



HAND COMPLEX CMC, MCP, IPS – Type, Motion & Mechanism

PRESENTOR: ARCHANA K Assistant professor SNS COLLEGE OF PHYSIOTHERAPY





INTRODUCTION

- The hand consists of 5 digits: 4 fingers and a thumb
- Each digit has a carpometacarpal (CMC) joint and a metacarpophalangeal (MCP) joint.
- Between the phalanges of the fingers, a proximal (PIP) and a distal (DIP) interphalangeal joint are found;

the thumb has only one interphalangeal (IP) joint.





Figure 9–14 Bony anatomy of the thumb and fingers. DIP, distal interphalangeal; PIP, proximal interphalangeal; MP, metacarpophalangeal; CMC, carpometacarpal; M, metacarpal; P1, proximal phalanx; P2, middle phalanx; P3, distal phalanx.









- There are 19 bones and 19 joints distal to the carpals that make up the hand complex.
- ✓ 5 metacarpal bones
- ✓ 5 proximal phalanges
- ✓4 middle phalanges and
- ✓5 distal phalanges





<u>CARPOMETACARPAL</u> (CMC) <u>JOINTS</u>

There are two CMC joints of the hand

- \checkmark one for the thumb and
- \checkmark second for the other four digits of the hand.
- *Each digital ray articulates proximally with a particular carpal bone to form the carpometacarpal (CMC) joint.
- It is at the CMC joint that the thumb separates from the rest of the hand.



CMC JOINT OF THE THUMB (Digit1)



- The CMC joint of the thumb is formed by the trapezium and the base of the first metacarpal
- The surfaces of both of these bones are both convex and concave and form a **saddle joint**.
- It has a lax capsule and wide range of motion (ROM), which allows opposition movement in prehension activities.







- >Abduction (palmar abduction) & Adduction
- Flexion & Extension (radial abduction)
- >Opposition- net effect at this joint is a circumduction motion known as opposition. The thumb, together with the first metacarpal, is opposed to the other fingers.
- >Reposition (the reverse of opposition)
- ➢Rotation



Fig. 1.47 Movements of the thumb MCP and IP joints. (From Hochschild J. Functional Anatomy for Physical Therapists. Stuttgart: Thieme; 2016.) (a) Abduction and adduction of the thumb. (b) Extension and flexion of the thumb. (c) Opposition of the thumb.















- □ Flexion / Extension:
- ✓ in the **frontal plane**,
- ✓ The surface of the trapezium is convex, and the base of the metacarpal is concave;
- ✓ therefore, its surface slides in the same direction as the angulating bone.
- ✓ The axis for this movement takes a radiopalmar to ulnodorsal course through the trapezium.
- ✓ Occurs around a somewhat **oblique A-P axis**











- □ Abduction / Adduction:
- ✓ In the **sagittal plane**
- The trapezium surface is concave and the metacarpal slides is convex;
- ✓ therefore, the surface of the metacarpal slides in the opposite direction of the physiological motion.
- ✓ around an axis through the base of the 1st metacarpal that takes a radiodorsal to ulnopalmar course and forms a 45° angle to the plane of the extended hand.
- ✓ Occurs around an oblique coronal axis











First Carpometacarpal Joint ROM:

- 1. 42° of abduction and adduction (approx. 35° abduction and approx. 25° adduction)
- 2. 53° of flexion–extension (approx. 25° flexion and approx. 45° extension)
- 3. 10° of rotation





- The supporting structures of the CMC joint of the thumb:
- The joint capsule relatively lax
- The intraarticular beak ligament –It is considered as the primary ligamentous stabilizer of the CMC joint of the thumb
- >2 intermetacarpal ligaments helps tether the bases of the first and second metacarpals, preventing extremes of radial and dorsal displacement of the base of the first metacarpal joint.
- >Radial CMC ligament









The dorsal (posterior) and volar (anterior) oblique CMC ligaments

- A. The pull of the dorsal oblique CMC ligament rotates the metacarpal in the ulnar direction during flexion and abduction.
- B. The pull of the volar oblique CMC ligament rotates the metacarpal radially during extension and adduction.







- Thumb is the first and strongest digit of the hand and has special status.
- The thumb's **opposition position** enables the powerful **closing of the fist** and thus acts **as a grasping tool**
- The thumb contributes significantly to **optimizing gross motor and fine motor grasping functions of the hand**
- The functional significance of the CMC joint of the thumb is that the use of the thumb against a finger occurs in almost all forms of **prehension** (**grasp and dexterity activities**).



