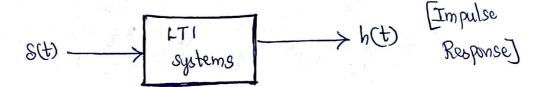


## UNIT- III

0

## TIME SYSTEMS LTI - CONTINUOUS

Impulse Response :-



Impulse response is the olp generated by the system when unit impulse is applied at the Input.

consolution Integral: - Output of an LTI CT System:

yt)= 7[xt)] can be supresented interms of impulses as xt) = \$ x(t) &(t-t) dt

$$y(t) = T \left[ \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau \right]$$

$$= \int_{0}^{\infty} x(t) + \int_{0}^{\infty} (t-t) dt$$
Relation between
$$= \int_{0}^{\infty} x(t) + \int_{0}^{\infty} (t-t) dt$$
If and of the
$$y(t) = \int_{0}^{\infty} x(t) + \int_{0}^{\infty} dt$$
System

Relation between af the System

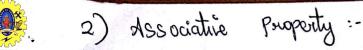


By using convolution Integral obtain the response of the system two unit step input signals: het) = & e-te/ u(t) , x(t) = u(t) y (t) = 5 x(t) h (t-t) dt = S u(T) R/L e(t-T) R/L u(t-T) dT = t R/L e-(t-t) R/L dt  $= \frac{t}{s} R/L e^{-(t-\tau)R/L} d\tau$ = R/L S [ e-tR/L TR/L dT] = R/L e-tR/L 5 e TR/L dt = R/L e-t R/L [eTR/L] = R/e + R/L [e+R/L - /R/L y (t) = 1 - e + R/L Proporties of completion Integral:

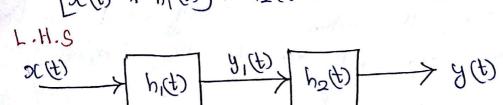
) commutative property: y(t) = x(t) \* h(t) = h(t) \* x(t)

=  $\int_{0}^{\infty} x(t) h(t-t) d\tau = \int_{0}^{\infty} h(\tau) x(t-\tau) d\tau$ 

R.Sathish kumar, AP/ECE Scanned by CamScanner



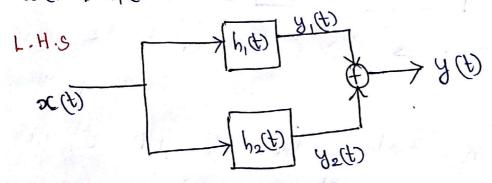
(2) ASSOCIANCE 1 supports  $\left[x(t) * h_1(t)\right] * h_2(t) = x(t) * \left[h_1(t) * h_2(t)\right]$ 



R.H.S

$$\frac{x \oplus}{} \rightarrow \left[ h' \oplus * h^{5} \oplus \right] \rightarrow \partial \oplus$$

3) Distributive property:- $x(t) * h_1(t) + x(t) * h_2(t) = x(t) * [h_1(t) + h_2(t)]$ 



R.H.S

$$x(t) \rightarrow h_1(t) + h_2(t) \rightarrow y(t)$$

condition for an LTI system to be causal:

condition for an LTI system to be stable:

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