



# SNS COLLEGE OF ENGINEERING



(Autonomous)

DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING

## UNIT- I

### Discrete Fourier Transform

### Review of Discrete Signals and Systems



# Overview

- Signal
- Continuous or analog signals
- Discrete-time signals
- Causal signals
- Deterministic and Random signals
- Digital Functions (Impulse, Step, Ramp, Power, Exponential, Sine)
- Notation for Digital Signals
- Composite Functions
- Two-Dimensional Digital Signals
- Linear, Time-Invariant (LTI), Causal Systems



# Signal

- A **signal** is a physical quantity, or quality, which conveys information
- The variation of the signal value as a function of the independent variable is called a **waveform**
- The independent variable often represents **time**
- We define a **signal** as a function of one independent variable that contains information about the behavior or nature of a phenomenon
- We assume that the independent variable is **time** even in cases where the independent variable is a physical quantity other than time

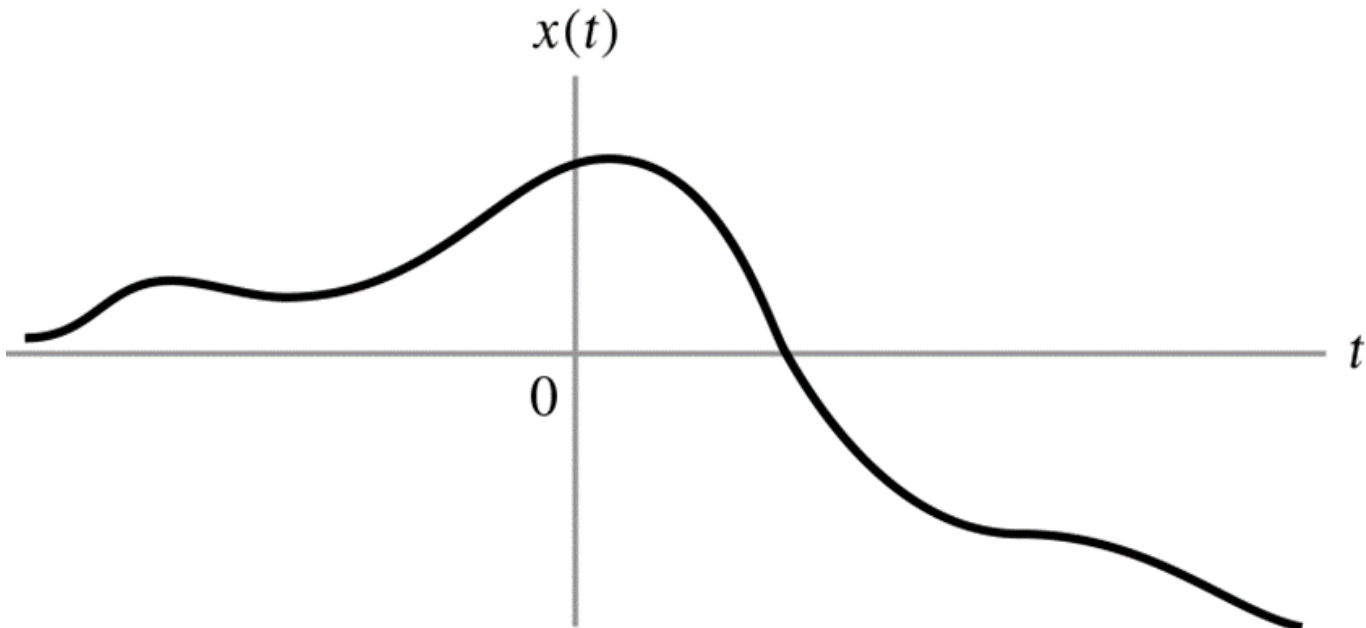


# Continuous or Analog Signals

- **Continuous signal** is a signal that exists at every instant of time
- A continuous signal is often referred to as **continuous time (CT)** or **analog**
- The independent variable is a **continuous** variable
- Continuous signal can assume **any value** over a continuous range of numbers

# Continuous or Analog Signals

- Most of the signals in the physical world are CT signals.
- Examples: voltage & current, pressure, temperature, velocity, etc.



