# SNS COLLEGE OF TECHNOLOGY



Coimbatore-35
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# DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

# 19EET301 / POWER ELECTRONICS AND DRIVES V SEM EEE

**Unit 2: DC CONVERTERS** 

TOPIC - Single Phase Controlled Converters (1)

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### Phase-Control Converters



Three-Phase

# Single-Phase

Half & Semi conv

Full converter

Half & Semi conv

Full converter

Dual converter Dual converter

#### Semiconverter

.. is a one-quadrant converter and it has one polarity

#### Full converter

..is a two-quadrant converter and the polarity of its output can be either positive or negative.

#### However

the output current of full converter has one polarity only

#### Dual converter

...can operate in four quadrants; both the output voltage and current can be either positive or

negative



## **CLASSIFICATION OF RECTIFIERS**

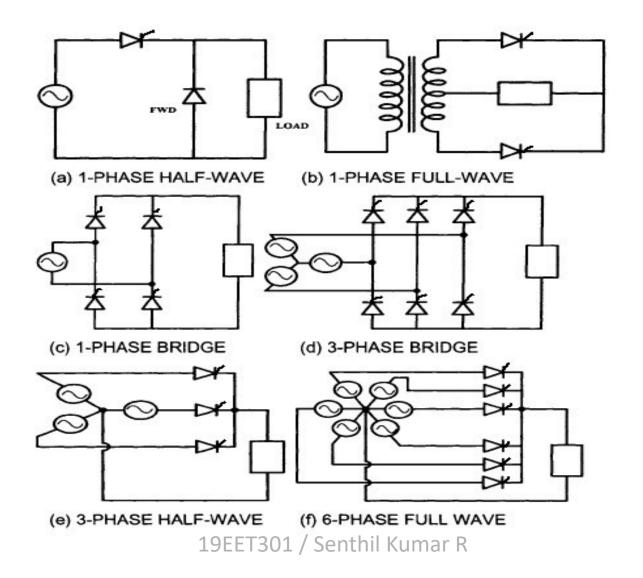


- BASED ON INPUT SUPPLY
  - SINGLE PHASE
  - THREE PHASE
- BASED ON QUADRANT OPERATION
  - 1 QUADRANT
  - 2 QUADRANT
  - 4 QUADRANT
- BASED ON NO. OF PULSES
  - ONE PULSE
  - TWO PULSES
  - THREE PULSES
  - SIX PULSES



#### PHASE CONTROLLED RECTIFIERS









#### APPLICATIONS OF RECTIFIERS

- DC MOTOR SPEED CONTROL
- DC SUPPLY FOR INVERTERS
- ELECTROCHEMICAL PROCESSES
- DC TRACTION
- HVDC TRANSMISSION



#### **TOPICS**

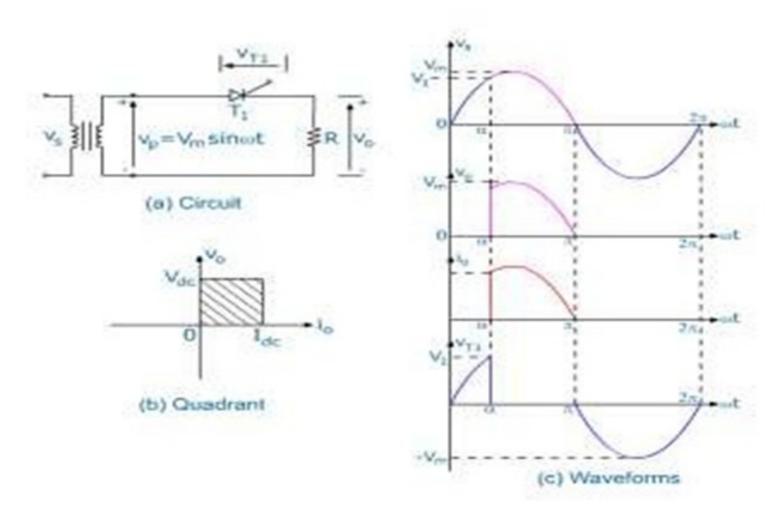


- 1. Single Phase Half Wave Converter R Load
- 2. Single Phase Half Wave Converter RL Load
- 3. Single Phase Half Wave Converter RL Load with FD
- 4. Single Phase Semi Converter
- 5. Single Phase Full Converter



# 1. SINGLE PHASE HWC WITH R LOAD









#### FIRING ANGLE α

 Angle between the zero crossing of the input voltage and the instant thyristor is fired.



# **AVERAGE OUTPUT VOLTAGE- R LOAD**



The average output voltage V<sub>dc</sub> is given by

$$V_{dc} = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_{m} \sin \omega t d(\omega t)$$

$$V_{dc} = \frac{V_{m}}{2\pi} [-\cos \omega t]_{\alpha}^{\pi}$$

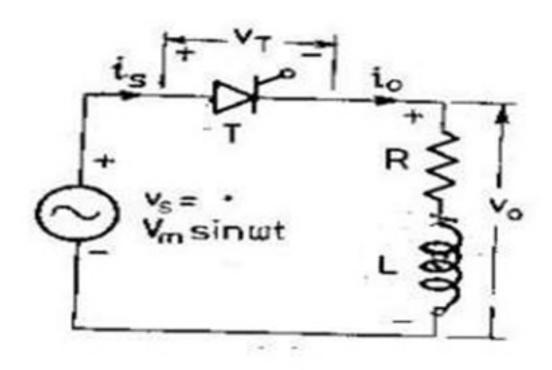
$$V_{dc} = \frac{V_{m}}{2\pi} (1 + \cos \alpha)$$

The output voltage  $\mathbf{V}_{dc}$  can be varied from  $\mathbf{V}_{m}/\pi$  to zero as the firing angle  $\alpha$  varies from zero to  $\pi$ .



