



# **SNS COLLEGE OF TECHNOLOGY**

## **(AN AUTONOMOUS INSTITUTION)**

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## **Department of Biomedical Engineering**

**Course Name: Control Systems**

**III Year : V Semester**

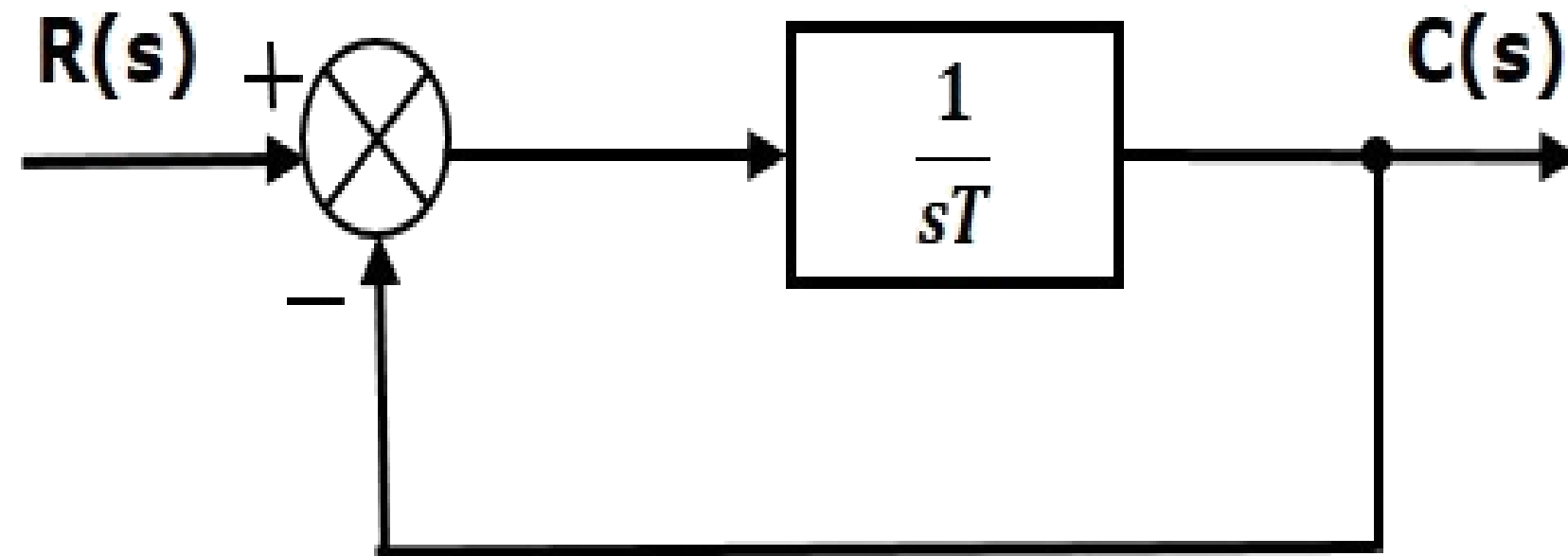
**Unit II -Time Response**

**Topic : First Order System**



## Introduction

- Consider the following block diagram of the closed loop control system.
- Here, an open loop transfer function,  $1/sT$  is connected with a unity negative feedback. The system is called as first order system





## First Order Response

- The closed loop transfer function of the system is given by

$$\frac{C(s)}{R(s)} = \frac{G(s)}{1 + G(s)}$$

Vision Title 3

- Substituting the transfer function for first order system in above equation

$$\frac{C(s)}{R(s)} = \frac{\frac{1}{sT}}{1 + \frac{1}{sT}} = \frac{1}{sT + 1}$$

$$R(s) = \frac{1}{s}$$



## First Order Response

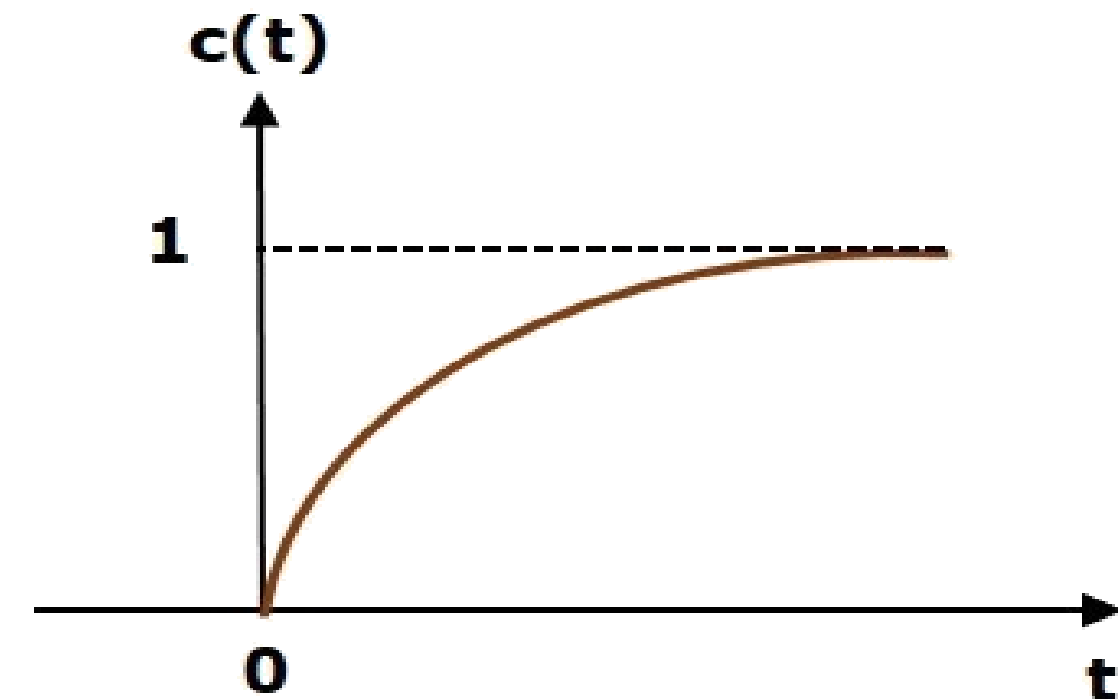
$$C(s) = \left( \frac{1}{sT + 1} \right) \left( \frac{1}{s} \right) = \frac{1}{s(sT + 1)}$$

