

# **SNS COLLEGE OF ENGINEERING**

Kurumbapalayam (Po), Coimbatore – 641 107

### **An Autonomous Institution**

Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A' Grade Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai

### **DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING**

### **COURSE NAME : 19EE401 SYNCHRONOUS AND INDUCTION MACHINES**

II YEAR /IV SEMESTER

## **Unit 3: INDUCTION MOTOR**

## **Topic 5 : Equivalent Circuit of Three Phase Induction Motor**

Equivalent Circuit of Three Phase Induction Motor/19EE401-Synchronous and Induction Machines/JEBARANI S/EEE/SNSCE



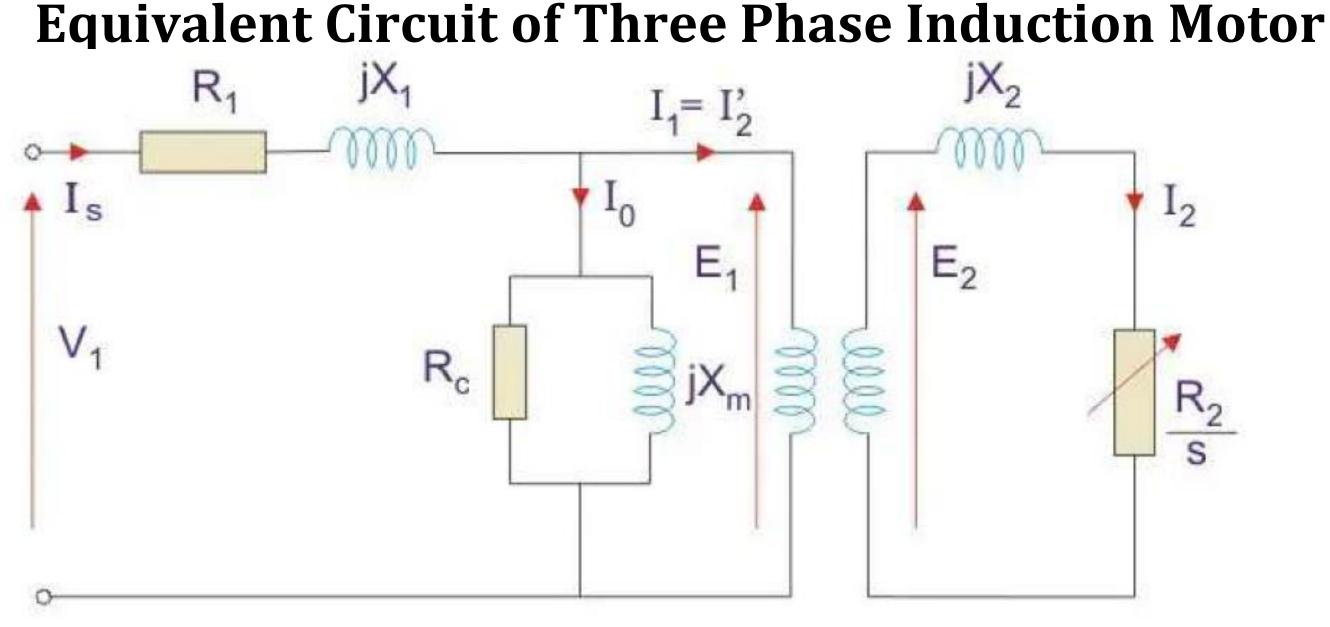


## **Equivalent Circuit of Three Phase Induction Motor**

An induction motor is a well-known device which works on the principle of transformer. So it is also called the rotating transformer. That is, when an EMF is supplied to its stator, then as a result of electromagnetic induction, a voltage is induced in its rotor. So an induction motor is said to be a transformer with rotating secondary. Here, primary of transformer resembles stator winding of an induction motor and secondary resembles rotor.







Here,  $R_1$  is the winding resistance of the stator.