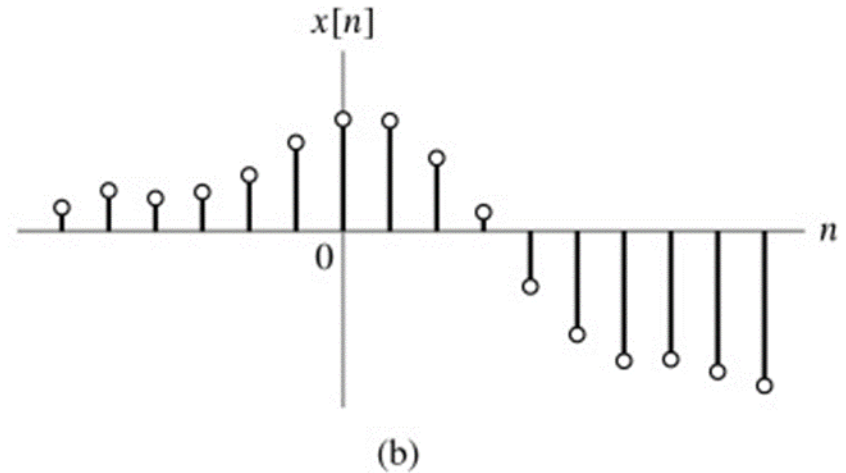
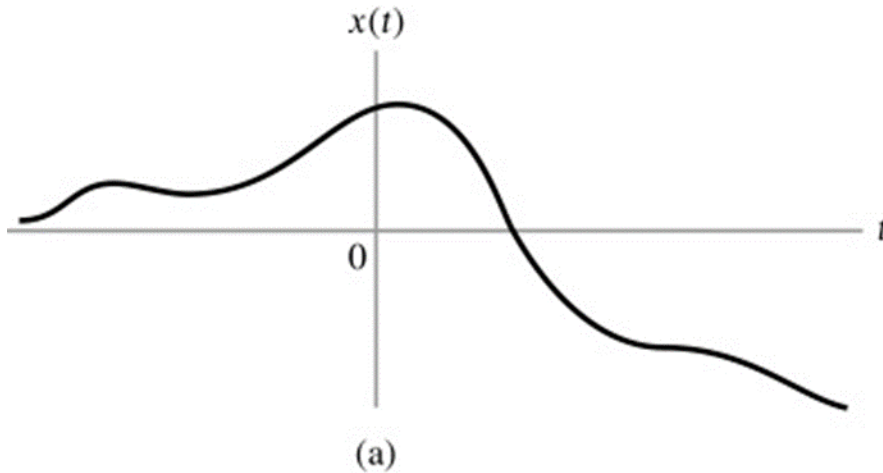


# Discrete-Time Signals

- A signal defined only for discrete values of time is called a **discrete-time (DT) signal** or simply a **discrete signal**
- Discrete signal can be obtained by taking **samples** of an analog signal at discrete instants of time
- **Digital signal** is a discrete-time signal whose values are represented by digits

# Discrete-Time Signals

- Figure (a): CT Signal
- Figure (b): DT Signal



- Examples of DT signals in nature:
- DNA base sequence
- Number of students in a class
- Population of the  $n$ th generation of certain species



# Discrete-time signal – Sequence

- A **sequence** (discrete-time signal, discrete signal, data sequence, or sample set) is a collection of ordered samples
- In practical applications we process **finite-length** sequences
- The existing sequence is often a sampled version of a continuous signal





# Causal Signals

- A signal is **causal** if it is zero for  $t < 0$
- Causal signals are readily created by multiplying any continuous signal by the unit step signal
- The instant when the signal begins is called the **starting time**
- We usually take the starting time to be **zero**



# Causal Sequence

- A sequence that is nonzero only over a finite interval of indices is called a ***finite-length sequence***
- A sequence whose samples are zero-valued for negative indices is ***causal***
- ***Anti-causal sequence*** can have nonzero samples only for negative indices



# Deterministic and Random Signal

- Signal that can be described by an explicit mathematical form is **deterministic**
- Deterministic signal can be **periodic** or **aperiodic**
- Periodic signal consists of a basic shape of finite duration that is replicated infinitely
- Signal that cannot be described in an explicit mathematical form is called **random**, also known as **nondeterministic** or **stochastic**



# Classification of Systems



*A system is any process that produces an output signal in response to an input signal.*

Systems are classified into the following categories:

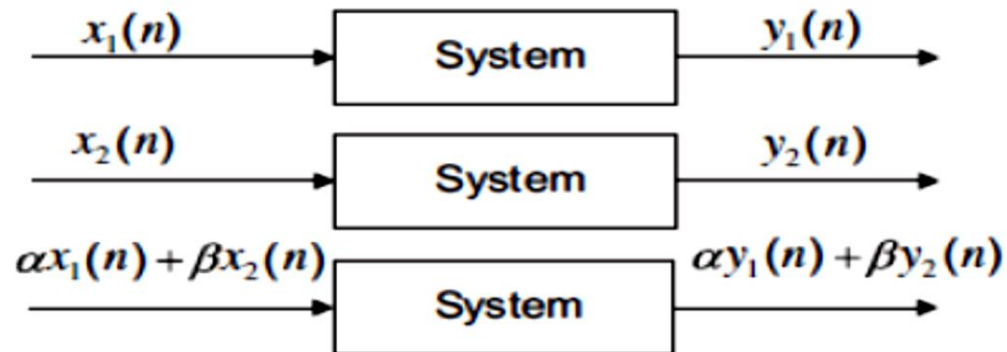
- Linear and Non-linear Systems.
- Time Variant and Time Invariant Systems
- Static and Dynamic System
- Causal and non causal system
- Stable and Unstable system



# Linear System



- A linear system is illustrated in the figure.
- The linear system obeys the superposition principle.
- $y_1(n)$  is the system output using an input  $x_1(n)$
- $y_2(n)$  the system output with an input  $x_2(n)$





- The Linear system output due to the weighted sum inputs

$\alpha x_1(n) + \beta x_2(n)$  is equal to the same weighted sum of the individual outputs obtained from their corresponding inputs, that is,

$y(n) = \alpha y_1(n) + \beta y_2(n)$ , where  $\alpha$  and  $\beta$  are constants.



## Linear System

**Example:** A digital amplifier is represented by  $y(n) = 10x(n)$ , the input is multiplied by 10 to generate the output.

- The inputs  $x_1(n) = u(n)$  and  $x_2(n) = \delta(n)$  generate the outputs  
 $y_1(n) = 10u(n)$  and  $y_2(n) = 10\delta(n)$ , respectively
- We apply the combined input  $x(n)$  to the system, where the first input multiplied by a constant 2 while the second input multiplied by a constant 4,  
 $x(n) = 2x_1(n) + 4x_2(n) = 2u(n) + 4\delta(n)$



# Linear System

- The system output due to the combined input is

$$\begin{aligned}y(n) &= 10x(n) = 10(2u(n) + 4\delta(n)) \\ &= 20u(n) + 40\delta(n) \quad (1)\end{aligned}$$

- If we verify the weighted sum of the individual outputs, we see that

$$2y_1(n) + 4y_2(n) = 20u(n) + 40\delta(n) \quad (2)$$

- Comparing Equations (1) and (2) verifies that

$$y(n) = 2y_1(n) + 4y_2(n)$$

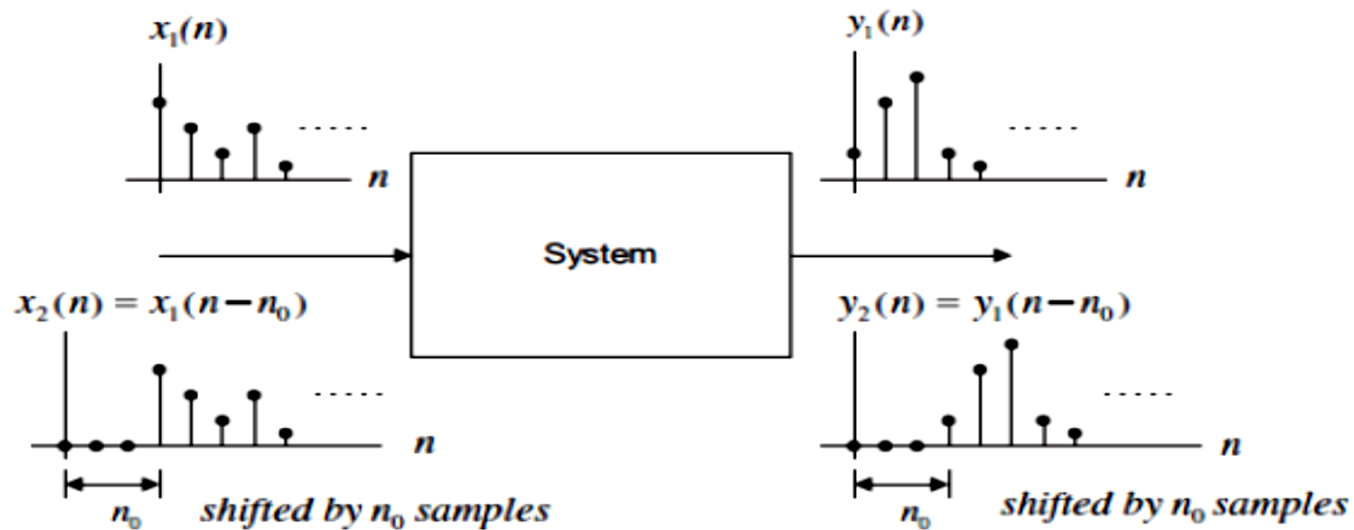
- Hence, the system  $y(n) = 10x(n)$  is a **linear system**.





