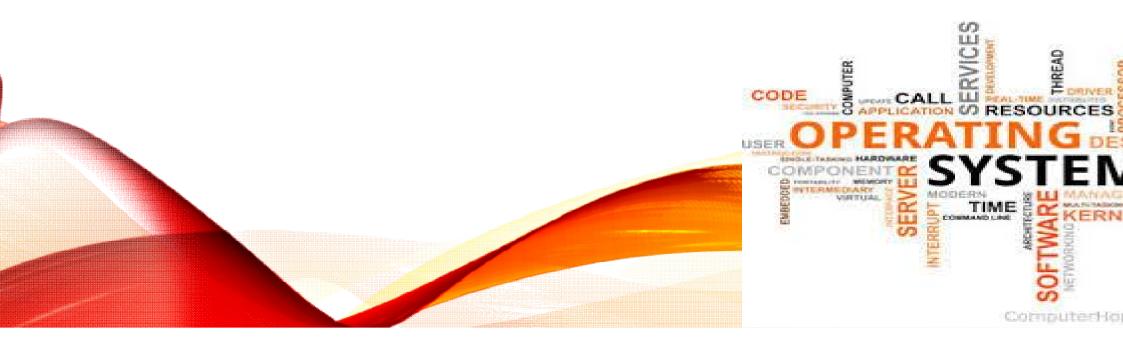
# UNIT I

Operating

Systems

# INTRODUCTION



# Introduction

- Introduction
  - What Operating Systems Do
  - Computer-System Architecture
  - Operating-System Structure
  - Operating-System Operations
  - Operating-System Services
  - User Operating System Interface
  - System Calls
  - Types of System Calls
  - System Programs
  - System Boot

- Process Concept
  - Process Scheduling
  - Operations on Processes
  - Interprocess Communication

### **Process Concept**

- An operating system executes a variety of programs:
  - Batch system **jobs**

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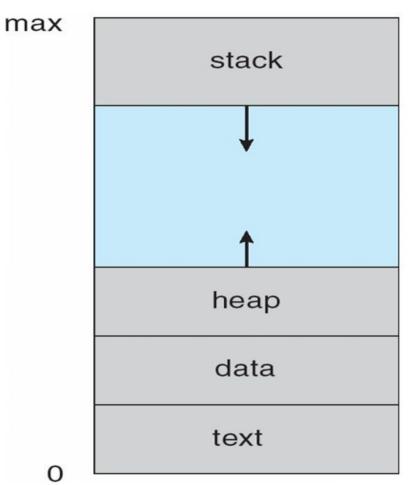
- Time-shared systems user programs or tasks
- Textbook uses the terms *job* and *process* almost interchangeably
- Process a program in execution; process execution must progress in sequential fashion
- Multiple parts
  - The program code, also called text section
  - Current activity including program counter, processor registers
  - Stack containing temporary data
    - Function parameters, return addresses, local variables
  - Data section containing global variables
  - Heap containing memory dynamically allocated during run time

## Process Concept (Cont.)

- Program is *passive* entity stored on disk (executable file), process is *active* 
  - Program becomes process when executable file loaded into memory
- Execution of program started via GUI mouse clicks, command line entry of its name, etc
- One program can be several processes
  - Consider multiple users executing the same program

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### **Process in Memory**

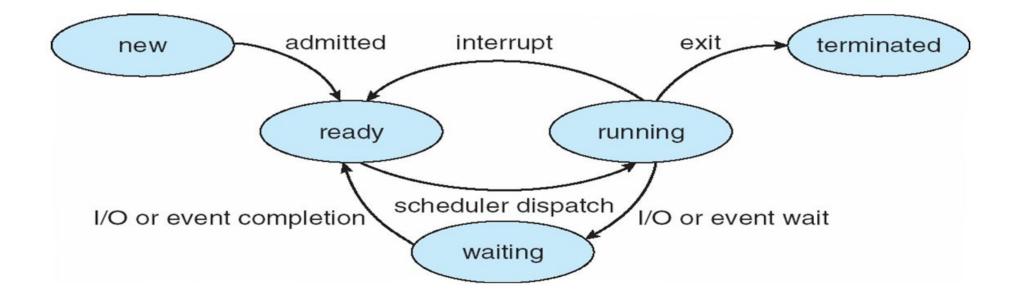




#### **Process State**

- As a process executes, it changes state
  - **new**: The process is being created
  - **running**: Instructions are being executed
  - waiting: The process is waiting for some event to occur
  - **ready**: The process is waiting to be assigned to a processor
  - terminated: The process has finished execution