- Composed of the articulations between the distal carpal row and the bases of the second through fifth metacarpal joints.
- The joints of digits **2,3, and 4 are plane uniaxial** joints, the joint of digit **5 is biaxial**.







- The 2nd metacarpal articulates primarily with the trapezoid and secondarily with the trapezium and capitate.
- The 3rd metacarpal articulates primarily with the capitate
- The 4th metacarpal articulates with the capitate and hamate
- The 5th metacarpal articulates with the hamate.









- All finger CMC joints are supported by strong transverse and weaker longitudinal ligaments volarly and dorsally.
- The deep transverse metacarpal ligament spans the heads of the second through fourth metacarpals volarly.
- It tethers together the metacarpal heads and effectively prevents the attached metacarpals from any more than minimal abduction at the CMC joints.
- Although it contributes directly to CMC stability





- One attribute of the distal carpals that affects carpometacarpal and hand function is the volar concavity, or proximal transverse (carpal) arch
- Which is formed by the trapezoid, trapezium, capitate and hamate
- The carpal arch persists even when the hand is fully opened
 The ligaments that maintains the arch are the transverse carpal
 ligament and the transversely oriented intercarpal ligaments





- These structures also form the **carpal tunnel**.
- The carpal tunnel contains the median nerve and 9 extrinsic flexor tendons of the fingers and thumb



Figure 9–15 The proximal transverse arch, or carpal arch, forms the tunnel through which the median nerve and long finger flexors travel. The transverse carpal ligament and intercarpal ligaments assist in maintaining this concavity. C, capitate; H, hamate; Tp, trapezium; Tz, trapezoid.



CMC joint mobility:



- Mobility increases from radial to ulnar side.
- The motion in the 2^{nd} CMC joint is immobile
- **3rd CMC joint** is **least mobile**, it is the central pillar of the hand around which the rest of the hand rotates.
- 4th CMC joint is mobile (10° to 15° of dorsovolar movement).
- 5th CMC joint is the most mobile with 25° to 30° of motion.





CMC joint range of motion:

- The 2nd -4th CMC joints are plane synovial joints.
- The 2nd and 3rd CMC joints are immobile -"zero degrees of freedom"
- The 4th CMC joint -flexion/extension.
- The 5th CMC joint is a saddle joint, with two degrees of freedom- flexion/extension, abduction/adduction, and a limited amount of opposition.













- Proximal transverse arch
- Fixed arch
- Formed by concavity of carpal bones
- Maintained by flexor retinaculum.





- Distal transverse arch
- Mobile arch
- Formed by metacarpal heads
- Maintained by deep transverse metacarpal ligament.
- Also called metacarpal arch
- 2nd and 3rd metacarpal are stable, 4th and 5th are mobile.





- Longitudnal transverse arch
- Transverse the digits from proximal to distal.
- Fixed at proximal end and free at distal end.







Figure 9–17 The palmar arch system assists with functional grasp. The proximal transverse arch (A) is fixed, while the distal transverse arch (B) and longitudinal arch (C) are mobile.





Functions of Palmar Arches

- Enable hand to conform the shape of the object.
- Maximizes the amount of surface contact
- Enhances stability
- Increases sensory feedback.





carpal ligament – supports the palmar arch.



Figure 9–18 The opponens digiti minimi is the only muscle that acts exclusively on a carpometacarpal joint. As indicated by its action line, it is effective at flexion of the fifth metacarpal joint and rotation of the metacarpal joint around its long axis. The opponens digiti minimi muscle's attachment to the transverse carpal ligament may also contribute to supporting the proximal palmar arch.







• Articulation: convex metacarpal head proximally

and concave base of the first phalanx distally.

• Condyloid joint- two degrees of freedom:

flexion/extension and abduction/adduction





- The supporting structures of the MCP joints of the fingers are:
- capsule, collateral ligaments, the accessory and glenoid ligaments and the volar (palmar) plates.







- The MCP joint **capsule** is lax in extension.
- Two collateral ligaments- joint stability.
- At the MCP joint, the volar plate- provide stability.



COLLATERAL LIGAMENTS



Radial and Ulnar Collateral ligaments

Collateral ligament proper

Accessory collateral ligament





° CL Proper- Dorsally located.

° Accessory CL- Volarly located.

• MCP joint flexion:

 $_{\circ}$ CL Proper- lengthens, accessory CL – shortens

• MCP Joint extension:

_o The collateral ligament proper is loose ,whereas

the accessory collateral ligament is taut.