# Time-Invariant System

A time-invariant system is illustrated in the figure.





## Time-Invariant System

If the system is time invariant and  $y_1(n)$  is the system output due to the input  $x_1(n)$ , then the shifted system input  $x_1(n - n_0)$  will produce a shifted system output  $y_1(n - n_0)$  by the same amount of time  $n_0$ .



## Time-Invariant System

**Example: Determine whether the linear system  $y(n) = 2x(n) - 5$  is time invariant.**

- Let the input and output be  $x_1(n)$  and  $y_1(n)$ , respectively; then the system output is

$$y_1(n) = 2x_1(n - 5)$$

- Again, let  $x_2(n) = x_1(n - n_0)$  be the shifted input and  $y_2(n)$  be the output due to the shifted input. The system output using the shifted input can be described as

$$y_2(n) = 2x_2(n - 5) = 2x_1(n - n_0 - 5)$$



## Time-Invariant System

- ▣ Meanwhile, shifting  $y_1(n) = 2x_1(n - 5)$  by  $n_0$  samples leads to

$$y_1(n - n_0) = 2x_1(n - 5 - n_0)$$

- ▣ We can verify that  $y_2(n) = y_1(n - n_0)$ . Thus the shifted input of  $n_0$  samples causes the system output to be shifted by the same  $n_0$  samples. The system is thus **time invariant**.



## Causal System

- A causal system is the one in which the output  $y(n)$  at time  $n$  depends only on the current input  $x(n)$  at time  $n$ , and its past input sample values such as  $x(n - 1)$ ,  $x(n - 2)$ , .... Otherwise, if a system output depends on future input values such as  $x(n + 1)$ ,  $x(n + 2)$ , .... the system is noncausal.
- The noncausal system cannot be realized in real time..



# Static and Dynamic System



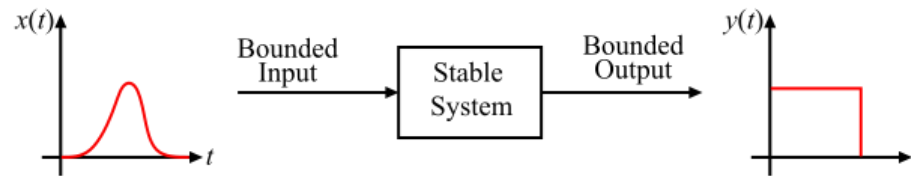
- A system whose response or output is due to present input alone is known as **static system**.
- The static system is also called **the memoryless system**.
- For a static or memoryless system, the output of the system at any instant of time ( $t$  for continuous-time system or  $n$  for discrete-time system) depends only on the input applied at that instant of time ( $t$  or  $n$ ), but not on the past or future values of the input.
- A system whose response or output depends upon the past or future inputs in addition to the present input is called the **dynamic system**.
- The dynamic systems are also known as **memory systems**.
- Any continuous-time dynamic system can be described by a differential equation or any discrete-time dynamic system by a difference equation.



# Stable System



- A system is called a BIBO (**bounded input bounded output**) **stable system** or simply **stable system**, if and only if every bounded input produces a bounded output. The output of a stable system does not change unreasonably.

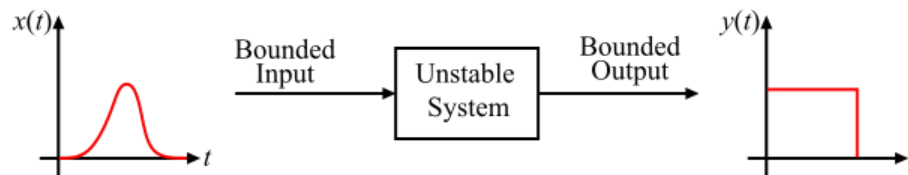




# Unstable System



- If a system does not satisfy the BIBO stability condition, the system is called the unstable system. Therefore, for a bounded input, it is not necessary that the unstable system produces a bounded output.
- Thus, we can say that a system is unstable even if one bounded input generates an unbounded output.







# Assessment



1. A signal which contains -----
2. List the classification of signals.
3. What is meant by Periodic and Aperiodic Signal.
4. A signal that is defined for every instants of time is known as -----
5. Give some applications of signals.
6. Define System and mention its types.
7. What is meant by deterministic and Random Signal.
8. Define Even and Odd Signal.



Thank You!