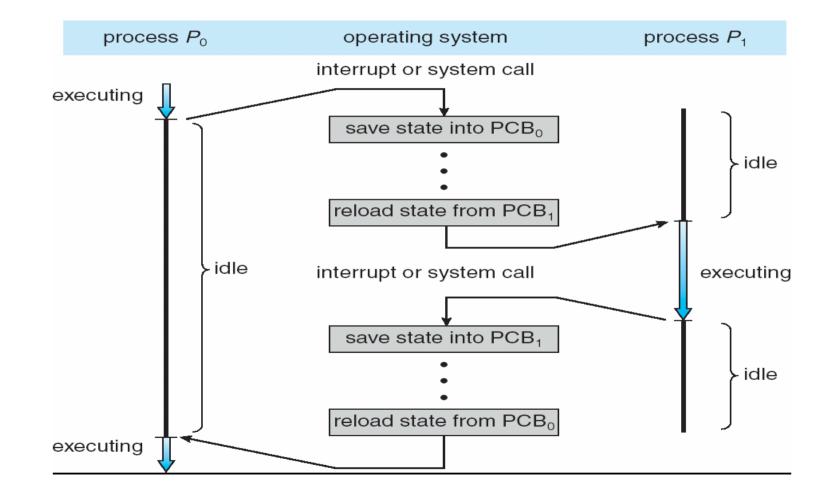
## Process Control Block (PCB)

information associated with each process

(also called task control block)

- Process state running, waiting, etc
- Program counter location of instruction to next execute
- CPU registers contents of all process-centric registers
- CPU scheduling information- priorities, scheduling queue pointers
- Memory-management information memory allocated to the process
- Accounting information CPU used, clock time elapsed since start, time limits
- I/O status information I/O devices allocated to process, list of open files

### **CPU Switch From Process to Process**





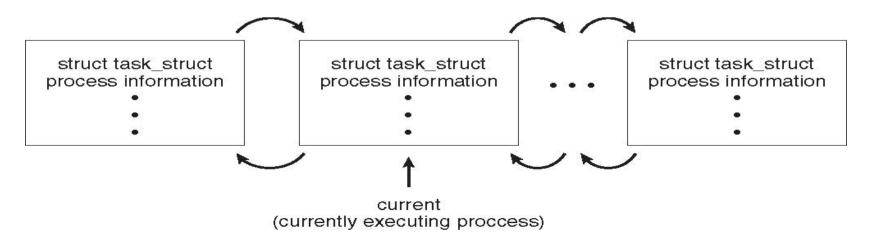
- So far, process has a single thread of execution
- Consider having multiple program counters per process
  - Multiple locations can execute at once
    - Multiple threads of control -> threads
- Must then have storage for thread details, multiple program counters in PCB

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#### Represented by the C structure task\_struct

