



SNS COLLEGE OF ENGINEERING

Kurumbapalayam (Po), Coimbatore – 641 107

An Autonomous Institution

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DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING-IOT Including CS&BCT

COURSE NAME : 19SB601 ARTIFICIAL INTELLIGENCE AND NATURAL LANGUAGE PROCESSING

III YEAR / VI SEMESTER

Unit I-INTRODUCTION TO ARTIFICIAL INTELLIGENCE& INTELLIGENT SYSTEMS Topic : INFORMED STRATEGIES

INTRODUCTION TO ARTIFICIAL INTELLIGENCE& INTELLIGENT SYSTEMS / 19SB601 ARTIFICIAL INTELLIGENCE AND NATURAL LANGUAGE PROCESSING /Mr.R.Kamalakkannan/CSE-IOT/SNSCE



ARTIFICIAL INTELLIGENT





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Informed Search Algorithms



- The informed search algorithm is also called heuristic search or directed search.
- In contrast to uninformed search algorithms, informed search algorithms require details such as distance to reach the goal, steps to reach the goal, cost of the paths which makes this algorithm more efficient.
- > The goal state can be achieved by using the heuristic function.
- The heuristic function is used to achieve the goal state with the lowest cost possible.
- > This function estimates how close a state is to the goal.





- Greedy best-first search uses the properties of both depth-first search and breadth-first search.
- Greedy best-first search traverses the node by selecting the path which appears best at the moment.
- > The closest path is selected by using the heuristic function.
- > Consider the below graph with the heuristic values.











- Here, A is the start node and H is the goal node.
- Greedy best-first search first starts with A and then examines the next neighbour B and C.
- ➢ Here, the heuristics of B is 12 and C is 4.
- > The best path at the moment is C and hence it goes to C.
- ➢ From C, it explores the neighbours F and G.
- ➤ the heuristics of F is 8 and G is 2. Hence it goes to G.
- From G, it goes to H whose heuristic is 0 which is also our goal state.







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Let's try this with Python.

```
graph = {
  'A':[('B',12), ('C',4)],
  'B':[('D',7), ('E',3)],
  'C':[('F',8), ('G',2)],
  'D':[],
  'E':[('H',0)],
  'F':[('H',0)],
  'G':[('H',0)]
}
```





```
def bfs(start, target, graph, queue=[], visited=[]):
  if start not in visited:
    print(start)
    visited.append(start)
  queue=queue+[x for x in graph[start] if x[0][0] not in visited]
  queue.sort(key=lambda x:x[1])
  if queue[0][0]==target:
    print(queue[0][0])
  else:
    processing=queue[0]
    queue.remove(processing)
    bfs(processing[0], target, graph, queue, visited)
bfs('A', 'H', graph)
```

```
The time complexity of Greedy best-first search is O(b<sup>m</sup>) in worst cases.
```





Advantages of Greedy best-first search

> Greedy best-first search is more efficient compared with breadth-first search and depth-first search.

Disadvantages of Greedy best-first search

- > In the worst-case scenario, the greedy best-first search algorithm may behave like an unguided DFS.
- > There are some possibilities for greedy best-first to get trapped in an infinite loop.
- > The algorithm is not an optimal one.





Any Query????

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Thank you.....

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