overall small dimensions- Gear ratio of 100 can be possible. For spur gears 3 stages are required and gear ratio is less than 7 and space requirement is higher.
4. Irreversibility or **self locking capability** – ability to make movement in only one direction
5. Motion cannot be transmitted from wheel to worm
6. Mainly used in load **hoisting applications**
7. When the lead angle of the worm is greater than the friction angle – drive is reversible



# WORM GEARS - INTRODUCTION

Worm gears resemble screws, and can be used to drive gear wheels (spur gears or helical gears).

They allow two non-intersecting shafts at right angles to mesh with each other.

Worm drives provide a large reduction in speed. For one rotation of the worm gear, the gear wheel moves by a distance of one tooth.

They are typically used in gearboxes, where large reductions in speed, for example 300:1, are required.



Spur gears



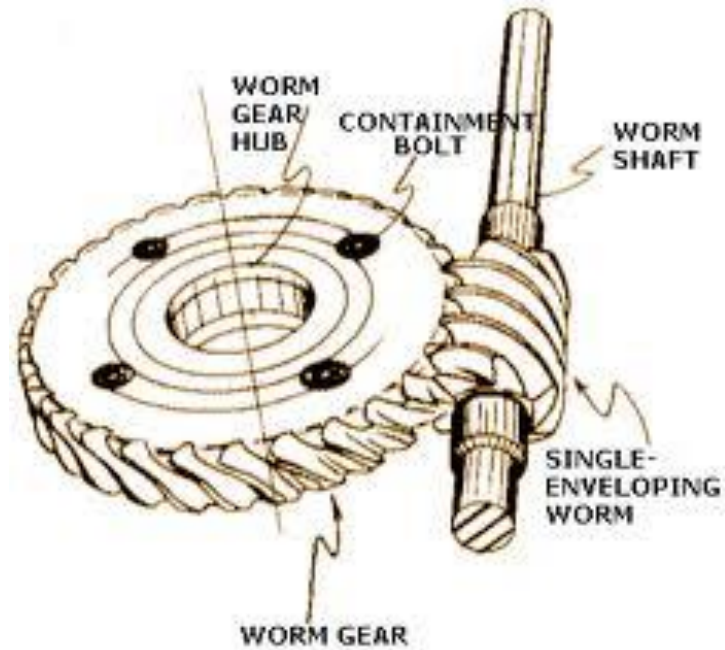
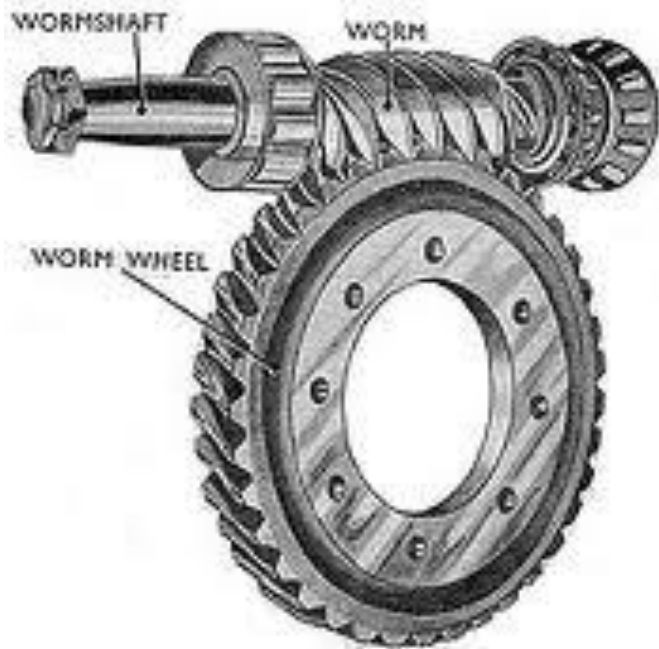
Helical gears