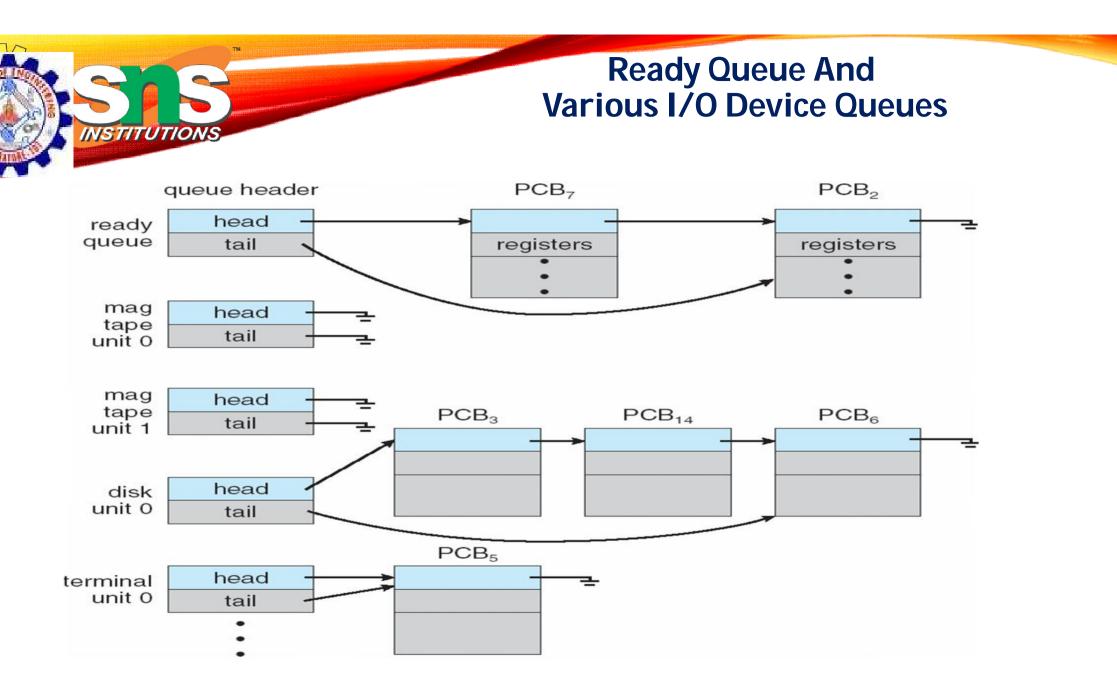
pid t\_pid; /\* process identifier \*/ long state; /\* state of the process \*/ unsigned int time\_slice /\* scheduling information \*/ struct task\_struct \*parent; /\* this process's parent \*/ struct list\_head children; /\* this process's children \*/ struct files\_struct \*files; /\* list of open files \*/ struct mm struct \*mm; /\* address space of this process \*/



### **Process Scheduling**

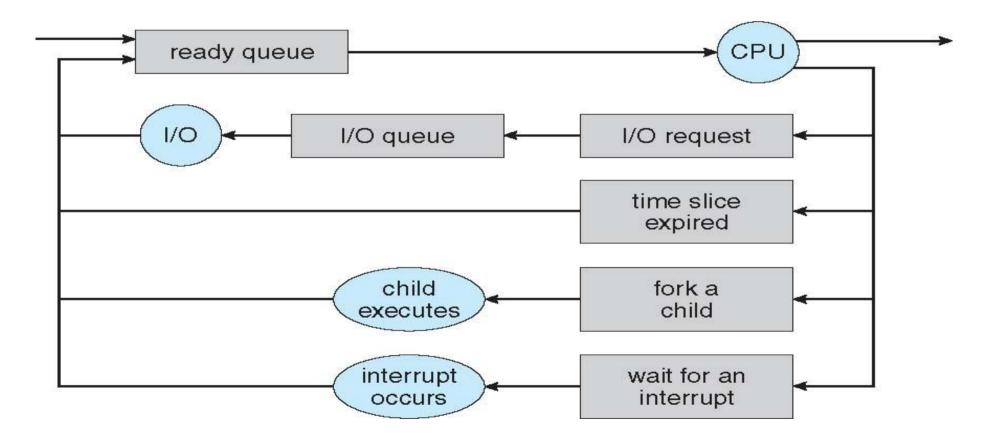
- Maximize CPU use, quickly switch processes onto CPU for time sharing
- Process scheduler selects among available processes for next execution on CPU
- Maintains scheduling queues of processes
  - Job queue set of all processes in the system
  - Ready queue set of all processes residing in main memory, ready and waiting to execute
  - **Device queues** set of processes waiting for an I/O device
  - Processes migrate among the various queues

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#### **Representation of Process Scheduling**

Queueing diagram represents queues, resources, flows



### **Schedulers**

 Short-term scheduler (or CPU scheduler) – selects which process should be executed next and allocates CPU

