



**SNS COLLEGE OF TECHNOLOGY
COIMBATORE-35
DEPARTMENT OF ECE**



19ECB231 – Digital Electronics

2 MARK QUESTIONS AND ANSWERS

UNIT - I

MINIMIZATION TECHNIQUES AND LOGIC GATES

1. Write the names of basic logical operators.

1. NOT / INVERT

2. AND

3. OR

2. What are basic properties of Boolean algebra?

The basic properties of Boolean algebra are commutative property, associative property and distributive property.

3. State the associative property of boolean algebra.

The associative property of Boolean algebra states that the OR ing of several variables results in the same regardless of the grouping of the variables. The associative property is stated as follows:

$$A + (B + C) = (A + B) + C$$

4. State the commutative property of Boolean algebra.

The commutative property states that the order in which the variables are OR ed makes no difference. The commutative property is: $A + B = B + A$

5. State the distributive property of Boolean algebra.

The distributive property states that AND ing several variables and OR ing the result with a single variable is equivalent to OR ing the single variable with each of the the several variables and then AND ing the sums. The distributive property is:

$$A+BC=(A+B)(A+C)$$

6. State the absorption law of Boolean algebra.

The absorption law of Boolean algebra is given by $X+XY=X$, $X(X+Y)=X$.

7. State De Morgan's theorem.

De Morgan suggested two theorems that form important part of Boolean algebra. They are,

1) The complement of a product is equal to the sum of the complements.

$$(AB)' = A' + B'$$

2) The complement of a sum term is equal to the product of the complements. $(A + B)' = A'B'$

8. Reduce $A.A'C$

$$A.A'C = 0.C [A.A' = 1]$$

$$= 0$$

9. Reduce $A(A + B)$

$$A(A + B) = AA + AB$$

$$= A(1 + B) [1 + B = 1]$$

$$= A.$$

10. Reduce $A'B'C' + A'BC' + A'BC$

$$A'B'C' + A'BC' + A'BC = A'C'(B' + B) + A'B'C$$

$$= A'C' + A'BC [A + A' = 1]$$

$$= A'(C' + BC)$$

$$= A'(C' + B) [A + A'B = A + B]$$

11. Reduce $AB + (AC)' + AB'C(AB + C)$

$$AB + (AC)' + AB'C(AB + C) = AB + (AC)' + AAB'BC + AB'CC$$

$$= AB + (AC)' + AB'CC [A.A' = 0]$$

$$= AB + (AC)' + AB'C [A.A = 1]$$

$$= AB + A' + C' = AB'C [(AB)' = A' + B']$$

$$= A' + B + C' + AB'C [A + AB' = A + B]$$

$$= A' + B'C + B + C' [A + A'B = A + B]$$

$$= A' + B + C' + B'C$$

$$= A' + B + C' + B'$$

$$= A' + C' + 1$$

$$= 1 [A + 1 = 1]$$

12. Simplify the following expression $Y = (A + B)(A + C')(B' + C')$

$$Y = (A + B)(A + C')(B' + C')$$

$$= (AA' + AC + A'B + BC)(B' + C') [A.A' = 0]$$

$$= (AC + A'B + BC)(B' + C')$$

$$= AB'C + ACC' + A'BB' + A'BC' + BB'C + BCC'$$

$$= AB'C + A'BC'$$

13. Show that $(X + Y' + XY)(X + Y')(X'Y) = 0$

$$(X + Y' + XY)(X + Y')(X'Y) = (X + Y' + X)(X + Y')(X' + Y) [A + A'B = A + B]$$

$$= (X + Y')(X + Y')(X'Y) [A + A = 1]$$

$$= (X + Y')(X'Y) [A.A = 1]$$

$$= X.X' + Y'.X'.Y$$

$$= 0 [A.A' = 0]$$

14. Prove that $ABC + ABC' + AB'C + A'BC = AB + AC + BC$

$$ABC + ABC' + AB'C + A'BC = AB(C + C') + AB'C + A'BC$$

$$= AB + AB'C + A'BC$$

$$= A(B + B'C) + A'BC$$

$$= A(B + C) + A'BC$$

$$= AB + AC + A'BC$$

$$= B(A + C) + AC$$

$$= AB + BC + AC$$

$$= AB + AC + BC \dots \text{Proved}$$

15. Convert the given expression in canonical SOP form $Y = AC + AB + BC$

$$Y = AC + AB + BC$$

$$= AC(B + B') + AB(C + C') + (A + A')BC$$

$$= ABC + ABC' + AB'C + AB'C' + ABC + ABC' + ABC$$

$$=ABC + ABC' + AB'C + AB'C' [A + A = 1]$$

16. Define duality property.

Duality property states that every algebraic expression deducible from the postulates of Boolean algebra remains valid if the operators and identity elements are interchanged. If the dual of an algebraic expression is desired, we simply interchange OR and AND operators and replace 1's by 0's and 0's by 1's.