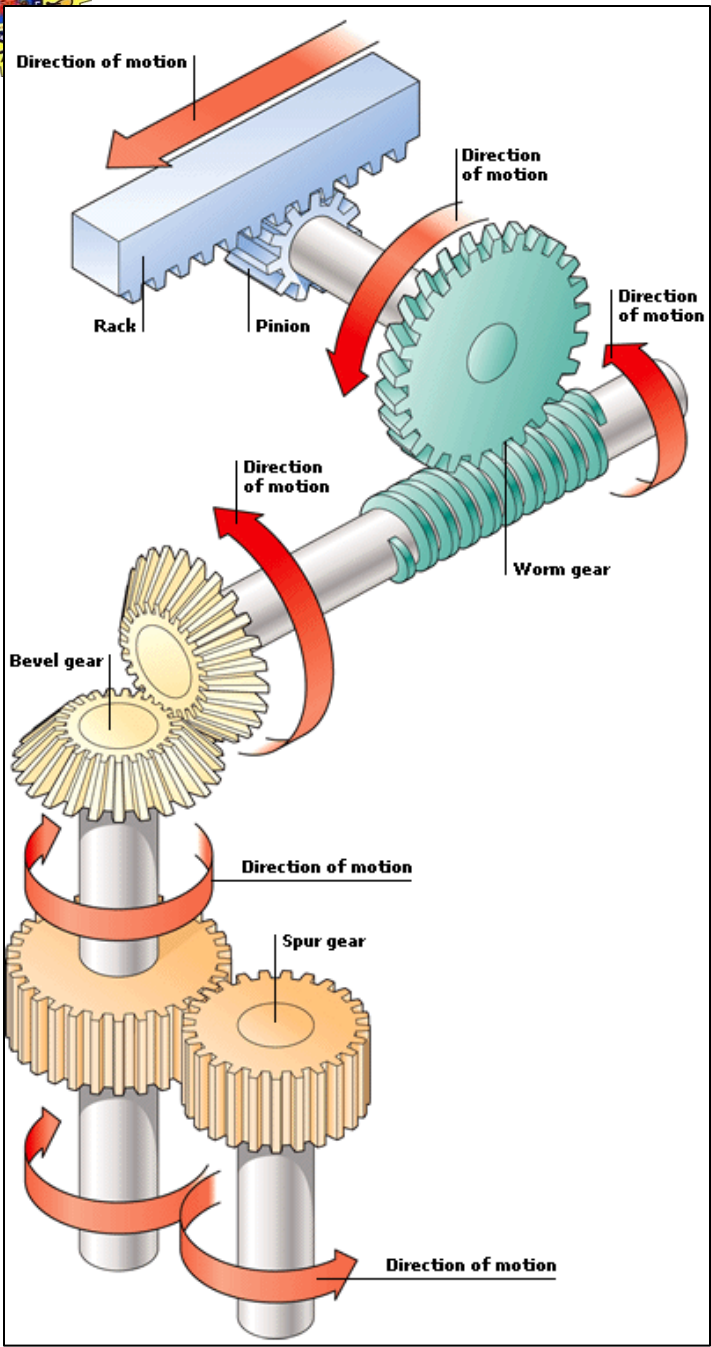






# WORM GEAR





1. Gears are pairs of wheels with teeth around their edges that mesh and turn together.
2. Gears are machines because they multiply turning force or speed.
3. If one gear wheel drives another that has more teeth, the wheel with more teeth turns more slowly but with greater force than the other.
4. If a gear wheel drives another with fewer teeth, the wheel with fewer teeth turns with less force but faster.



# WORM GEAR







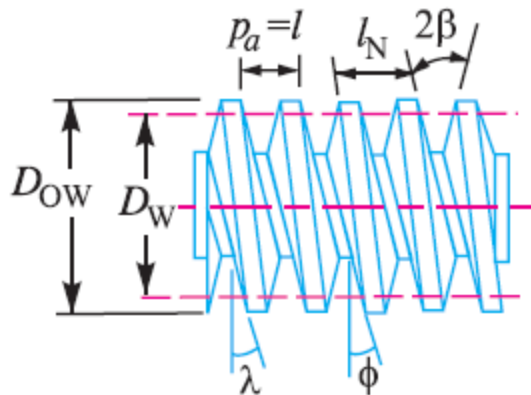
# WORM GEAR

## TYPES OF WORM GEAR

### CYLINDRICAL OR STRAIGHT WORM GEAR :

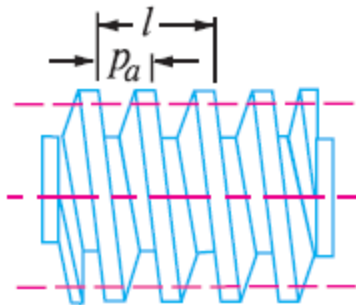
The shape of the thread is in involute helicoids of pressure angle  $14\frac{1}{2}^\circ$  for single and double threaded worms and  $20^\circ$  for triple and quadruple threaded worms. The worm threads are cut by a straight sided milling cutter having its diameter not less than the outside diameter of worm or greater than 1.25 times the outside diameter of worm.

### CONE OR DOUBLE ENVELOPING WORM

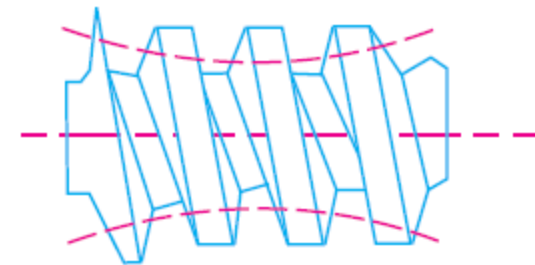


Single threaded.

(a) Cylindrical or straight worm.



Double threaded.



(b) Cone or double enveloping worm.