- Tension in the collateral ligaments at full MCP joint flexion (the close-packed position for the MCP joint) limits MCP joint abduction/ adduction in full flexion.
- Provides stability throughout the MCP joint
 ROM





Volar Plate or Palmar Plate:

- The volar plate is composed of fibrocartilage.
- The volar plate at each of the MCP joints is a unique structure that increases joint congruence.



- The volar plate at the MCP joint attaches to the base of the proximal phalanx distally.
- The plate blends with MCP joint capsule and then attaches to metacarpal head proximally.



collateral ligament





- Provides stability to the MCP joint by limiting
 hyperextension
- provides indirect support to the longitudinal arch.
- Increases joint congruency.





- In MCP joint flexion, the flexible attachments of the plate allow the plate to slide proximally on the metacarpal head without impeding motion.
- The collateral ligament proper is loose in MCP joint extension, whereas the accessory collateral ligament is taut.
- The reverse occurs in MCP joint flexion.







- The four volar plates and their respective capsules of the MCP joints of the fingers
 blend with and are interconnected superficially
 by the deep transverse metacarpal ligament.
- That tethers together the heads of the metacarpals of the four fingers



Figure 9–20 The deep transverse metacarpal ligament runs transversely across the heads of the four metacarpophalangeal joints of the fingers. The fibers of the transverse metacarpal ligament blend with each metacarpophalangeal joint capsule and with the deeper volar plates. The superficial aspect of the transverse metacarpal ligament at each metatarsal head is grooved (shown on fourth and fifth metacarpophalangeal joints) for the long finger flexors that pass over the transverse metacarpal ligament and through the annular ligaments (shown on second and third metacarpophalangeal joints).





• Sagittal bands:

- Dorsal to the deep transverse metacarpal ligament are sagittal bands on each side of the metacarpal head that connect each volar plate to the extensor digitorum communis tendon and extensor expansion.
- The sagittal bands help stabilize the volar plates over the four metacarpal heads.







Figure 9–21 The connections of the sagittal bands to each side of the volar plate, the collateral ligaments of the metacarpophalangeal joint (via the capsule), and the extensor digitorum communis muscle via the extensor expansion help stabilize the volar plates on the four metacarpal heads volarly and the extensor digitorum communis tendons over the metacarpophalangeal joints dorsally.







- The distal end of each metacarpal is convex and the proximal phalanx concave.
- The proximal surface of the phalanx rolls and slides in the same direction.

Range of Motion:

• The total ROM available at the MCP joint varies with each finger.





- Flexion/extension increases radially to ulnarly
- **Index finger-** approx 90° of MCP joint flexion
- Little finger -110° flexion.
- Hyperextension is fairly consistent between fingers but varies widely among individuals



Figure 9–22 The available range of motion at the metacarpophalangeal joints of the fingers increases from the radial to the ulnar side, with the greatest metacarpophalangeal finger range at the fifth metacarpophalangeal joint.



- Articulation between the head of the first metacarpal and the base of its proximal phalanx.
- Condyloid joint
- 2 degrees of freedom: flexion/extension and abduction/adduction
- The main functions:
- > to provide additional flexion range to the thumb in opposition
- > to allow the thumb to grasp and contour to objects



The 1st MCP joint is far more restricted in motion than tho

the fingers.

• The 1st MCP joint is reinforced by 2 sesamoid bones and are maintained in position by intersesamoid ligaments.









- Each of the digits 2 through 5 has two interphalangeal (IP) joints, referred to as the proximal interphalangeal (PIP) and distal interphalangeal (DIP) joints.
- All of the IP joints are **hinge joints with one degree of freedom**.
- The IP joints possess volar plate mechanisms similar to the MCP joints with the addition of check rein ligaments, which prevent hyperextension







Figure 9–23 The proximal interphalangeal and distal interphalangeal joints, like the metacarpophalangeal joints, have volar plates that blend with the volar capsule portion of the capsule. The orientation of the collateral ligaments at the proximal and distal joints, however, differs from the orientation of the collateral ligaments at the metacarpophalangeal joints.







- The interphalangeal joint of the thumb is the articulation between the head of the proximal phalanx and the base of the distal phalanx.
- The thumb has only one IP joint.
- Pure hinge joint, which allows for extension, flexion, and opposition.
- It is structurally and functionally identical to the IP joints of the fingers.