17. Find the complement of the functions $F1 = x'yz' + x'y'z$ and $F2 = x(y'z' + yz)$. By applying De-Morgan's theorem.

$$F1' = (x'yz' + x'y'z)' = (x'yz')'(x'y'z)' = (x + y' + z)(x + y + z')$$

$$F2' = [x(y'z' + yz)]' = x' + (y'z' + yz)'$$

$$= x' + (y'z')(yz)'$$

$$= x' + (y + z)(y' + z')$$

18. Simplify the following expression

$$Y = (A + B) (A = C) (B + C)$$

$$= (A A + A C + A B + B C) (B + C)$$

$$= (A C + A B + B C) (B + C)$$

$$= A B C + A C C + A B B + A B C + B B C + B C C$$

$$= A B C$$

19. What are the methods adopted to reduce Boolean function?

i) Karnaugh map

ii) Tabular method or QuineMc-Cluskey method iii) Variable entered map technique.

20.State the limitations of karnaugh map.

i) Generally it is limited to six variable map (i.e) more than six variable involving expression are not reduced.

ii) The map method is restricted in its capability since they are useful for simplifying only Boolean expression represented in standard form.

21. What is a karnaugh map?

A karnaugh map or k map is a pictorial form of truth table, in which the map diagram is made up of squares, with each squares representing one minterm of the function.

22. Find the minterms of the logical expression $Y = A'B'C' + A'B'C + A'BC + ABC'$

$$Y = A'B'C' + A'B'C + A'BC + ABC'$$

$$=m_0 + m_1 + m_3 + m_6$$

$$= _m(0, 1, 3, 6)$$

23. Write the maxterms corresponding to the logical expression

$$Y = (A + B + C')(A + B' + C')(A' + B' + C)$$

$$= (A + B + C')(A + B' + C')(A' + B' + C)$$

$$=M_1.M_3.M_6$$

$$= _M(1,3,6)$$

24. What are called don't care conditions?

In some logic circuits certain input conditions never occur, therefore the corresponding output never appears. In such cases the output level is not defined, it can be either high or low. These output levels are indicated by 'X' or 'd' in the truth tables and are called don't care conditions or incompletely specified functions.

25. What is a prime implicant?

A prime implicant is a product term obtained by combining the maximum possible number of adjacent squares in the map.

26. What is an essential implicant?

If a min term is covered by only one prime implicant, the prime implicant is said to be essential

27. What is a Logic gate?

Logic gates are the basic elements that make up a digital system. The electronic gate is a circuit that is able to operate on a number of binary inputs in order to perform a particular logical function.

28. Give the classification of logic families

Bipolar Unipolar

Saturated Non Saturated PMOS NMOS

CMOS

RTL Schottky TTL ECL DTL

29. What are the basic digital logic gates?

The three basic logic gates are

AND gate OR gate NOT gate

30. Which gates are called as the universal gates? What are its advantages?

The NAND and NOR gates are called as the universal gates. These gates are used to perform any type of logic application.

31. Classify the logic family by operation?

The Bipolar logic family is classified into

Saturated logic

Unsaturated logic.

The RTL, DTL, TTL, I²L, HTL logic comes under the saturated logic family. The Schottky TTL, and ECL logic comes under the unsaturated logic family.

32.State the classifications of FET devices.

FET is classified as

1. Junction Field Effect Transistor (JFET)
2. Metal oxide semiconductor family (MOS).

33. Mention the classification of saturated bipolar logic families.

The bipolar logic family is classified as follows: RTL- Resistor Transistor Logic

DTL- Diode Transistor logic I²L- Integrated Injection Logic TTL- Transistor Transistor Logic ECL- Emitter Coupled Logic

34.Mention the different IC packages?

DIP- Dual in line package

LCC- Leadless Chip Carrier

PLCC- Plastic Leaded Chip carrier PQFP- Plastic Quad Flat Pack PGA- Pin Grid Array

35. Mention the important characteristics of digital IC's?

Fan out

Power dissipation Propagation Delay Noise Margin

Fan In

Operating temperature

Power supply requirements

UNIT - II COMBINATIONAL CIRCUITS

PART-A (2 MARKS)

1. Define combinational logic

When logic gates are connected together to produce a specified output for certain specified combinations of input variables, with no storage involved, the resulting circuit is called combinational logic.