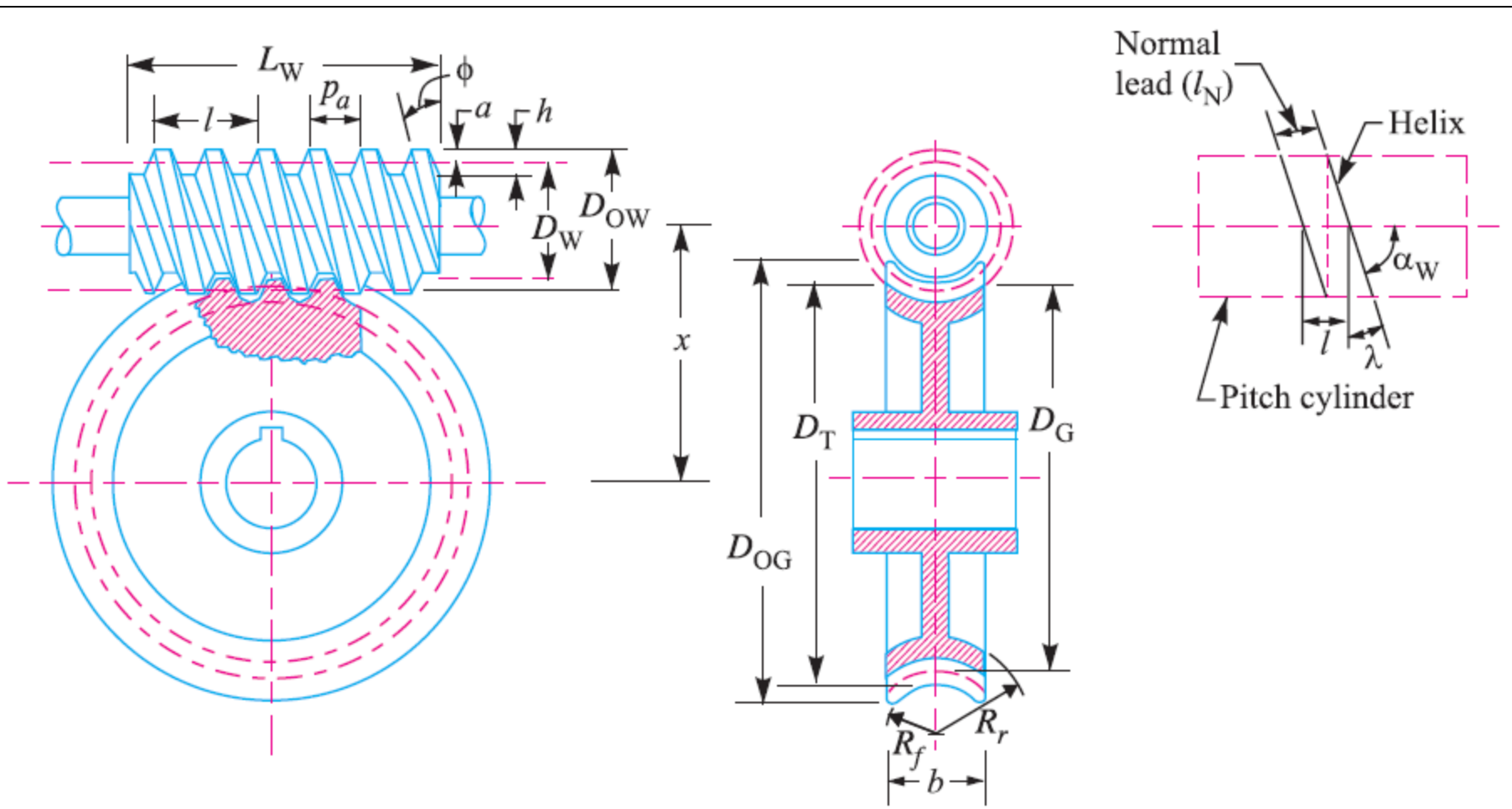


# WORM GEAR





# WORM GEAR - NOMENCLATURE





# WORM and WORM WHEEL

**LEAD ANGLE ( $\gamma$ )** – ANGLE BETWEEN TANGENT TO THE PITCH HELIX AND THE PLANE OF ROTATION

**AXIAL PITCH** – DISTANCE BETWEEN A POINT ON A WORM THREAD AND A CORRESPONDING POINT ON THE ADJACENT THREAD MEASURED PARALLEL TO THE AXIS

