#### Image Segmentation Using Region Growing and Shrinking







### Contents

- Brief introduction to Image segmentation
- Types of Image segmentation
- Region growing and Shrinking (split /merge) method
- Applications of Image segmentation
- Results

### Introduction

The shape of an object can be described in terms of:

- Its boundary requires image edge detection
- The region it occupies requires image segmentation in homogeneous regions, Image regions generally have homogeneous characteristics (e.g. intensity, texture)

- The goal of Image Segmentation is to find regions that represent objects or meaningful parts of objects. Major problems of image segmentation are result of noise in the image.
- An image domain X must be segmented in N different regions R(1),...,R(N)
- The segmentation rule is a logical predicate of the form P(R)

Image segmentation partitions the set X into the subsets R(i), i=1,...,N having the following properties
X = i=1,..N U R(i)
R(i) ∩ R(j) = 0 for I ≠ j
P(R(i)) = TRUE for i = 1,2,...,N
P(R(i) U R(j)) = FALSE for i ≠ j

- The segmentation result is a logical predicate of the form P(R,x,t)
- x is a feature vector associated with an image pixel
- t is a set of parameters (usually thresholds) A simple segmentation rule has the form:

 $\mathsf{P}(\mathsf{R}):\mathsf{I}(\mathsf{r},\mathsf{c})<\mathsf{T}$ 

- In the case of color images the feature vector x can be three RGB image components {IR(r,c),IG(r,c),IB(r,c)
- A simple segmentation rule may have the form:

$$\begin{split} \mathsf{P}(\mathsf{R}, \mathsf{x}, \mathsf{t}) &: (\mathsf{IR}(\mathsf{r}, \mathsf{c}) < \mathsf{T}(\mathsf{R})) \&\& & (\mathsf{IG}(\mathsf{r}, \mathsf{c}) < \mathsf{T}(\mathsf{G})) \&\& \\ & (\mathsf{IB}(\mathsf{r}, \mathsf{c}) < \mathsf{T}(\mathsf{B})) \end{split}$$

- A region is called connected if : .....
- A pixel (x,y) is said to be adjacent to the pixel (a,b) if it belongs to its immediate neighbourhood
- The 4-neighbourhood of a pixel (x,y) is the set that includes its .....
- The 8-neighbourhood of (x,y) is a superset of the 4-neighbourhood and contains the .....

### Types

- By Histogram Thresholding
- By Region Growing and Shrinking
- By Clustering in the color space

# **Region Growing**

- A simple approach to image segmentation is to start from some pixels (seeds) representing distinct image regions and to grow them, until they cover the entire image
- For region growing we need a rule describing a growth mechanism and a rule checking the homogeneity of the regions after each growth step

# **Region Growing – cont.d**

- The growth mechanism at each stage k and for each region Ri(k), i = 1,...,N, we check if there are unclassified pixels in the 8neighbourhood of each pixel of the region border
- Before assigning such a pixel x to a region Ri(k),we check if the region homogeneity: P(Ri(k) U {x}) = TRUE, is valid

# **Region Growing – cont.d**

 The arithmetic mean m and standard deviation sd of a class Ri having n pixels: M = (1/n)(r,c)€R(i) ∑ I(r,c) s.d = Square root((1/n)(r,c)€R(i) ∑[I(r,c)-M]<sup>2</sup>) Can be used to decide if the merging of the two regions R1,R2 is allowed, if [M1 – M2] < (k)s.d(i), i = 1, 2, two regions are merged</li>