2. Explain the design procedure for combinational circuits

The problem definition

Determine the number of available input variables & required O/P variables. Assigning letter symbols to I/O variables

Obtain simplified Boolean expression for each O/P.

Obtain the logic diagram.

3. Define Half adder and full adder

The logic circuit that performs the addition of two bits is a half adder. The circuit that performs the addition of three bits is a full adder.

4. Define Decoder?

A decoder is a multiple - input multiple output logic circuit that converts coded inputs into coded outputs where the input and output codes are different.

5. What is binary decoder?

A decoder is a combinational circuit that converts binary information from n input lines to a maximum of 2^n outputs lines.

6. Define Encoder?

An encoder has 2^n input lines and n output lines. In encoder the output lines generate the binary code corresponding to the input value.

7. What is priority Encoder?

A priority encoder is an encoder circuit that includes the priority function. In priority encoder, if 2 or more inputs are equal to 1 at the same time, the input having the highest priority will take precedence.

8. Define multiplexer?

Multiplexer is a digital switch. It allows digital information from several sources to be routed onto a single output line.

9. What do you mean by comparator

A comparator is a special combinational circuit designed primarily to compare the relative magnitude of two binary numbers.

9. List basic types of programmable logic devices.

- . Read only memory
- . Programmable logic Array
- . Programmable Array Logic

10. Define ROM

Read only memory is a device that includes both the decoder and the OR gates within a single IC package.

11. Define address and word:

In a ROM, each bit combination of the input variable is called an address. Each bit combination that comes out of the output lines is called a word.

12. State the types of ROM

- . Masked ROM.

- . Programmable Read only Memory
- . Erasable Programmable Read only memory.
- . Electrically Erasable Programmable Read only Memory.

13. What is programmable logic array? How it differs from ROM?

In some cases the number of don't care conditions is excessive, it is more economical to use a second type of LSI component called a PLA. A PLA is similar to a ROM in concept; however it does not provide full decoding of the variables and does not generate all the minterms as in the ROM.

14. Which gate is equal to AND-invert Gate?

NAND gate.

15. Which gate is equal to OR-invert Gate?

NOR gate.

16. Bubbled OR gate is equal to-----

NAND gate

17. Bubbled AND gate is equal to-----

UNIT -III SEQUENTIAL CIRCUITS

PART-A (2 MARKS)

1. What are the classification of sequential circuits?

The sequential circuits are classified on the basis of timing of their signals into two types. They are,

1) Synchronous sequential circuit.

2) Asynchronous sequential circuit.

2. Define Flip flop.

The basic unit for storage is flip flop. A flip-flop maintains its output state either at 1 or 0 until directed by an input signal to change its state.

3. What are the different types of flip-flop?

There are various types of flip flops. Some of them are mentioned below they are,

ü RS flip-flop

ü SR flip-flop

ü D flip-flop

ü JK flip-flop

ü T flip-flop

4. What is the operation of RS flip-flop?

ü When R input is low and S input is high the Q output of flip-flop is set.

ü When R input is high and S input is low the Q output of flip-flop is reset.

ü When both the inputs R and S are low the output does not change

ü When both the inputs R and S are high the output is unpredictable.

5. What is the operation of SR flip-flop?

ü When R input is low and S input is high the Q output of flip-flop is set.

ü When R input is high and S input is low the Q output of flip-flop is reset.

ü When both the inputs R and S are low the output does not change.

ü When both the inputs R and S are high the output is unpredictable.

6. What is the operation of D flip-flop?

In D flip-flop during the occurrence of clock pulse if $D=1$, the output Q is set and if

$D=0$, the output is reset.

7. What is the operation of JK flip-flop?

Ø When K input is low and J input is high the Q output of flip-flop is set.

Ø When K input is high and J input is low the Q output of flip-flop is reset.

Ø When both the inputs K and J are low the output does not change

Ø When both the inputs K and J are high it is possible to set or reset the flip-flop (ie) the output toggle on the next positive clock edge.

8. What is the operation of T flip-flop?

T flip-flop is also known as Toggle flip-flop.

Ø When $T=0$ there is no change in the output.

Ø When $T=1$ the output switch to the complement state (ie) the output toggles.

