

CPU Scheduling



- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms



Objectives



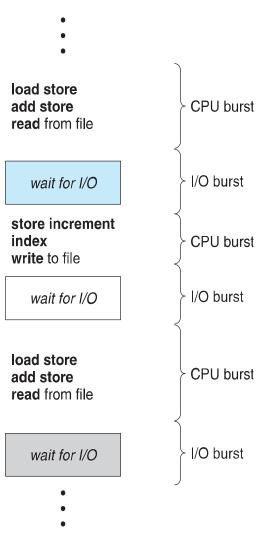
- To introduce CPU scheduling, which is the basis for multiprogrammed operating systems
- To describe various CPU-scheduling algorithms
- To discuss evaluation criteria for selecting a CPUscheduling algorithm for a particular system
- To examine the scheduling algorithms of several operating systems



Basic Concepts



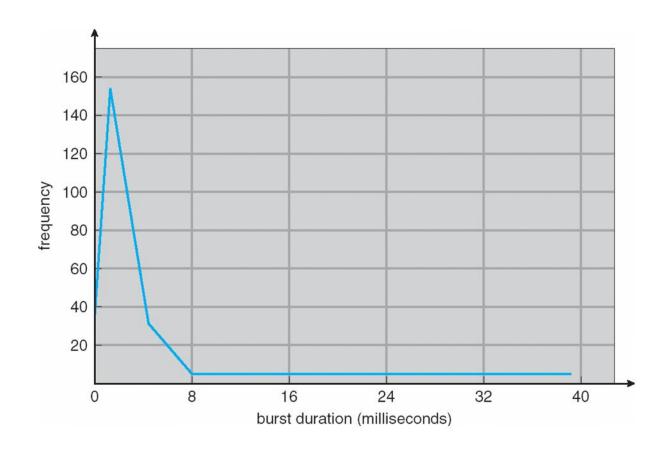
- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle –
 Process execution
 consists of a cycle of
 CPU execution and I/O
 wait
- CPU burst followed by I/O burst
- CPU burst distribution is of main concern





Histogram of CPU-burst Times







CPU Scheduler



- Short-term scheduler selects from among the processes in ready queue, and allocates the CPU to one of them
 - Queue may be ordered in various ways
- CPU scheduling decisions may take place when a process:
 - 1. Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from waiting to ready
 - 4. Terminates
- Scheduling under 1 and 4 is nonpreemptive
- All other scheduling is preemptive
 - Consider access to shared data
 - Consider preemption while in kernel mode
 - Consider interrupts occurring during crucial OS activities



Dispatcher



- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
 - switching context
 - switching to user mode
 - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running



Scheduling Criteria



- CPU utilization keep the CPU as busy as possible
- Throughput # of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)



Scheduling Algorithm Optimization Criter's



- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time



First-Come, First-Served (FCFS) Scheduling S



<u>Process</u>	Burst Time
P_1	24
P_2	3
P_3	3

• Suppose that the processes arrive in the order: P_1 , P_2 , P_3 The Gantt Chart for the schedule is:



- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17



FCFS Scheduling (Cont.)



Suppose that the processes arrive in the order:

$$P_2$$
, P_3 , P_1

The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process
 - Consider one CPU-bound and many I/O-bound processes



- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal gives minimum average waiting time for a given set of processes
 - The difficulty is knowing the length of the next CPU request
 - Could ask the user