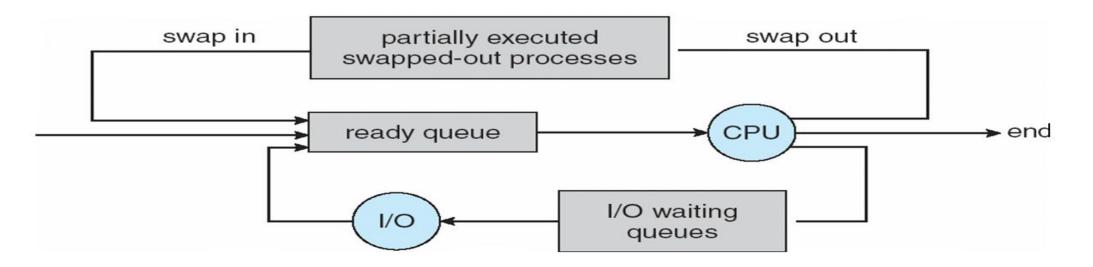
- Sometimes the only scheduler in a system
- Short-term scheduler is invoked frequently (milliseconds)  $\Rightarrow$  (must be fast)
- Long-term scheduler (or job scheduler) selects which processes should be brought into the ready queue
  - Long-term scheduler is invoked infrequently (seconds, minutes)  $\Rightarrow$  (may be slow)
  - The long-term scheduler controls the degree of multiprogramming



- Processes can be described as either:
  - I/O-bound process spends more time doing I/O than computations, many short CPU bursts
  - CPU-bound process spends more time doing computations; few very long CPU bursts
- Long-term scheduler strives for good *process mix*



- Medium-term scheduler can be added if degree of multiple programming needs to decrease
  - Remove process from memory, store on disk, bring back in from disk to continue execution: swapping





#### Due to screen real estate, user interface limits iOS provides for a

- Single foreground process- controlled via user interface
- Multiple background processes- in memory, running, but not on the display, and with limits
- Android runs foreground and background, with fewer limits
  - Background process uses a **service** to perform tasks
  - Service can keep running even if background process is suspended
  - Service has no user interface, small memory use



- When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process via a context switch
- **Context** of a process represented in the PCB
- Context-switch time is overhead; the system does no useful work while switching
  - The more complex the OS and the PCB → the longer the context switch
- Time dependent on hardware support
  - Some hardware provides multiple sets of registers per CPU → multiple contexts loaded at once



- System must provide mechanisms for:
  - process creation,
  - process termination,
  - and so on as detailed next



**Process Creation** 

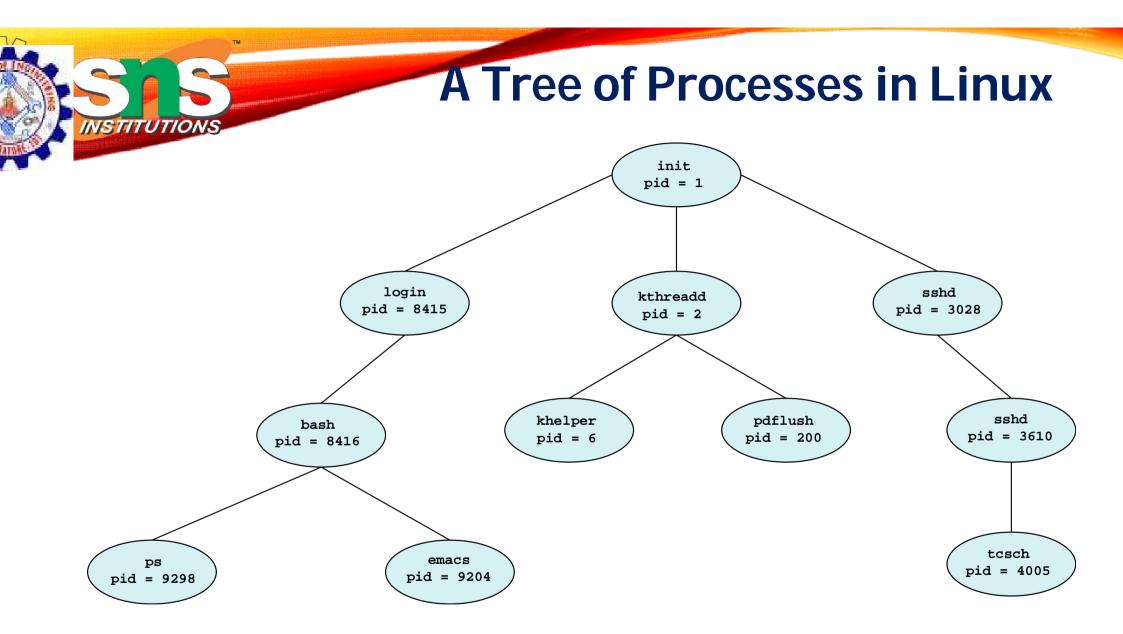
• Generally, process identified and managed via a process identifier (pid)