9. Define race around condition.

In JK flip-flop output is fed back to the input. Therefore change in the output change in the input. Due to this in the positive half of the clock pulse if both J and K are high then output toggles continuously. This condition is called 'race around condition'.

10. What is edge-triggered flip-flop?

The problem of race around condition can solved by edge triggering flip flop. The term edge triggering means that the flip-flop changes state either at the positive edge or negative edge of the clock pulse and it is sensitive to its inputs only at this transition of the clock.

11. What is a master-slave flip-flop?

A master-slave flip-flop consists of two flip-flops where one circuit serves as a master and the other as a slave.

12. Define rise time.

The time required to change the voltage level from 10% to 90% is known as rise time (t_r).

13. Define fall time.

The time required to change the voltage level from 90% to 10% is known as fall time (t_f).

14. Define skew and clock skew.

The phase shift between the rectangular clock waveforms is referred to as skew and the time delay between the two clock pulses is called clock skew.

15. Define setup time.

The setup time is the minimum time required to maintain a constant voltage levels at the excitation inputs of the flip-flop device prior to the triggering edge of the clock pulse in order for the levels to be reliably clocked into the flip flop. It is denoted as setup.

16. Define hold time.

The hold time is the minimum time for which the voltage levels at the excitation inputs must remain constant after the triggering edge of the clock pulse in order for the levels to be reliably clocked into the flip flop. It is denoted as thold.

17. Define propagation delay.

A propagation delay is the time required to change the output after the application of the input.

18. Define registers.

A register is a group of flip-flops flip-flop can store one bit information. So an n-bit register has a group of n flip-flops and is capable of storing any binary information/ number containing n-bits.

19. Define shift registers.

The binary information in a register can be moved from stage to stage within the register or into or out of the register upon application of clock pulses. This type of bit movement or shifting is essential for certain arithmetic and logic operations used in microprocessors. This gives rise to group of registers called shift registers.

20. What are the different types of shift type?

There are five types. They are,

Ø Serial In Serial Out Shift Register

Ø Serial In Parallel Out Shift Register

Ø Parallel In Serial Out Shift Register

Ø Parallel In Parallel Out Shift Register

Ø Bidirectional Shift Register

21. Explain the flip-flop excitation tables for RS FF.

RS flip-flop

In RS flip-flop there are four possible transitions from the present state to the next state. They are,

Ø 0_0 transition: This can happen either when $R=S=0$ or when $R=1$ and $S=0$.

Ø 0_1 transition: This can happen only when $S=1$ and $R=0$.

Ø 1_0 transition: This can happen only when $S=0$ and $R=1$.

Ø 1_1 transition: This can happen either when $S=1$ and $R=0$ or $S=0$ and $R=0$.

22. Explain the flip-flop excitation tables for JK flip-flop

In JK flip-flop also there are four possible transitions from present state to next state.

They are,

Ø 0_0 transition: This can happen when $J=0$ and $K=1$ or $K=0$.

Ø 0_1 transition: This can happen either when $J=1$ and $K=0$ or when $J=K=1$.

Ø 1_0 transition: This can happen either when $J=0$ and $K=1$ or when $J=K=1$.

Ø 1_1 transition: This can happen when $K=0$ and $J=0$ or $J=1$.

23. Explain the flip-flop excitation tables for D flip-flop

In D flip-flop the next state is always equal to the D input and it is independent of the present state. Therefore D must be 0 if Q_{n+1} has to be 0, and if Q_{n+1} has to be 1 regardless the value of Q_n .

24. Explain the flip-flop excitation tables for T flip-flop

When input $T=1$ the state of the flip-flop is complemented; when $T=0$, the state of the flip-flop remains unchanged. Therefore, for 0_0 and 1_1 transitions T must be 0 and for 0_1 and 1_0 transitions must be 1.

25. Define sequential circuit?

In sequential circuits the output variables dependent not only on the present input variables but they also depend up on the past history of these input variables.

26. Give the comparison between combinational circuits and sequential circuits.

∅ Combinational circuits Sequential circuits

∅ Memory unit is not required Memory unity is required

∅ Parallel adder is a combinational circuit Serial adder is a sequential circuit

27. What do you mean by present state?

The information stored in the memory elements at any given time defines the present state of the sequential circuit.

28. What do you mean by next state?

The present state and the external inputs determine the outputs and the next state of the sequential circuit.