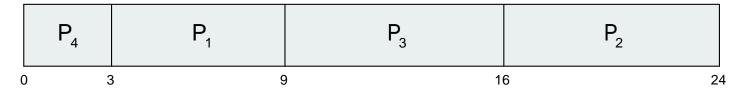


Example of SJF



<u>Process</u>		<u>Burst Time</u>
P_1	6	
P_2	8	
P_3	7	
P_4	3	

SJF scheduling chart



• Average waiting time = (3 + 16 + 9 + 0) / 4 = 7

Determining Length of Next CPU Burst

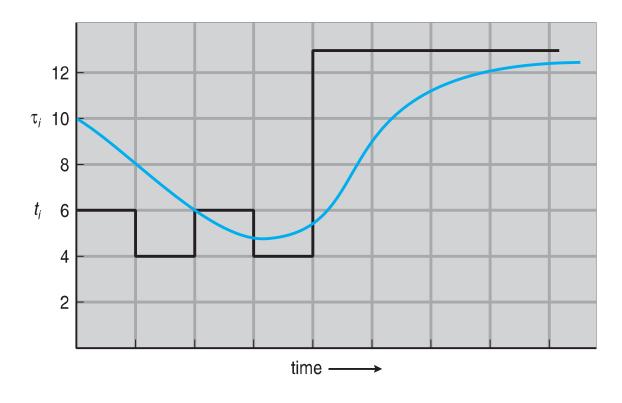


- Can only estimate the length should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging
 - 1. $t_n = \text{actual length of } n^{th} \text{ CPU burst}$
 - 2. τ_{n+1} = predicted value for the next CPU burst
 - 3. α , $0 \le \alpha \le 1$
 - 4. Define: $\tau_{n=1} = \alpha t_n + (1-\alpha)\tau_n$.
- Commonly, α set to ½
- Preemptive version called shortest-remaining-time-first



Prediction of the Length of the Next CPU Burst





CPU burst (t_i) 6 4 6 4 13 13 ...
"guess" (τ_i) 10 8 6 6 5 9 11 12 ...



Examples of Exponential Averaging



- \bullet $\alpha = 0$
 - $\tau_{n+1} = \tau_n$
 - Recent history does not count
- $\alpha = 1$
 - $\tau_{n+1} = \alpha t_n$
 - Only the actual last CPU burst counts
- If we expand the formula, we get:

$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\alpha t_{n-1} + ...$$

$$+ (1 - \alpha)^j \alpha t_{n-j} + ...$$

$$+ (1 - \alpha)^{n+1} \tau_0$$

• Since both α and (1 - α) are less than or equal to 1, each successive term has less weight than its predecessor



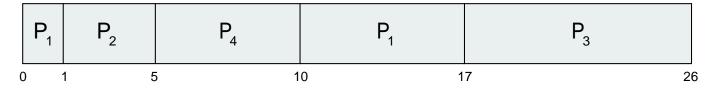
Example of Shortest-remaining-time-first



 Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>	<u> Arrival Time</u>	Burst Time
P_1	0	8
P_2	1	4
P_3	2	9
P_4	3	5

• *Preemptive* SJF Gantt Chart



• Average waiting time = [(10-1)+(1-1)+(17-2)+5-3)]/4 = 26/4 = 6.5 msec



Priority Scheduling



- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
 - Preemptive
 - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- Problem = Starvation low priority processes may never execute
- Solution = Aging as time progresses increase the priority of the process



Example of Priority Scheduling



<u>Process</u>	Burst Time	<u>Priority</u>
P_1	10	3
P_2	1	1
P_3	2	4
P_4	1	5
P_5	5	2

Priority scheduling Gantt Chart



Average waiting time = 8.2 msec



Round Robin (RR)



- Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once. No process waits more than (*n*-1)*q* time units.
- Timer interrupts every quantum to schedule next process
- Performance
 - q large \Rightarrow FIFO
 - q small $\Rightarrow q$ must be large with respect to context switch, otherwise overhead is too high

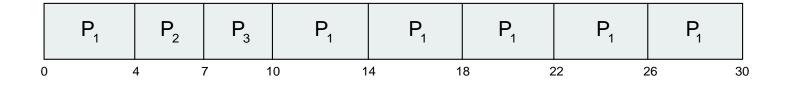


Example of RR with Time Quantum = 4



<u>Process</u>	Burst Time
P_1	24
P_2	3
P_3	3

The Gantt chart is:

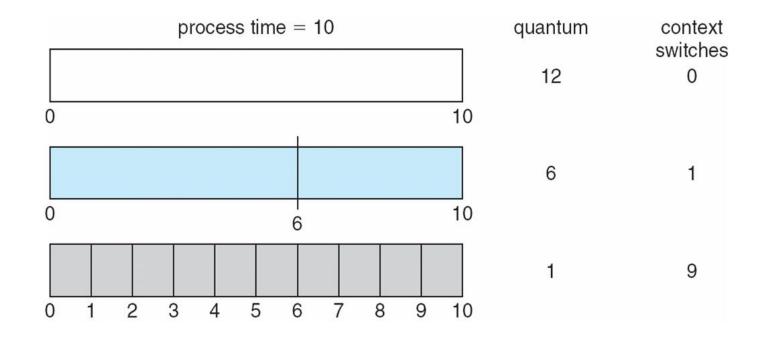


- Typically, higher average turnaround than SJF, but better response
- q should be large compared to context switch time
- q usually 10ms to 100ms, context switch < 10 usec



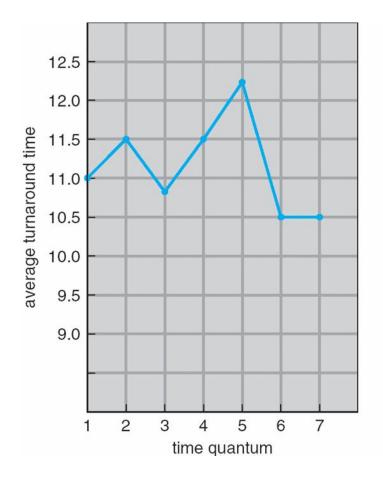
Time Quantum and Context Switch Time





Turnaround Time Varies With The Time Quantum 🥿





process	time
P_1	6
P_2	3
P_3	1
P_4	7

80% of CPU bursts should be shorter than q



Multilevel Queue

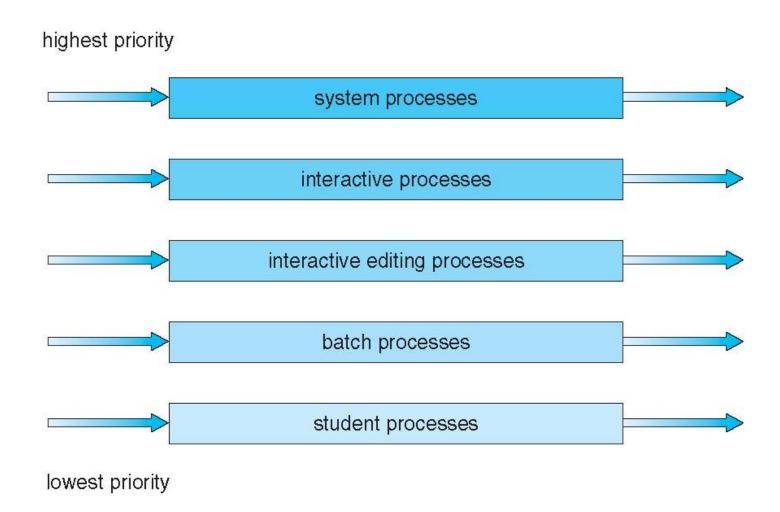


- Ready queue is partitioned into separate queues, eg:
 - foreground (interactive)
 - background (batch)
- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
 - foreground RR
 - background FCFS
- Scheduling must be done between the queues:
 - Fixed priority scheduling; (i.e., serve all from foreground then from background). Possibility of starvation.
 - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR
 - 20% to background in FCFS



Multilevel Queue Scheduling







Multilevel Feedback Queue



- A process can move between the various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
 - number of queues
 - scheduling algorithms for each queue
 - method used to determine when to upgrade a process
 - method used to determine when to demote a process
 - method used to determine which queue a process will enter when that process needs service



Example of Multilevel Feedback Queue



- Three queues:
 - $-Q_0$ RR with time quantum 8 milliseconds
 - Q_1 RR time quantum 16 milliseconds
 - $-Q_2 FCFS$
- Scheduling
 - A new job enters queue Q₀ which is served FCFS
 - When it gains CPU, job receives 8 milliseconds
 - If it does not finish in 8 milliseconds, jol moved to queue Q₁
 - At Q₁ job is again served FCFS and receives 1₂ additional milliseconds
 - If it still does not complete, it is preempted and moved to queue Q₂