## 2. SINGLE PHASE HWC WITH RL LOAD

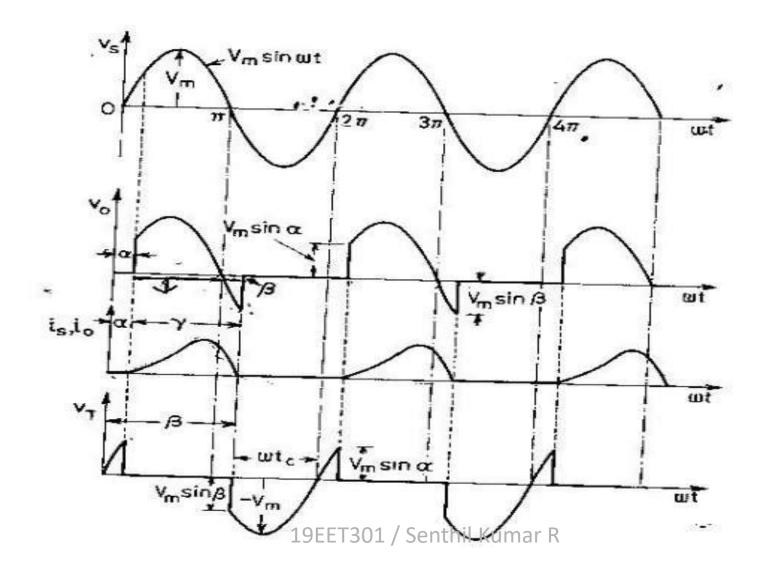






# 2. SINGLE PHASE HWC WITH RL LOAD

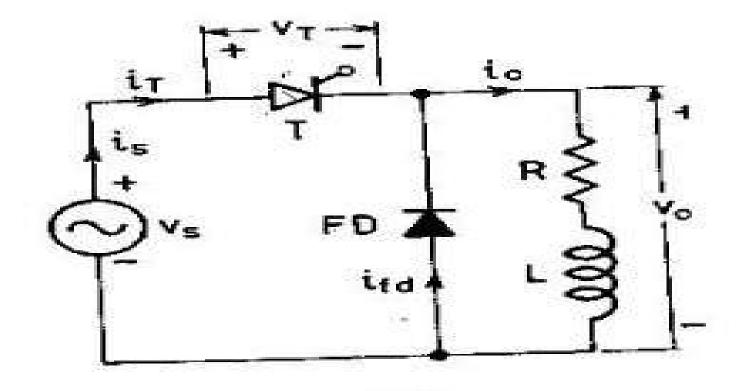








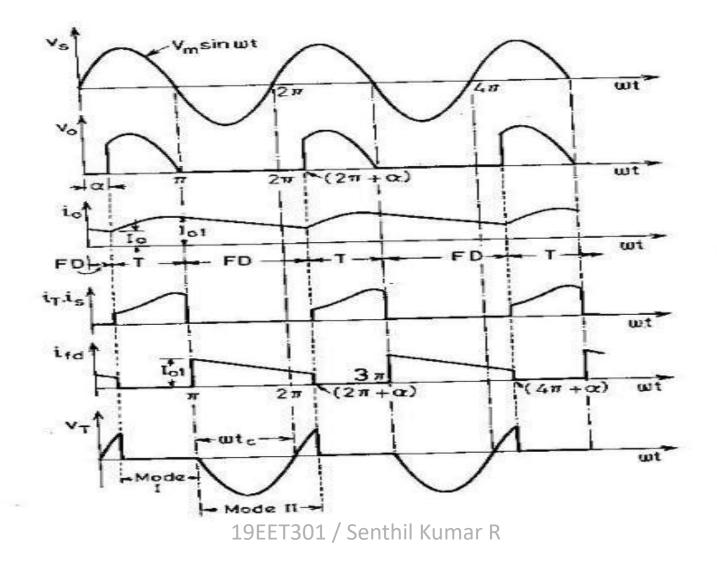














## **ADVANTAGES OF USING FREEWHEELING DIODE**



- Input power factor is improved
- Load current waveform is improved and load performance is better.

#### Main functions of **fwd**

- It prevents the reversal of load voltage except for a small voltage drop
- It transfers the load current away from the main rectifier thereby allowing all the thyristors to regain their blocking states

# Average Output Voltage

$$V_{dc} = \frac{1}{2\pi} \int_{0}^{\pi} V_{m} \sin \frac{t d(\omega t) = V_{m}}{\cos^{2}} (1 + \omega)$$

Maximum
Output Voltage

$$V_{dm} = \frac{V_{m}}{\pi}$$

Normalizing
Output Voltage

$$V_n = \frac{V_{dc}}{V_{dm}} = 0.5(1 + \cos\alpha)$$

RMS Output Voltage

$$V_{rms} = \sqrt{\frac{1}{2\pi}} \int_{0}^{\pi} V_{m}^{2} \sin^{2} t d(\omega t) \frac{V_{m}}{\pi} \sqrt{\frac{1}{\pi} \left(\pi - \alpha + \frac{\sin 2\alpha}{2}\right)}$$