29. State the types of sequential circuits?

1. Synchronous sequential circuits
2. Asynchronous sequential circuits

30. Define synchronous sequential circuit

In synchronous sequential circuits, signals can affect the memory elements only at discrete instant of time.

31. Define Asynchronous sequential circuit?

In asynchronous sequential circuits change in input signals can affect memory element at any instant of time.

32. Give the comparison between synchronous & Asynchronous sequential circuits?

Synchronous sequential circuits Asynchronous sequential circuits.

Memory elements are clocked flip-flops Memory elements are either unlocked flip - flops or time delay elements.

Easier to design More difficult to design

33. Define flip-flop

Flip - flop is a sequential device that normally samples its inputs and changes its outputs only at times determined by clocking signal.

34. Draw the logic diagram for SR latch using two NOR gates.

35. The following wave forms are applied to the inputs of SR latch. Determine the

Q waveform Assume initially $Q = 1$

Here the latch input has to be pulsed momentarily to cause a change in the latch output state, and the output will remain in that new state even after the input pulse is over.

36. What is race around condition?

In the JK latch, the output is feedback to the input, and therefore changes in the output results change in the input. Due to this in the positive half of the clock pulse if J and K are both high then output toggles continuously. This condition is known as race around condition.

37. What are the types of shift register?

1. Serial in serial out shift register?
2. Serial in parallel out shift register
3. Parallel in serial out shift register
4. Parallel in parallel out shift register
5. Bidirectional shift register shift register

38. State the types of counter?

1. Synchronous counter
2. Asynchronous Counter

39. Give the comparison between synchronous & Asynchronous counters.

Asynchronous counters

Ø In this type of counter flip-flops are connected in such a way that output of 1st flip-flop drives the clock for the next flipflop.

Ø All the flip-flops are Not clocked Simultaneously Synchronous counters

Ø In this type there is no connection between output of first flip-flop and clock input of the next flip - flop

Ø All the flip-flops are clocked simultaneously

40. The t_{pd} for each flip-flop is 50 ns. Determine the maximum operating frequency for MOD - 32 ripple counter

$$f_{\max}(\text{ripple}) = 5 \times 50 \text{ ns} = 4 \text{ MHZ}$$

UNIT-IV MEMORY DEVICES PART-A (2 MARKS)

1. What is meant by ROM?

A read only memory(ROM) is a device that includes both the decoder and the OR gates within a single IC package. It consists of n input lines and m output lines. Each bit combination of the input variables is called an address. Each bit combination that comes out of the output lines is called a word. The number of distinct addresses possible with n input variables is 2^n .

2. What are the types of ROM?

1.PROM

2.EPROM

3.EEPROM

3. Explain PROM.

PROM (Programmable Read Only Memory)

It allows user to store data or program. PROMs use the fuses with material like nichrome and polycrystalline. The user can blow these fuses by passing around 20 to 50 mA of current for the period 5 to 20 μ s. The blowing of fuses is called programming of ROM. The PROMs are one time programmable. Once programmed, the information is stored permanent.

4. Explain EPROM.

EPROM(Erasable Programmable Read Only Memory)

EPROM use MOS circuitry. They store 1's and 0's as a packet of charge in a buried layer of the IC chip. We can erase the stored data in the EPROMs by exposing the chip to ultraviolet light via its quartz window for 15 to 20 minutes. It is not possible to erase selective information. The chip can be reprogrammed.

5. Explain EEPROM.

EEPROM(Electrically Erasable Programmable Read Only Memory) EEPROM also use MOS circuitry. Data is stored as charge or no charge on an insulated layer or an insulated floating gate in the device. EEPROM allows selective erasing at the register level rather than erasing all the information since the information can be changed by using electrical signals.

6. What is RAM?

Random Access Memory. Read and write operations can be carried out.

7. Define ROM

A read only memory is a device that includes both the decoder and the OR gates within a single IC package.

8. Define address and word:

In a ROM, each bit combination of the input variable is called on address. Each bit combination that comes out of the output lines is called a word.

9. What are the types of ROM.

1. Masked ROM.
2. Programmable Read only Memory
3. Erasable Programmable Read only memory.
4. Electrically Erasable Programmable Read only Memory.

10. What is programmable logic array? How it differs from ROM?

In some cases the number of don't care conditions is excessive, it is more economical to use a second type of LSI component called a PLA. A PLA is similar to a ROM in concept; however it does not provide full decoding of the variables and does not generate all the minterms as in the ROM.

11. What is mask - programmable?

With a mask programmable PLA, the user must submit a PLA program table to the manufacturer.