$$C(s) = \frac{1}{s(sT + 1)} = \frac{A}{s} + \frac{B}{sT + 1}$$

$$C(s) = \frac{1}{s} - \frac{T}{sT + 1} = \frac{1}{s} - \frac{T}{T(s + \frac{1}{T})}$$

Applying Laplace inverse transform

$$c(t) = \left( 1 - e^{-\left(\frac{t}{T}\right)} \right)$$



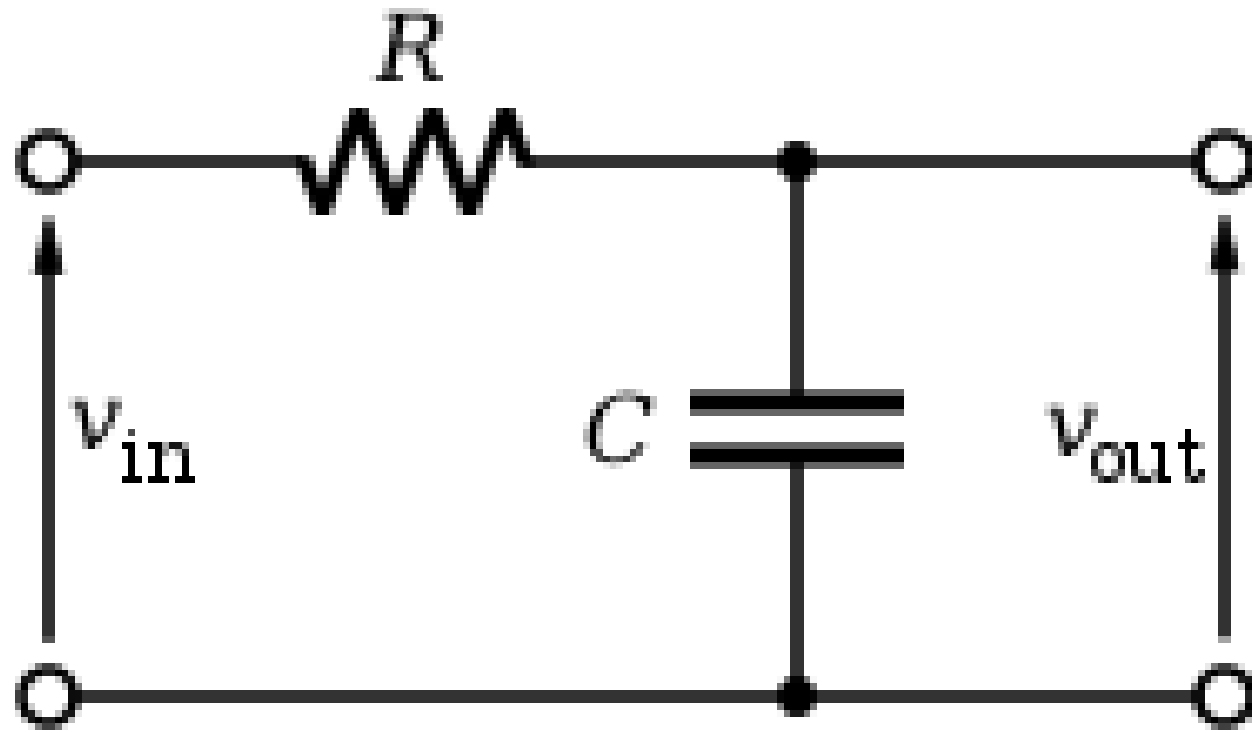
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# Practical Example



A first-order RC filter:



$$\frac{dV_{out}}{dt} = \frac{1}{RC} (V_{in} - V_{out})$$

$$\frac{V_{OUT}}{V_{IN}} = \frac{1}{1 + sRC}$$

Unit step response of an RC filter with time constant  $\tau = RC$