**LEAD** = NUMBER OF THREADS IN THE WORM \* PITCH

**GEAR RATIO** = NO OF TEETH ON THE WORM WHEEL/ NO OF STARTS OF TH WORM





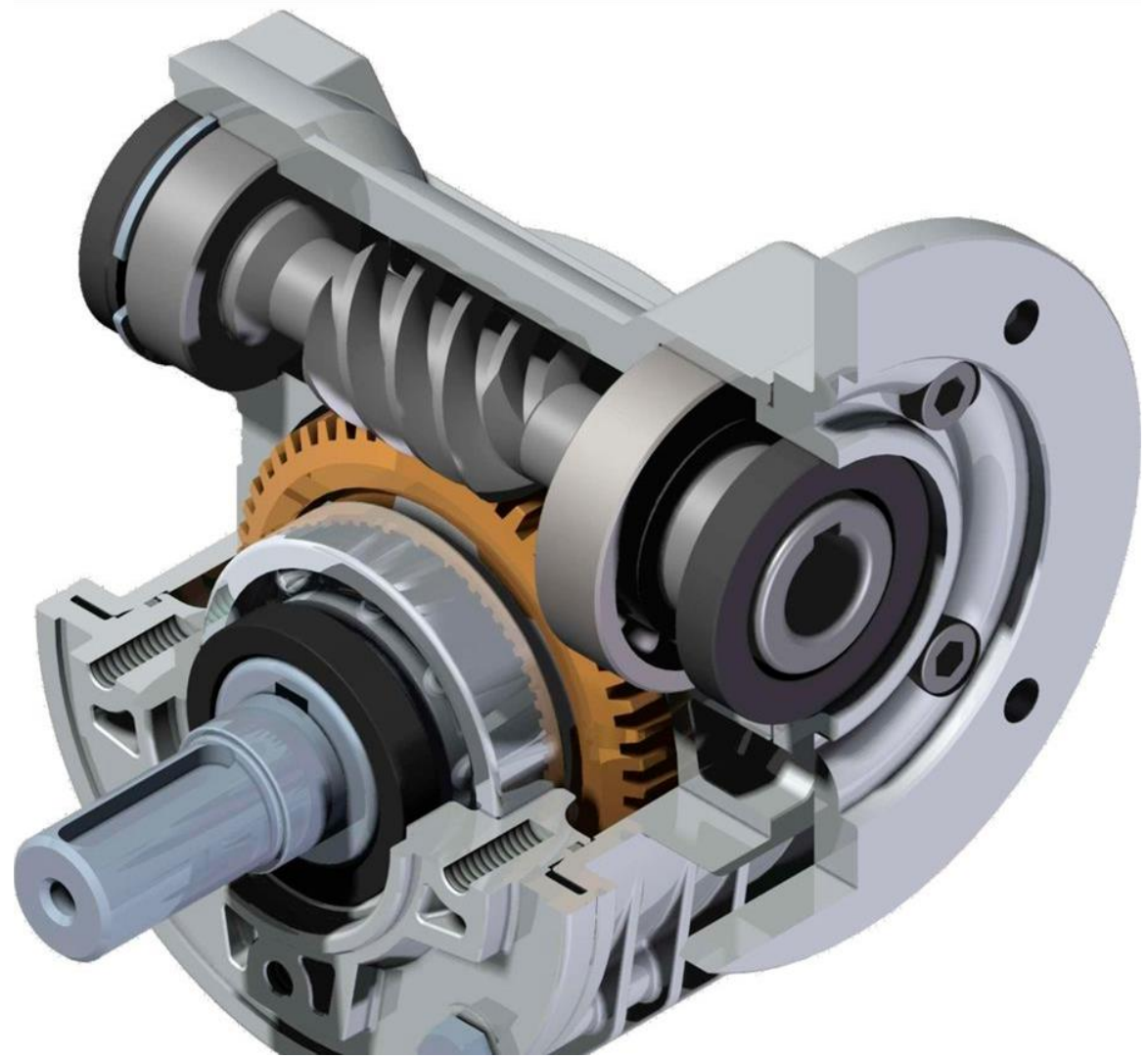
# WORM and WORM WHEEL





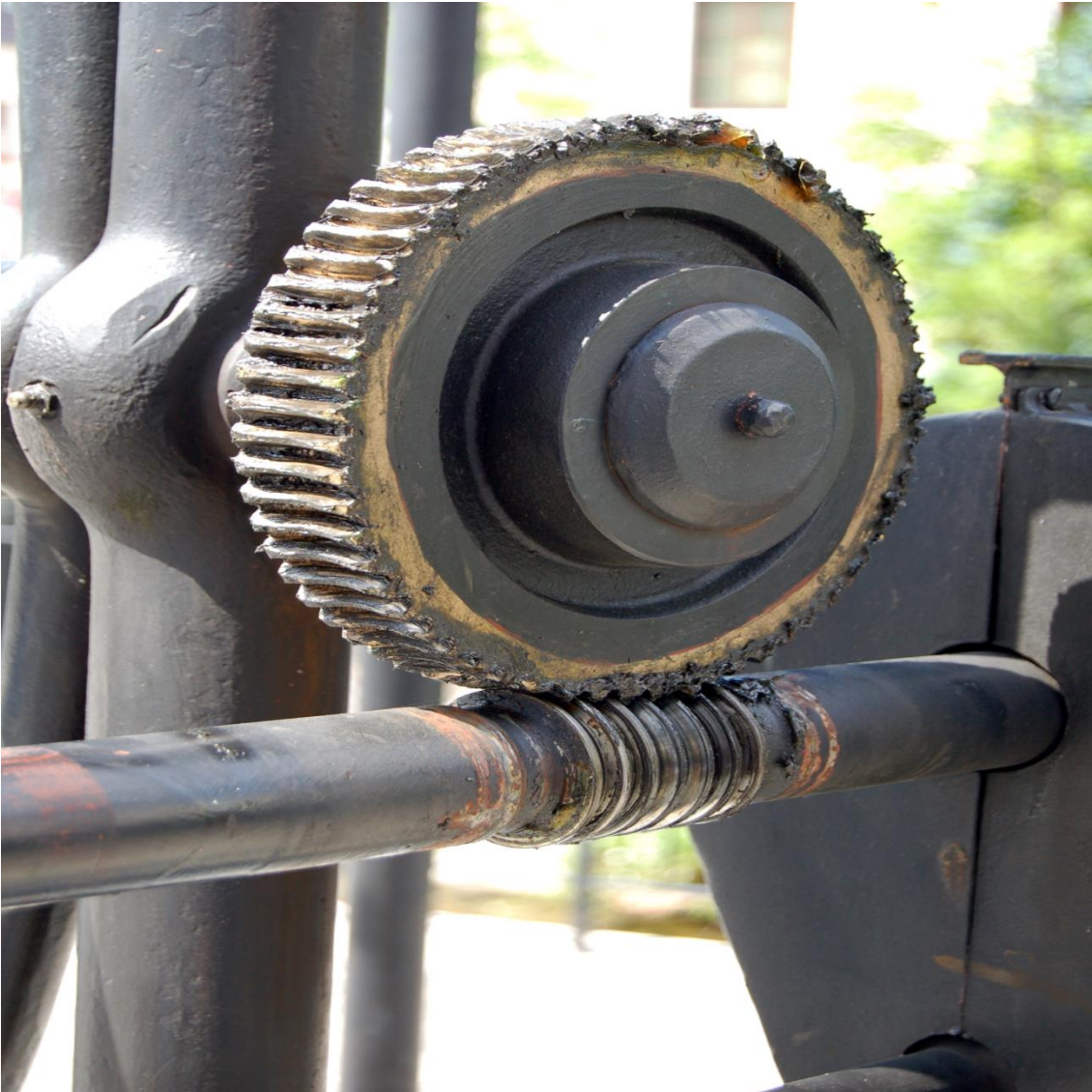


# WORM GEAR BOX