12. What is field programmable logic array?

The second type of PLA is called a field programmable logic array. The user by means of certain recommended procedures can program the EPLA.

13. List the major differences between PLA and PAL

PLA:

Both AND and OR arrays are programmable and Complex

Costlier than PAL

AND arrays are programmable OR arrays are fixed

Cheaper and Simpler

14. Define PLD.

Programmable Logic Devices consist of a large array of AND gates and OR gates that can be programmed to achieve specific logic functions.

15. Give the classification of PLDs.

PLDs are classified as PROM(Programmable Read Only Memory), Programmable Logic Array(PLA), Programmable Array Logic (PAL), and Generic Array Logic(GAL)

16. Define PROM.

PROM is Programmable Read Only Memory. It consists of a set of fixed AND gates connected to a decoder and a programmable OR array.

17. Define PLA

PLA is Programmable Logic Array(PLA). The PLA is a PLD that consists of a programmable AND array and a programmable OR array.

18. Define PAL

PAL is Programmable Array Logic. PAL consists of a programmable AND array and a fixed OR array with output logic.

19. Why was PAL developed?

It is a PLD that was developed to overcome certain disadvantages of PLA, such as longer delays due to additional fusible links that result from using two programmable arrays and more circuit complexity.

20. Define GAL

GAL is Generic Array Logic. GAL consists of a programmable AND array and a fixed OR array with output logic.

21. Give the feature of flash memory.

The ideal memory has high storage capacity, non-volatility; in-system read and write capability, comparatively fast operation. The traditional memory technologies such as ROM, PROM, EEPROM individually exhibits one of these characteristics, but no single technology has all of them except the flash memory.

22. What are Flash memories?

They are high density read/write memories that are non-volatile, which means data can be stored indefinitely with out power.

23. List the three major operations in a flash memory.

Programming, Read and Erase operation

24. What is a FIFO memory?

The term FIFO refers to the basic operation of this type of memory in which the first data bit written into the memory is to first to be read out.

25. List basic types of programmable logic devices.

1. Read only memory
2. Programmable logic Array
3. Programmable Array Logic

26. Define ROM

A read only memory is a device that includes both the decoder and the OR gates Within a single IC package.

27. Define address and word:

In a ROM, each bit combination of the input variable is called on address. Each bit combination that comes out of the output lines is called a word.

28. What are the types of ROM?

1. Masked ROM.
2. Programmable Read only Memory
3. Erasable Programmable Read only memory.
4. Electrically Erasable Programmable Read only Memory.

29. What is programmable logic array? How it differs from ROM?

In some cases the number of don't care conditions is excessive, it is more economical to use a second type of LSI component called a PLA. A PLA is similar to a ROM in concept; however it does not provide full decoding of the variables and does not generates all the minterms as in the ROM.

30. What is mask - programmable?

With a mask programmable PLA, the user must submit a PLA PLA program table to the manufacturer.

31. Give the comparison between PROM and PLA.

PROM PLA

1. And array is fixed and OR Both AND and OR arrays are array is programmable. Programmable.
2. Cheaper and simple to use. Costliest and complex than PROMS.

32. Give the feature of UV EPROM

UV EPROM is electrically programmable by the user, but the store data must be erased by exposure to ultra violet light over a period of several minutes.

33. Why the input variables to a PAL are buffered

The input variables to a PAL are buffered to prevent loading by the large number of AND gate inputs to which available or its complement can be connected.

34. What does PAL 10L8 specify?

PAL - Programmable Logic Array

10 - Ten inputs

L - Active LOW Ouput

8 - Eight Outputs

35. What is CPLD?

CPLDs are Complex Programmable Logic Devices. They are larger versions of PLDs with a centralized internal interconnect matrix used to connect the device macro cells together.

36. Define bit, byte and word.

The smallest unit of binary data is bit. Data are handled in a 8 bit unit called byte. A complete unit of information is called a word which consists of one or more bytes.

37. How many words can a 16x8 memory can store?

A 16x8 memory can store 16,384 words of eight bits each

38. Define address of a memory.

The location of a unit of data in a memory is called address.

39. Define Capacity of a memory.

It is the total number of data units that can be stored.

40. What is Read and Write operation?

The Write operation stores data into a specified address into the memory and the

Read operation takes data out of a specified address in the memory.

41. Why RAMs are called as Volatile?

RAMs are called as Volatile memories because RAMs lose stored data when the power is turned OFF.