#### Resource sharing options

- Parent and children share all resources
- Children share subset of parent's resources
- Parent and child share no resources

#### • Execution options

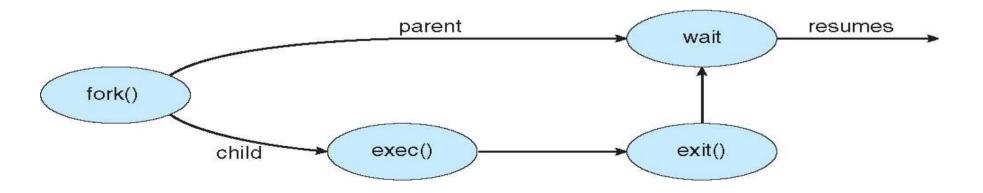
- Parent and children execute concurrently
- Parent waits until children terminate



## **Process Creation (Cont.)**

Address space

- Child duplicate of parent
- Child has a program loaded into it
- UNIX examples
  - fork() system call creates new process
  - **exec()** system call used after a **fork()** to replace the process' memory space with a new program



```
C Program
                           Forking Separate Process
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                #include <sys/types.h>
                #include <stdio.h>
                #include <unistd.h>
                int main()
                pid_t pid;
                   /* fork a child process */
                   pid = fork();
                   if (pid < 0) { /* error occurred */
                      fprintf(stderr, "Fork Failed");
                      return 1;
                    else if (pid == 0) { /* child process */
                      execlp("/bin/ls","ls",NULL);
                    }
                   else { /* parent process */
                      /* parent will wait for the child to complete */
                      wait(NULL);
                      printf("Child Complete");
                    }
                   return 0;
                }
```

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- Process executes last statement and then asks the operating system to delete it using the exit() system call.
  - Returns status data from child to parent (via **wait()**)
  - Process' resources are deallocated by operating system
- Parent may terminate the execution of children processes using the **abort()** system call. Some reasons for doing so:
  - Child has exceeded allocated resources
  - Task assigned to child is no longer required
  - The parent is exiting and the operating systems does not allow a child to continue if its parent terminates

### **Process Termination**

• Some operating systems do not allow child to exists if its parent has terminated.

If a process terminates, then all its children must also be terminated.

- cascading termination. All children, grandchildren, etc. are terminated.
- The termination is initiated by the operating system.
- The parent process may wait for termination of a child process by using the wait() system call. The call returns status information and the pid of the terminated process

pid = wait(&status);

- If no parent waiting (did not invoke wait()) process is a zombie
- If parent terminated without invoking wait, process is an orphan

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- 1. Abraham Silberschatz, Peter B. Galvin, "Operating System Concepts", 10<sup>th</sup> Edition, John Wiley & Sons, Inc., 2018.
- 2. Jane W. and S. Liu. "Real-Time Systems". Prentice Hall of India 2018.
- 3. Andrew S Tanenbaum, Herbert Bos, Modern Operating Pearson, 2015.

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- 1. William Stallings, "Operating Systems: Internals and Design Principles",9<sup>th</sup> Edition, Prentice Hall of India., 2018.
- 2. D.M.Dhamdhere, "Operating Systems: A Concept based Approach", 3<sup>rd</sup>Edition, Tata McGraw hill 2016.
- 3. P.C.Bhatt, "An Introduction to Operating Systems–Concepts and Practice", 4<sup>th</sup> Edition, Prentice Hall of India., 2013.

#### THANK YOU