Extrinsic finger flexors



- Flexor digitorum superficialis.
- Flexor digitorum profundus.
- Flexor digitorum superficialis: primarly flexes PIP, MCP joint
- FDP: Flexion MCP, PIP, DIP.
- Gentle pinch , grasp FDP muscle is alone active.
- Greater flexor force is needed when finger flexion with wrist flexion at that time FDS,FDP act together.



CAMPERS CHIASMA



• At the level of PIP joint two slips of each FDS

tendon reunite to form a tendinous chiasma.

• When FDS tendon is absent forceful pinch

activity of FDP muscle create PIP extension with

DIP flexion.



Mechanism of finger flexion



- Function of FDS, FDP:
- Stabilisation
- Smooth flexor gliding mechanism.
- Gliding mechanism consists of:
- Flexor retinacula, bursa, tendon, digital tendon sheath.
- Bursa, tendon sheath facilitate friction free gliding of tendon on the fibrous retinacula.





- Retinacula- prevent bowstringing of the tendons.
- Ulnar and radial bursa;
- Friction between tendons and friction of tendon overlying transverse carpal ligament prevented
 - by radial and ulnar bursa.





- The tendon of FDS, FDP through carpal tunnel is enclosed In ulnar bursa.
- The tendon of flexor pollicis longus through carpal tunnel is enclosed in radial bursa.
- Ulnar bursa is continuous with tendon sheath of little finger.
- For other fingers its ends at proximal palmar crease.





- Radial bursa is continuous with the tendon sheath.
- The tendon sheath for each finger ends at distal aspect of middle phalanx.







• FDS, FDP of each finger pass through fibro

osseous tunnel.

- Comprised of 5 transversely oriented ANNULAR
 PULLEY (Vaginal ligament).
- 3 obliquely oriented CRUCIATE PULLEY





- *A1-@ the head of metacarpal
- ***A2-** along volar midshaft of proximal phalanx
- ***A3** distal most part of proximal phalanx
- ***A4-** center of middle phalanx
- *A5- base of distal phalanx.
- **C1-** Located between A1 and A2
- **C2-** between A3 and A4
- **♦C3** between A4 and A5.
- Thumb has two annular pulley and 1 obique pulley





• VINCULA TENDINUM:

- These are folds of synovial membrane that carry blood vessels to the body of the tendon and to the insertions of FDS, FDP muscles of each finger.
- Direct vascularisation to tendon occurs through the vincula tendinum.
- Whenever this direct vascularisation is losed, it can withstand partialy with the nutrition from synovial fluid.









TRIGGER FINGER



- Repetative trauma of flexor tendons results in
 - nodules on the tendon and thickenning of annular pulley.
- During active finger flexion the nodule get caught/ stuck beneath the pulley that requires passive extension to unlock from the stucked flexed position.









Extrinsic-finger extensors



- Extensor digitorum communis
- Extensor indicis propius
- Extensor digiti minimi
- These muscle passes the forearm beneath the

extensor retinaculum.





• At the level of MCP joint , extensor communis

tendon of each finger merges with a broad

aponeurosis known as- EXTENSOR EXPANSION/

EXTENSOR HOOD.

Distal to extensor hood, the EDC tendon splits

into 3 band as: central tendon, 2 lateral bands.

Central tendon insert to base of middle phalanx.





- The extensor digitorum communis tendon of one finger is connected to the tendon of other adjacent fingers by a connective tissue called JUCTURA TENDINAE.
- This fibrous interconnections cause active extension of one finger to be accompanied by

passive extension of other finger.





 The EDC, EIP, EDM, Junctura tendinae connections results- independent extension of index finger with reduced independence of ring, middle, little finger.





Extensor mechanism



- Formed by EDC, EIP, EDM, extensor hood, central tendon, & the lateral bands that merge into terminal tendon
- Passive components are –
- Triangular ligaments (helps stabilize the bands on the dorsum of fingers) .
- Sagittal bands (connects volar surface of hood to volar plates) .
- Deep transverse MC ligament prevents bowstringing of extensor tendons.
- <u>Active components are:</u>
- Dorsal interossei (DI), Volar interossei (VI), Lumbrical.
- Lumbrical and interossei are called intrinsic muscles

Extensor mechanism influence on MCP joint function



- EDC tendon passes dorsal to MCP joint axis.
- Active contraction of muscle creates tension on

sagittal band of extensor mechanism.

- This tension pulls the band proximally over the MCP joint and extends proximal phalanx.
- Isolated contraction of EDC tendon cause:
- MCP joint hyperextension, IP joint flexion.