42. Define ROM.

ROM is a type of memory in which data are stored permanently or semi permanently. Data can be read from a ROM, but there is no write operation

43. Define RAM.

RAM is Random Access Memory. It is a random access read/write memory. The data can be read or written into from any selected address in any sequence.

44. List the two categories of RAMs.

The two categories of RAMs are static RAM (SRAM) and dynamic RAM (DRAM).

45. Define Static RAM and dynamic RAM

Static RAM use flip flops as storage elements and therefore store data indefinitely as long as dc power is applied.

Dynamic RAMs use capacitors as storage elements and cannot retain data very long without capacitors being recharged by a process called refreshing.

46. List the two types of SRAM

Asynchronous SRAMs and Synchronous Burst SRAMs

47. List the basic types of DRAMs

Fast Page Mode DRAM, Extended Data Out DRAM(EDO DRAM),Burst EDO DRAM and Synchronous DRAM.

48. Define a bus

A bus is a set of conductive paths that serve to interconnect two or more functional components of a system or several diverse systems.

49. Define Cache memory

It is a relatively small, high-speed memory that can store the most recently used instructions or data from larger but slower main memory.

50. What is the technique adopted by DRAMs.

DRAMs use a technique called address multiplexing to reduce the number of address lines.

UNIT-V PART-A (2 MARKS)

1. What are secondary variables?

∅ present state variables in asynchronous sequential circuits

2. What are excitation variables?

∅ -next state variables in asynchronous sequential circuits

3. What is fundamental mode sequential circuit?

Input variables changes if the circuit is stable inputs are levels, not pulses only one input can change at a given time

4. What are pulse mode circuit?

Inputs are pulses width of pulses are long for circuit to respond to the input pulse width must not be so long that it is still present after the new state is reached

5. What is the significance of state assignment?

∅ In synchronous circuits-state assignments are made with the objective of circuit reduction

∅ Asynchronous circuits-its objective is to avoid critical races

6. When do race condition occur?

∅ two or more binary state variables change their value in response to the change in i/p variable

7. What is non critical race?

∅ final stable state does not depend on the order in which the state variable changes

∅ race condition is not harmful

8. What is critical race?

∅ final stable state depends on the order in which the state variable changes

∅ race condition is harmful

9. When does a cycle occur?

∅ asynchronous circuit makes a transition through a series of unstable state

10. What are the different techniques used in state assignment?

∅ shared row state assignment

∅ one hot state assignment

11. What are the steps for the design of asynchronous sequential circuit?

∅ construction of primitive flow table

∅ reduction of flow table

∅ state assignment is made

∅ realization of primitive flow table

12. What is hazard?

∅ unwanted switching transients

13. What is static 1 hazard?

∅ output goes momentarily 0 when it should remain at 1

14. What is static 0 hazard?

∅ output goes momentarily 1 when it should remain at 0

15. What is dynamic hazard?

∅ output changes 3 or more times when it changes from 1 to 0 or 0 to 1

16. What is the cause for essential hazards?

∅ unequal delays along 2 or more path from same input

17. What is flow table?

∅ state table of an synchronous sequential network

18. What is SM chart?

∅ describes the behavior of a state machine

∅ used in hardware design of digital systems

19. What are the advantages of SM chart?

∅ easy to understand the operation

∅ east to convert to several equivalent forms

20. What is primitive flow chart?

∅ one stable state per row

21. What is combinational circuit?

∅ Output depends on the given input. It has no storage element.

22. What is state equivalence theorem ?

Two states SA and SB, are equivalent if and only if for every possible input X

sequence, the outputs are the same and the next states are equivalent i.e., if $SA(t+1) = SB(t+1)$ and $Z_A = Z_B$ then $SA = SB$.

23. What do you mean by distinguishing sequences?

Two states, SA and SB of sequential machine are distinguishable if and only if their exists at least one finite input sequence. Which, when applied to sequential machine causes different output sequences depending on whether SA or SB is the initial state.

24. Prove that the equivalence partition is unique

Consider that there are two equivalence partitions exists : PA and PB, and $PA \neq PB$. This states that, there exist 2 states S_i & S_j which are in the same block of one partition and

not in the same block of the other. If S_i & S_j are in different blocks of say PB, there exists at least one input sequence which distinguishes S_i & S_j and therefore, they cannot be in the same block of PA.

25. Define compatibility

States S_i and S_j said to be compatible states, if and only if for every input sequence that affects the two states, the same output sequence, occurs whenever both outputs are specified and regardless of whether S_i or S_j is the initial state.