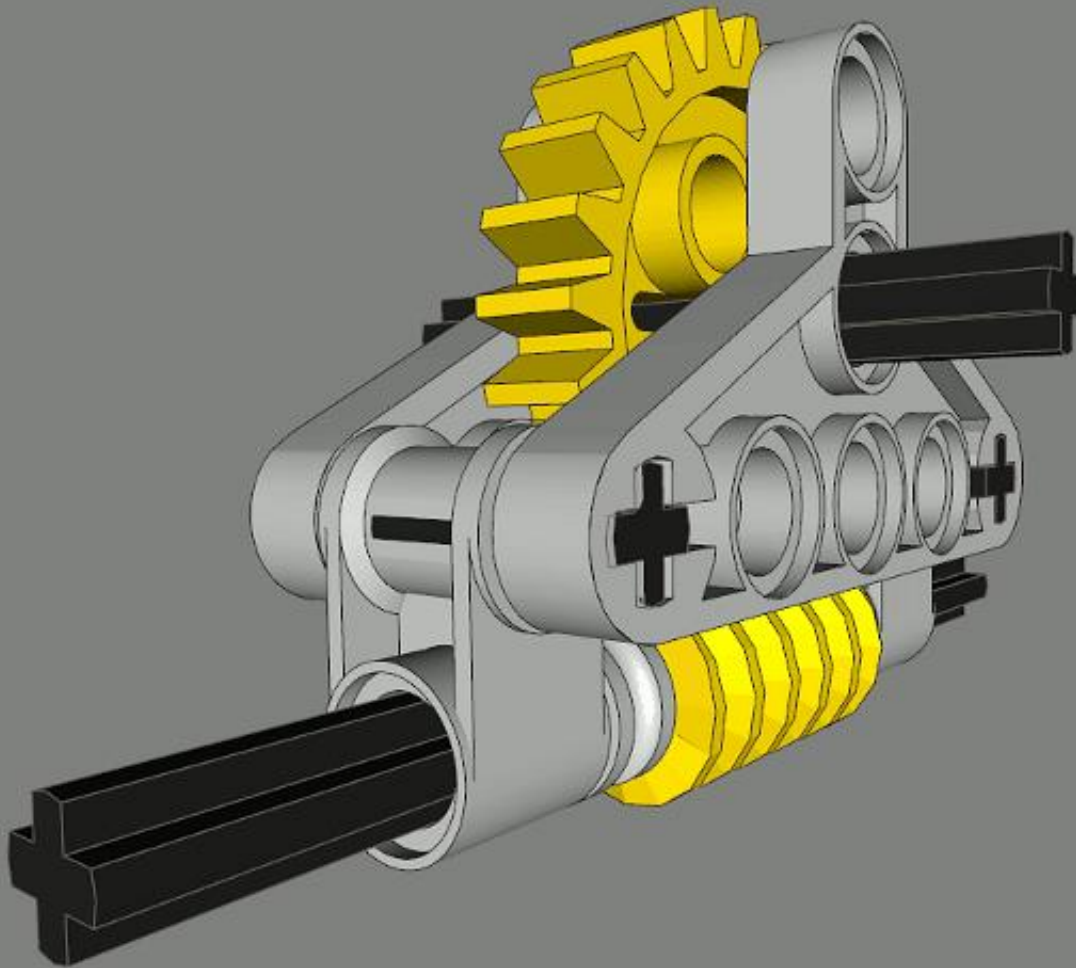




# WORM and WORM WHEEL



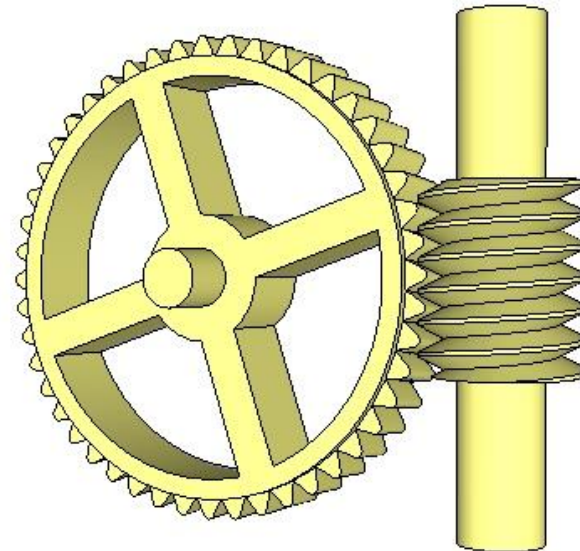
# WORM GEAR







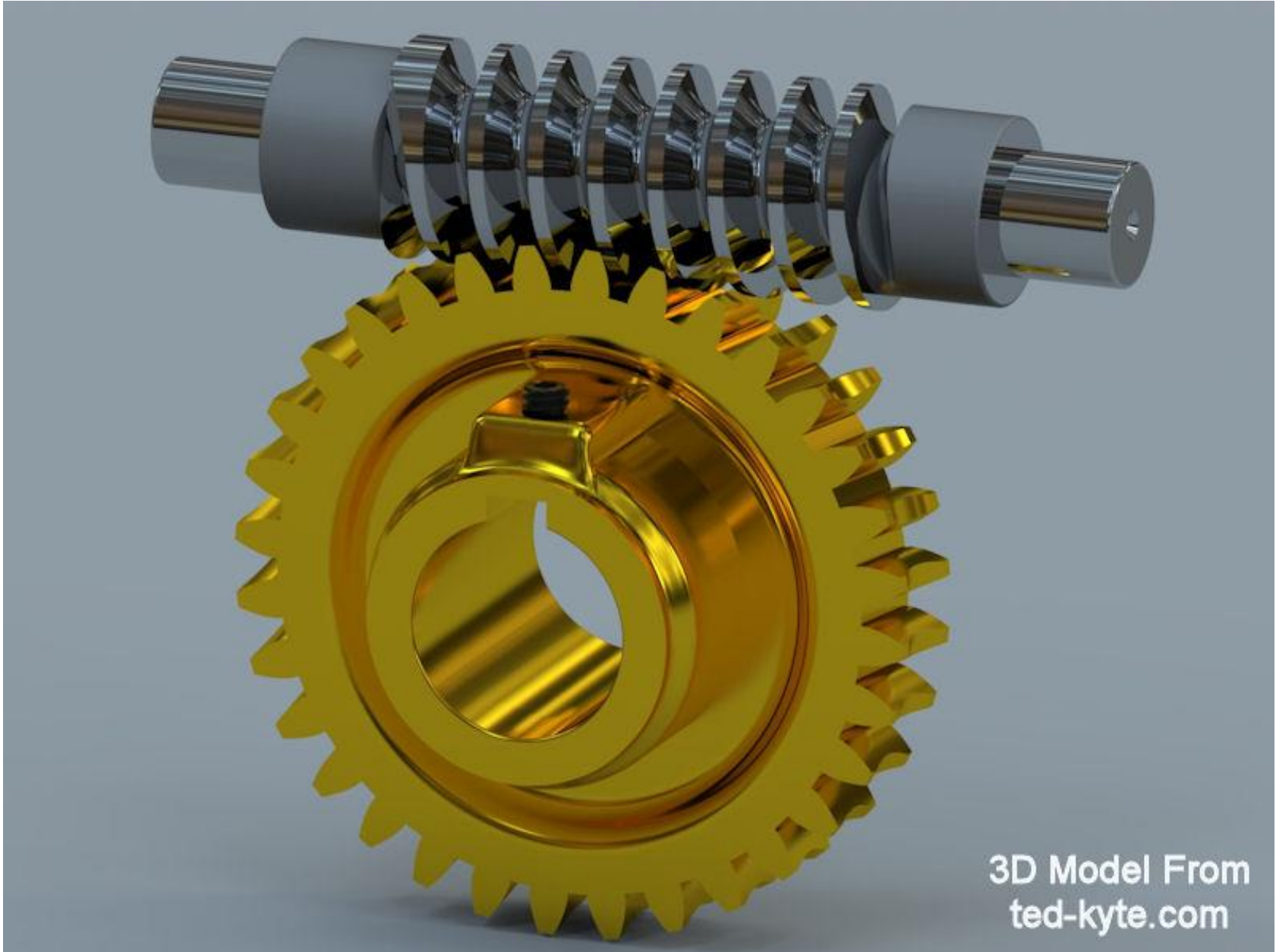
