

### **SNS COLLEGE OF TECHNOLOGY** (AN AUTONOMOUS INSTITUTION)

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# **Department of Biomedical Engineering**

### **Course Name: Control Systems**

**III Year : V Semester** 

**Unit II – Time Response Analysis** 

**Topic : Root Locus** 

**19B**MT301/CS/Dr.R.Karthick/HoD/BME







## Introduction

- The Root locus is the locus of the roots of the characteristic • varying system gain K from zero to infinity.
- We know that, the characteristic equation of the closed loop control system is ٠

1+G(s)H(s)=0

The points on the root locus branches satisfy the angle condition. So, the ٠ angle condition is used to know whether the point exist on root locus branch or not. We can find the value of K for the points on the root locus branches by using magnitude condition.

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### equation by



## Introduction

Characteristic equation of closed loop control system is ٠

1+G(s)H(s)=0

$$\Rightarrow$$
G(s)H(s)=-1+j0 ion Tit 2

The phase angle of G(s)H(s)G(s)H(s) is •

 $\angle G(s)H(s)=tan^{-1}(0/1)=(2n+1)\pi$ 

• The angle condition is the point at which the angle of the open loop transfer function is an odd multiple of 180°.

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### Introduction

• Magnitude of G(s)H(s)G(s)H(s) is –

## |G(s)H(s)| = 1

• The magnitude condition is that the point (which satisfied the angle condition) at which the magnitude of the open loop transfer function is one.

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