26. Define merger graph.

The merger graph is defined as follows. It contains the same number of vertices as the state table contains states. A line drawn between the two state vertices indicates each compatible state pair. If two states are incompatible no connecting line is drawn.

27. Define incompatibility

The states are said to be incompatible if no line is drawn in between them. If implied states are incompatible, they are crossed & the corresponding line is ignored.

28. Explain the procedure for state minimization.

1. Partition the states into subsets such that all states in the same subsets are 1 - equivalent.
2. Partition the states into subsets such that all states in the same subsets are 2 - equivalent.
3. Partition the states into subsets such that all states in the same subsets are 3 - equivalent.

29. Define closed covering

A Set of compatibles is said to be closed if, for every compatible contained in the set, all its implied compatibles are also contained in the set. A closed set of compatibles, which contains all the states of M, is called a closed covering.

30. Define machine equivalence

Two machines, M1 and M2 are said to be equivalent if and only if, for every state in M1, there is a corresponding equivalent state in M2 & vice versa.

31. Define state table.

For the design of sequential counters we have to relate present states and next states. The table, which represents the relationship between present states and next states, is called state table.

32. Define total state

The combination of level signals that appear at the inputs and the outputs of the delays define what is called the total state of the circuit.

33. What are the steps for the design of asynchronous sequential circuit?

1. Construction of a primitive flow table from the problem statement.
2. Primitive flow table is reduced by eliminating redundant states using the state reduction
3. State assignment is made
4. The primitive flow table is realized using appropriate logic elements.

34. Define primitive flow table:

It is defined as a flow table which has exactly one stable state for each row in the table. The design process begins with the construction of primitive flow table.

35. What are the types of asynchronous circuits ?

1. Fundamental mode circuits
2. Pulse mode circuits

36. Give the comparison between state Assignment Synchronous circuit and state assignment asynchronous circuit.

In synchronous circuit, the state assignments are made with the objective of circuit reduction. In asynchronous circuits, the objective of state assignment is to avoid critical races.

37. What are races?

When 2 or more binary state variables change their value in response to a change in an input variable, race condition occurs in an asynchronous sequential circuit. In case of unequal delays, a race condition may cause the state variables to change in an unpredictable manner.

38. Define non critical race.

If the final stable state that the circuit reaches does not depend on the order in which the state variable changes, the race condition is not harmful and it is called a non critical race.

39. Define critical race?

If the final stable state depends on the order in which the state variable changes, the race condition is harmful and it is called a critical race.

40. What is a cycle?

A cycle occurs when an asynchronous circuit makes a transition through a series of unstable states. If a cycle does not contain a stable state, the circuit will go from one unstable to stable to another, until the inputs are changed.

41. List the different techniques used for state assignment.

1. Shared row state assignment
2. One hot state assignment.

42. Write a short note on fundamental mode asynchronous circuit.

Fundamental mode circuit assumes that. The input variables change only when the circuit is stable. Only one input variable can change at a given time and inputs are levels and not pulses.

43. Write a short note on pulse mode circuit.

Pulse mode circuit assumes that the input variables are pulses instead of level. The width of the pulses is long enough for the circuit to respond to the input and the pulse width must not be so long that it is still present after the new state is reached.

44. Define secondary variables

The delay elements provide a short term memory for the sequential circuit. The present state and next state variables in asynchronous sequential circuits are called secondary variables.

45. Define flow table in asynchronous sequential circuit.

In asynchronous sequential circuit state table is known as flow table because of the behaviour of the asynchronous sequential circuit. The stage changes occur independent of a clock, based on the logic propagation delay, and cause the states to flow. from one to another.

46. What is fundamental mode.

A transition from one stable state to another occurs only in response to a change in the input state. After a change in one input has occurred, no other change in any input occurs until the circuit enters a stable state. Such a mode of operation is referred to as a fundamental mode.

47. Write short note on shared row state assignment.

Races can be avoided by making a proper binary assignment to the state variables. Here, the state variables are assigned with binary numbers in such a way that only one state variable can change at any one state variable can change at any one time when a state transition occurs. To accomplish this, it is necessary that states between which transitions occur be given adjacent assignments. Two binary are said to be adjacent if they differ in only one variable.

48. Write short note on one hot state assignment.

The one hot state assignment is another method for finding a race free state assignment. In this method, only one variable is active or hot for each row in the original flow table, ie, it requires one state variable for each row of the flow table. Additional row are introduced to provide single variable changes between internal state transitions.