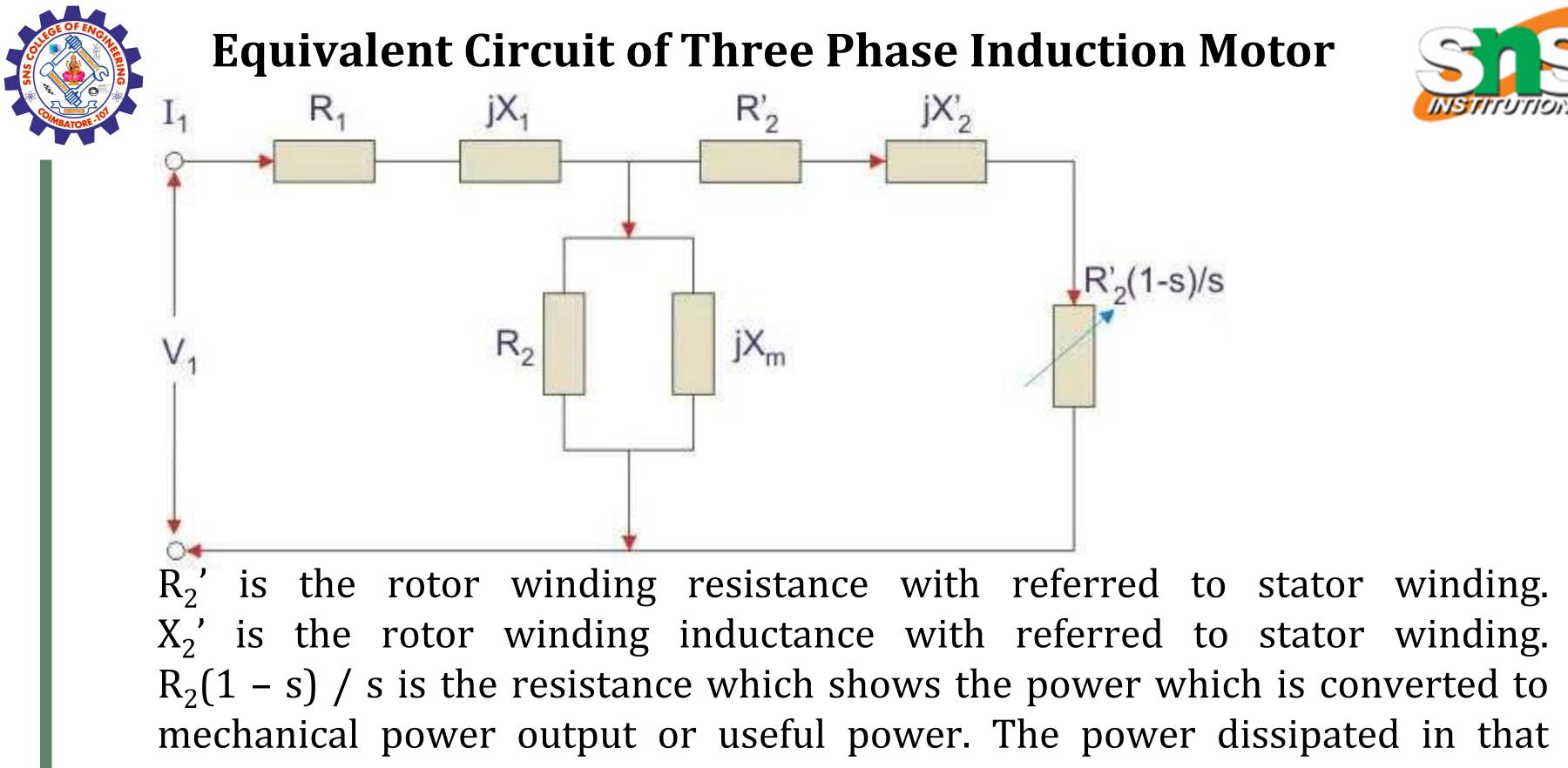
 $X_1$  is the inductance of the stator winding.

 $R_c$  is the core loss component.

 $X_{M}$  is the magnetizing reactance of the winding.  $R_2/s$  is the power of the rotor, which includes output mechanical power and copper loss of rotor.



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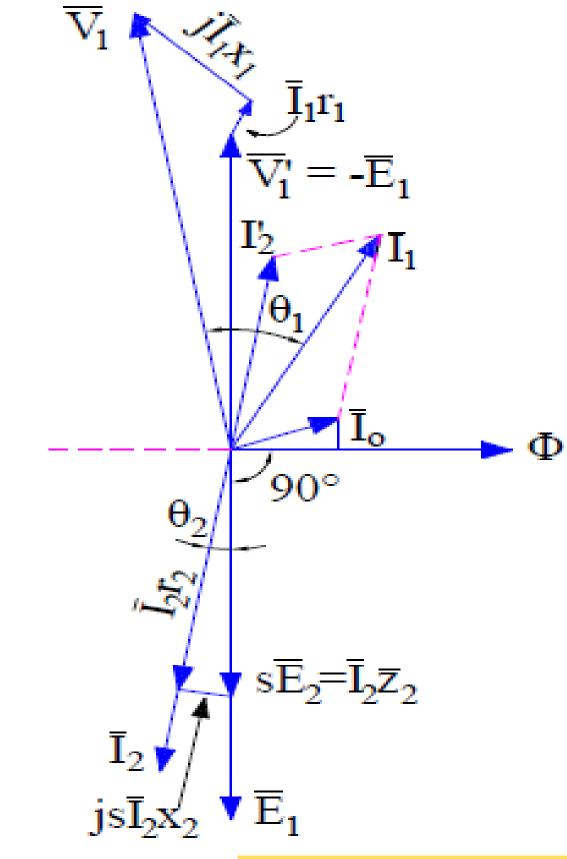


resistor is the useful power output or shaft power.





## **Three Phase Induction Motor on Load**



$$V_1 = V_1' +$$

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## + $I_1(r_1 + jx_1)$

## $E_2 = I_2 (r_2 + jx_2)$

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## **Power Relation of Equivalent Circuit of Three Phase Induction Motor**

- $\succ$  Input power to stator  $P_1 = 3 V_1 I_1 Cos(\theta)$ Where,  $V_1$  is the stator voltage applied,  $I_1$  is the current drawn by the stator winding.  $Cos(\Theta)$  is the stator power stator.
- Rotor input =Power input Stator copper and iron losses.
- Rotor Copper loss = Slip × power input to the rotor.
- $\blacktriangleright$  Developed Power =  $(1 s) \times Rotor$  input power.





## References

1.Kothari, D.P., Nagrath, I.J., "Electric Machines", McGraw Publishing Company Ltd, 5<sup>th</sup> Edition, 2017. 2. Murugesh Kumar, K., "Induction and Synchronous machines", Vikas Publishing House Private Ltd, 2016.

## **Thank You**



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