- IP joint flexion is caused tension of FDS and FDP.
- The position of finger with MCP joint hyperextension with passive IP flexion is known as **clawing.**
- In order to extend PIP, DIP, EDC tendon requires active assistance.
- Active forces of extensor expansion are DI, VI, Lumbricals.





- DI,VI- passes volar to MCP joint axis.
- When EDC, DI,VI, Lumbricals contract simultaneously MCP and IP joint will Extends.
- When intrinsic muscles are weak, EDC is unopposed, results in clawing of fingers with MCP joint

hyperextension.

 Clawed position is also called INTRINSIC MINUS POSITION.


Extensor mechanism influence on IP joint function



- When PIP Joint is extended, Dip joint is also extend.
- Active contraction of intrinsic muscle alone extends
 PIP, DIP joint.
- When intrinsic muscle contraction without simultaneous contraction of EDC cause flexion of MCP joint.
- Tension in both intrinsic and EDC tendon is necessary to produce full extension.



INTRINSIC FINGER MUSCULATURE



- Attachments distal to radiocarpal joint.
- Dorsal & volar interossei muscles :-
- Arise between the Metacarpals
- 4 DI & 3-4 VI muscles
- Function:
- MCP joint abduction &adduction.





- The interossei muscle fibers join extensor expansion in 2 locations.
- some fibers attach proximally to the proximal phalanx & to extensor hood.
- some attach more distally to lateral bands & central tendons.





- Role of interossei at MCP joint in Extension :-
- Effective stabilizer.
- prevent clawing due to flexion torque.
- Balances passive tension in the extrinsic extensors at MCP joint.
- Interossei muscles are effective abductors & adductors at MCP joint when MCP joint is in extension.



Role of interossei at MCP joint in flexion :-



- From extension to flexion tendons & action lines of interossei muscles migrate volarly away from coronal axis of MCP joint
- increases moment arm for MCP flexion –
- Increases the flexion torque at MCP joint as it approaches to full flexion.
- In full MCP flexion, abduction/adduction is restricted due to –tight collateral ligaments, shape of condyles on MC heads & active insufficiency of fully shortened interossei muscles.



Role of interossei at IP joint in IP extension:-



- IP joint extension produced by distal interossei is stronger than MCP abduction/adduction during MCP extension.
- Index & little finger has weaker IP extension than middle &ring fingers.
- proximal components are effective in MCP flexion & distal component in IP extension.
- So most consistent activity of interossei is when MCP joints are flexed & IP joints are extended.





Lumbrical muscles:-

- Only Muscles in the body that attaches to tendons of other muscles.
- Each muscle originates from tendon of FDP muscle in the palm
- ·-volar to deep transverse MC ligament .
- Inserted to lateral band of extensor mechanism on radial side.





Lumbrical contraction increases tension In lateral

band leading to PIP, DIP joint extension.







- When lumbricals and interossei contract
 - together without any extrinsic muscle activity these muscles produce :
- <u>MCP flexion and interphalangeal extension</u>
 - called as INTRINSIC PLUS POSITION OF HAND.



Intrinsic plus position









- This position is also known as ANTI DEFORMITY POSITION.- MCP- flexion and IP- Extension.
- After trauma to hand, splint is provided in this position.
- If MCP joint is in extended position, it result in shortening of collateral ligaments, that will limit MCP joint flexion that will leads to impairment in grasp and functional use.





- So immobilasation splint should be in MCP
 Flexion
- So collateral ligaments are stretched, reduces the

risk of contracture.











When extrinsic finger flexors and extensors are active without any activity of intrinsic muscles causes MCP extension and IP flexion. INTRINSIC MINUS POSITION



How Is Bunnell Test Performed?



- This test is done in two stages, metacarpophalangeal joint MCP extension and flexion:
- The metacarpophalangeal joint is stabilized in extension and the proximal interphalangeal joint is tried to flex and the degree of flexion is noted.
- Then the metacarpophalangeal joint is **flexed** and again the degree of flexion of proximal interphalangeal joint is noted.





The test most commonly used to test for

intrinsic contracture is the intrinsic tightness (Bunnell) test.



What Does A Positive Bunnell Test Mean?

- We differentiate 3 cases:
- If the PIP flexion is increased, the pathology is intrinsic muscle contracture (Intrinsic tightness) as the intrinsic get released on MCP flexion.
- If the PIP flexion is decreased, the pathology is Extensor tendon contracture (extrinsic tightness) which is stretched further on MCP flexion.
- If the PIP flexion is the same in both situations, the pathology is articular changes such as joint stiffness, tendon adhesions, and tenosynovitis









Thumb musculature



- Flexor pollicis longus
- Extensor pollicis brevis
- Extensor pollicis longus
- Abductor pollicis longus.





