



AUTOMATED PRODUCTION LINES





CH 17 AUTOMATED ASSEMBLY SYSTEMS

Sections:

- 1. Fundamentals of Automated Assembly Systems
- 2. Quantitative Analysis of Assembly Systems





AUTOMATED ASSEMBLY - DEFINED

The use of mechanized and automated devices to perform the various assembly tasks in an assembly line or cell

Fixed automation usually

 Most automated assembly systems are designed to perform a fixed sequence of assembly steps on a specific product that is produced in very large quantities



AUTOMATED ASSEMBLY -APPLICATION CHARACTERISTICS

STATE

Where is automated assembly appropriate:

- High product demand
- Stable product design
- The assembly consists of no more than a limited number of components
- The product is designed for automated assembly





TYPICAL PRODUCTS

Alarm clocks	Light bulbs
Ball bearings	Locks
Ball point pens	Mechanical pencils
Cigarette lighters	PCB assemblies
Door mechanisms	Small electric motors
Gear boxes	Wrist watches



ASSEMBLY PROCESSES IN AUTOMATED ASSEMBLY

STS INSTITUTIONS

Adhesive bonding

Insertion of components

Placement of components

Riveting

Screw fastening

Soldering

Spot welding

Snap fitting

Stapling

Stitching





SYSTEM CONFIGURATIONS

- 1. In-line assembly machine
- 2. Dial indexing machine
- 3. Carousel assembly system
- 4. Single-station assembly cell





IN-LINE ASSEMBLY MACHINE

A series of automatic workstations located along and in-line transfer system





OF ENGINE

DIAL INDEXING MACHINE

Base parts are loaded onto fixtures or nests attached to a circular dial table, and components are added at workstations located around the periphery of the dial as it indexes from station to station







Dial indexing assembly machine (Bodine Corp.)







CAROUSEL ASSEMBLY SYSTEM







SINGLE-STATION ASSEMBLY CELL

Assembly operations are performed on a base part at a single location

A robot is sometimes used as the assembly machine

Components added at one stations







MULTI-STATION VS. SINGLE-STATION

Multi-station assembly machine or line

- Faster cycle rate
- High production quantities
- More operations possible
- More components per assembly

Single-station assembly cell

- Suited to robotic assembly
- Intended for lower production quantities





PARTS DELIVERY AT WORKSTATIONS

Typical parts delivery system at a workstation consists of the following hardware components:

- 1. Hopper container for parts
- 2. Parts feeder removes parts from hopper
- 3. Selector and/or orientor to assure part is in proper orientation for assembly at workhead
- 4. Feed track moves parts to assembly workhead
- 5. Escapement and placement device removes parts from feed track and places them at station





PARTS DELIVERY SYSTEM AT STATION







VIBRATORY BOWL FEEDER

- Most versatile of hopper feeders for small parts
- Consists of bowl and helical track
- Parts are poured into bowl
- Helical track moves part from bottom of bowl to outlet
- Vibration applied by electromagnetic base
- Oscillation of bowl is constrained so that parts climb upward along helical track





VIBRATORY BOWL FEEDER







VIBRATORY BOWL FEEDER

Photo courtesy Syntron Inc.







SELECTOR AND/OR ORIENTOR

Purpose - to establish the proper orientation of the components for the assembly workhead

Selector

- Acts as a filter
- Only parts in proper orientation are allowed to pass through to feed track

Orientor

- Allows properly oriented parts to pass
- Reorients parts that are not properly oriented





PARTS SELECTION AND ORIENTATION



http://www.youtube.com/watch?v=QsJzSFVAnhk





FEED TRACK

Moves parts from hopper to assembly workhead

Categories:

- 1. Gravity hopper and feeder are located at higher elevation than workhead
- 2. Powered uses air or vibration to move parts toward workhead





Escapement device

 Device that removes parts from feed track at time intervals that are consistent with the cycle time of the assembly workhead

Placement device

• Device that physically places the parts in the correct location at the assembly workstation

Escapement and placement devices are sometimes the same device, sometimes different devices







(a) Horizontal and (b) vertical devices for placement of parts onto dial-indexing table







Escapement of rivet-shaped parts actuated by work carriers







Two types of pick-and-place mechanisms for transferring base parts from feeders to work carriers



QUANTITATIVE ANALYSIS OF ASSEMBLY SYSTEMS

- 1. Parts delivery system at workstations
- 2. Multi-station assembly machines
- 3. Single-station assembly cells
- 4. Partial automation