# WORM and WORM WHEEL







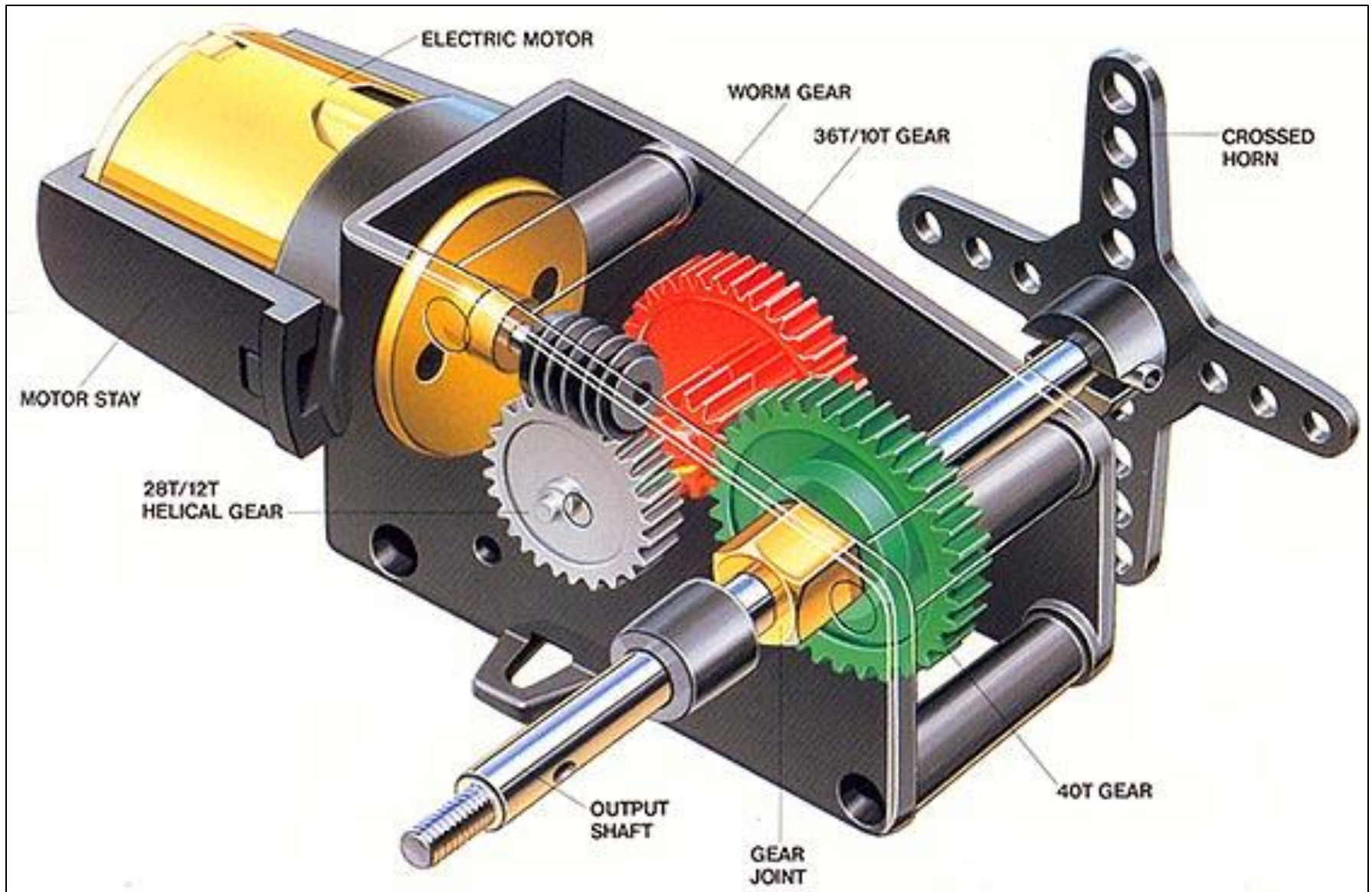
# WORM and WORM WHEEL



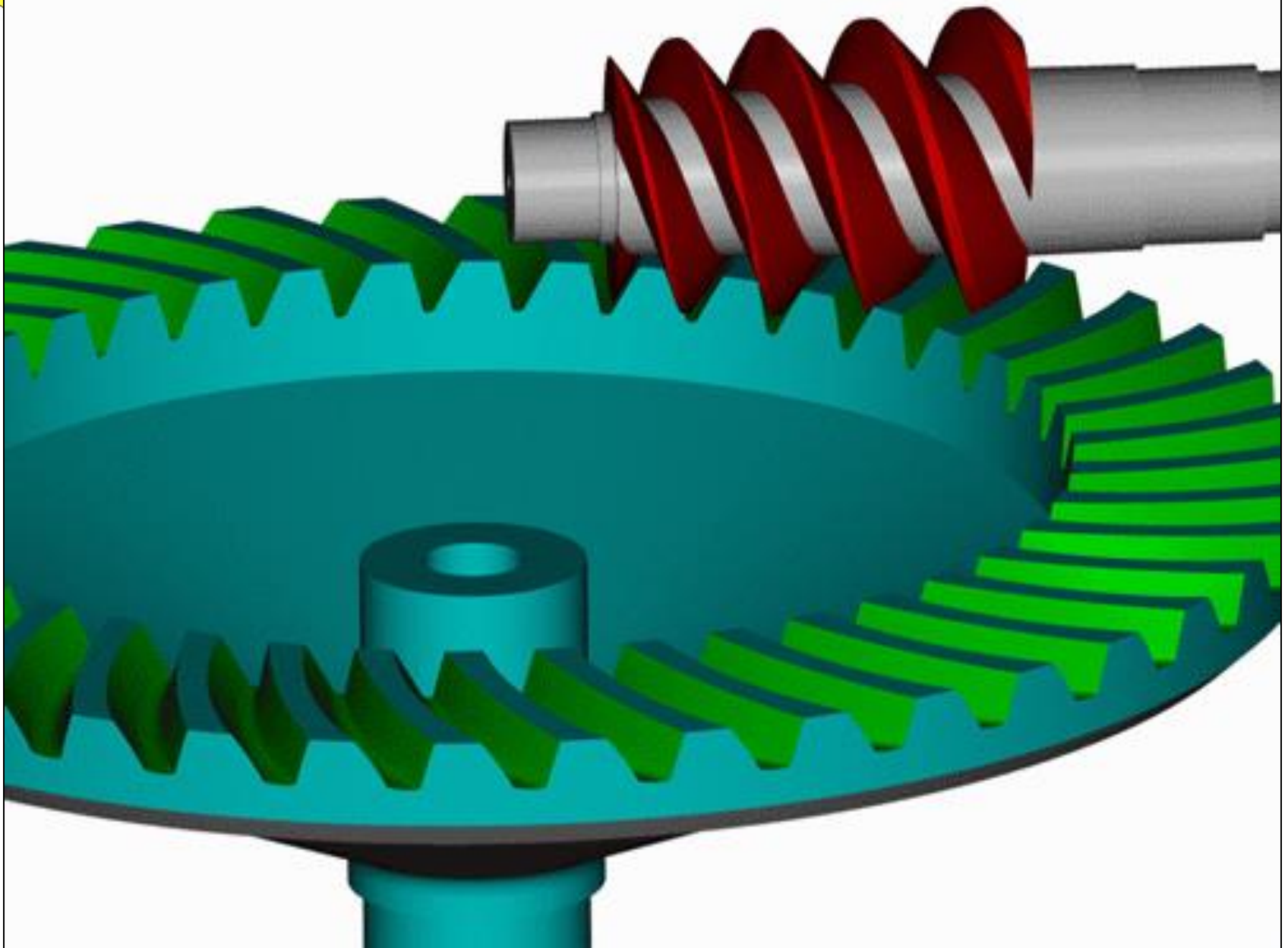
3D Model From  
[ted-kyte.com](http://ted-kyte.com)



# WORM GEAR BOX



# SPIRAL BEVEL GEAR







# BEVEL AND WORM GEAR