- There is a prominent bony tubercle over the dorsal aspect of distal radius known as LISTERS TUBERCLE.
- It function as anatomic pulley for the extensor pollicis longus tendon before the tendon pivot and turns to insert into distal phalanx of thumb.











PREHENSION



Prehension activities involves grasping or taking hold

of an object between any 2 surfaces of hand.

Thumb participate in most but not all the prehension







Power Grips





Cylindrical Grip



Hook Grip



Spherical Grip



Lateral Prehension

Precision Grips





POWER GRIP



- Forceful act resultig in flexion of all finger joint.
- Thumb act as stabiliser to the object held in fingers/ palm.
- Phases:
- Opening of hand
- Positioning of the fingers
- Bringing the fingers to the object
- Maintaining static phase
- Object is grasped to move through space by some proximal joints
- Thumb is generally adducted





- Different power grips –
- Cylindrical grip
- Spherical grip
- Hook grip
- Lateral prehension



CYLINDRICALGRIP

STS INSTITUTIONS

- Involves use of all finger flexors
- FDP works predominantly
- Interossei muscles –
 primary MCP flexors,
 abductors/adductors
- Wrist is in neutral/ extension and slight ulnar deviation.
- E.g. turning a door knob.









- Most respect to cylindrical grip but greater spread of fingers to encompass the object.
- More activity of interosseus
- for e.g. holding a ball.





HOOKGRIP



- Major activity of FDP&FDS.
- Load more carried distally FDP,
- proximally (FDS)
- Thumb- moderate to full extension.
- E.g. carrying a briefcase





LATERAL PREHENSION



- Contact between two fingers.
- MCP & IP joint- in extension
- Extensor musculature pre dominates.
- E.g. holding a paper





PRECISION HANDLING



- Require much finer motor control & more dependent on intact sensation.
- Skillful placement of an object between fingers or between fingers and thumb .
- No involvement of palm



PAD TO PAD PREHENSION



- 3 varieties of precision are –
- Pad to pad prehension
- Tip to tip prehension
- Pad to side prehension.







- Involves opposition of pad or pulp of thumb to pad or pulp of finger.
- MCP & proximal IP joint of the finger partially flexed
- Distal IP joint- extended or slightly flexed
- Thumb-CMC flexion, abduction
- E.g. holding a foreceps



TIP TO TIP PREHENSION



- MCP joint of opposing finger deviates ulnarly.
- E.g. holding a pen.







SIDE TO SIDE PREHENSION



- Key grip or lateral pinch.
- Between thumb & side of index Finger
 - Thumb more adducted and

least rotated.







Power Grip

Precision Grip







- The functional position is –
- Wrist complex in slight extension (20°) & slight ulnar deviation (10°)
- Fingers moderately flexed at MCP joint (45°)
 & proximal IP joint (30°) & slightly flexed at
 distal IP joint




PATHOMECHANICS

- Boutonniere deformity
- Swan neck deformity
- Dupuytren's contracture
- Mallet finger
- Claw finger





Boutonniere deformity

- Occurs when the central slip of the extensor digitorum is injured at its insertion on the middle phalanx.
- The lateral bands lose their connection to the central band, so they drift more anterior toward the **PIP joint**, causing that joint to **flex**.
- Because of the flexed position of the PIP, the lateral bands are now more posterior to the axis of motion of the **DIP joint**, so that joint becomes **hyperextended**.

Boutonniere Deformity









Swan neck deformity

- Occurs primarily with arthritis
- With subsequent weakness of the intrinsic muscles, the PIP joints deform into hyperextension.
- This causes increased tension on the flexor digitorum profundus so the DIP joint maintains a flexed position.







<u>Mallet finger</u>

- Result of the rupture of the avulsion of the extensor tendon where it inserts in the distal phalanx of the finger
- **Distal phalanx** rests in a **flexed position**













Dupuytren's contracture

• Palpable thickening of the palmar fascia and a progressive flexion contracture of the ulnar two fingers.



Figure 17.4: Dupuytren's contracture produces flexion of the ulnar fingers.

<u>Claw finger</u>

- Intrinsic minus hand
- MCP joints are hyperextended and PIP & DIP joints are flexed







THANK YOU