# **Region Growing – cont.d**

 Homogeneity test: if the pixel intensity is close to the region mean value

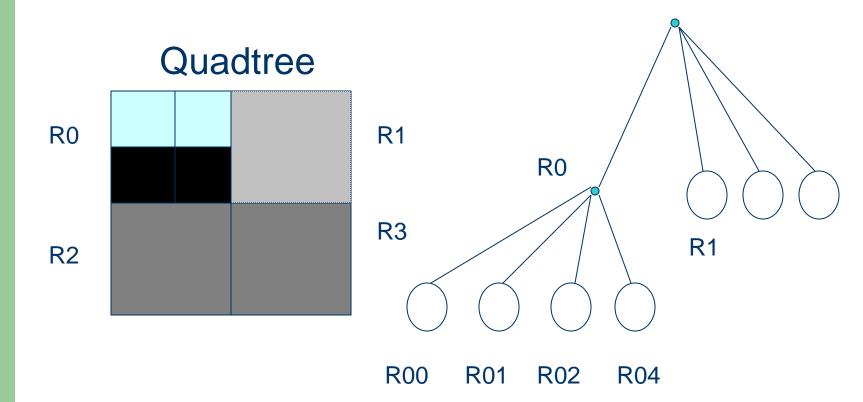
|I(r,c) - M(i)| <= T(i)

 Threshold Ti varies depending on the region Rn and the intensity of the pixel I(r,c). It can be chosen this way:

$$T(i) = \{ 1 - [s.d(i)/M(i)] \} T$$

- The opposite approach to region growing is region shrinking (splitting).
- It is a top-down approach and it starts with the assumption that the entire image is homogeneous
- If this is not true, the image is split into four sub images
- This splitting procedure is repeated recursively until we split the image into homogeneous regions

- If the original image is square N x N, having dimensions that are powers of 2(N = 2n):
- All regions produced but the splitting algorithm are squares having dimensions M x M, where M is a power of 2 as well (M=2m,M<= n).</li>
- Since the procedure is recursive, it produces an image representation that can be described by a tree whose nodes have four sons each
- Such a tree is called a Quadtree.



- Splitting techniques disadvantage, they create regions that may be adjacent and homogeneous, but not merged.
- Split and Merge method It is an iterative algorithm that includes both splitting and merging at each iteration:

- If a region R is inhomogeneous (P(R)= False) then is split into four sub regions
- If two adjacent regions Ri,Rj are homogeneous (P(Ri U Rj) = TRUE), they are merged
- The algorithm stops when no further splitting or merging is possible

• The split and merge algorithm produces more compact regions than the pure splitting algorithm

# **Applications**

- 3D Imaging : A basic task in 3-D image processing is the segmentation of an image which classifies voxels/pixels into objects or groups. 3-D image segmentation makes it possible to create 3-D rendering for multiple objects and perform quantitative analysis for the size, density and other parameters of detected objects.
- Several applications in the field of Medicine like magnetic resonance imaging (MRI).

### **Results – Region grow**





# **Results – Region Split**



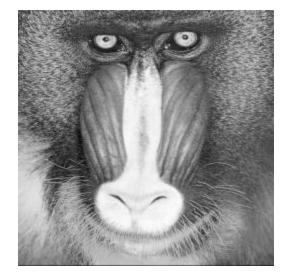


#### **Results – Region Split and Merge**



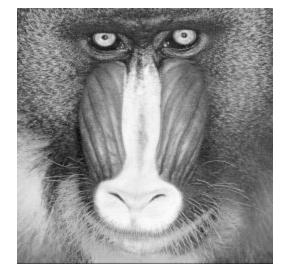


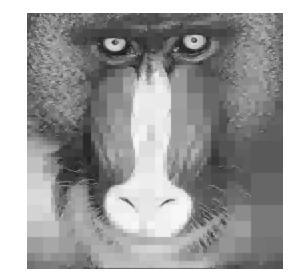
#### **Results – Region growing**



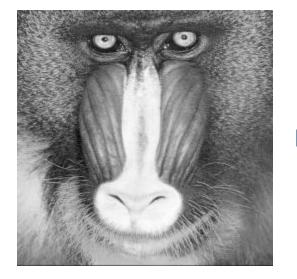


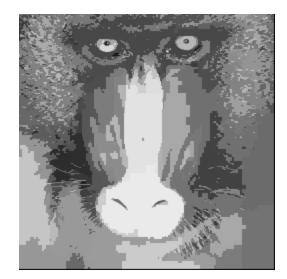
### **Results – Region Split**





#### **Results – Region Split and Merge**





### References

- "Digital Image Processing" Algorithms and Application, A multimedia approach.
  Prof. Ioannis Pitas
- Computer Vision and Image Processing: A Practical Approach
- CVIP Tools software

#### **Thank You**

