



THE STRUCTURE OF AGENTS

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- Agent Program:

It implements the agent function mapping percepts to actions

- Architecture:

Agent program will run on some sort of computing device with physical sensors called architecture.

Agent=architecture+program

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- ⊙ Agent programs:
 - The agent programs take the current percept as input from the sensors and return an action to the actuators.
 - The agent program takes just the current percept as input because nothing more is available from the environment.
 - If the agent's actions depend on the entire percept sequence, the agent will have to remember the percepts.

CONTINUE...

- ◉ Four kinds of agent programs:
 - Simple reflex agents
 - Model based reflex agents
 - Goal-based agents
 - Utility based agents

SIMPLE REFLEX AGENTS

- These are simplest kind of agents that select actions on the basis of current percept, ignoring the rest of the percept history.
- The agent program for a simple reflex agent in 2 state vacuum environment is as follows

```
function Reflex-Vacuum-Agent( [location,status])  
  returns an action
```

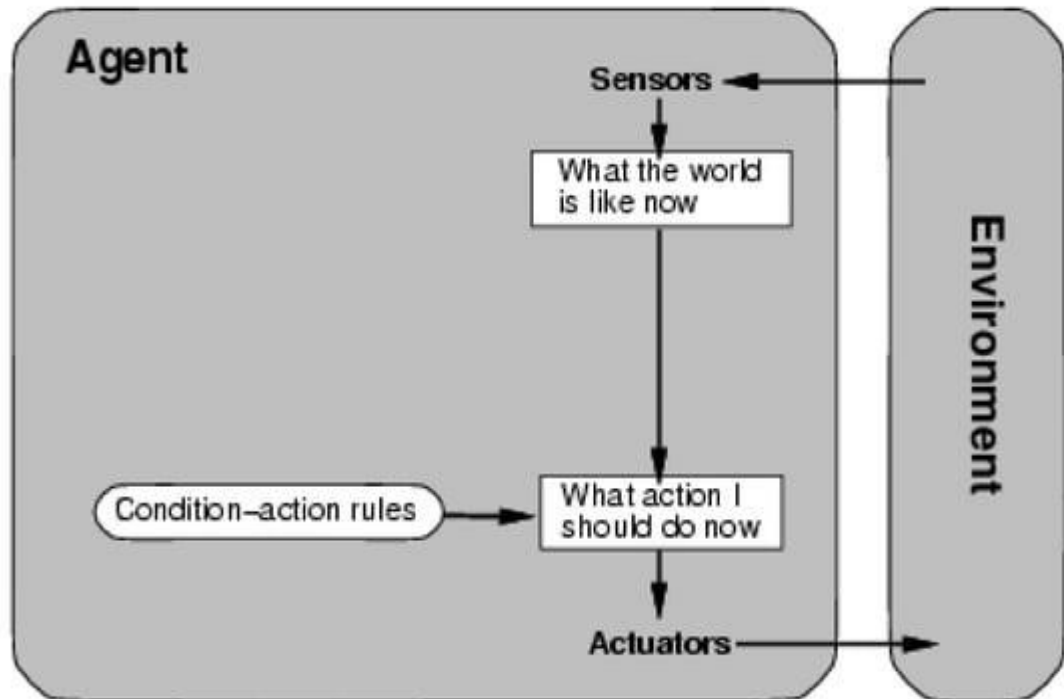
```
if status = Dirty then return Suck
```

```
else if location = A then return Right
```

```
else if location = B then return Left
```

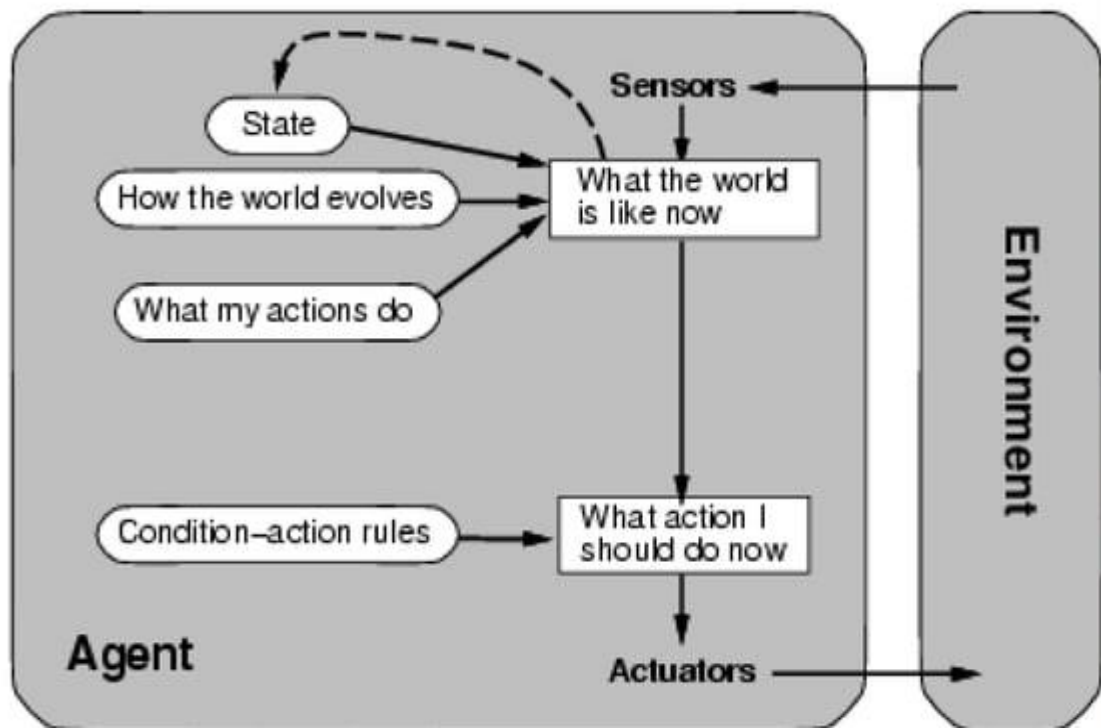
SIMPLE REFLEX AGENTS

FIG: SCHEMATIC DIAGRAM OF A SIMPLEX REFLEX AGENT



- Infinite loops are often unavoidable for simple reflex agents operating in partially observable environments.
- Escape from infinite loops is possible if the agent can randomize its actions.

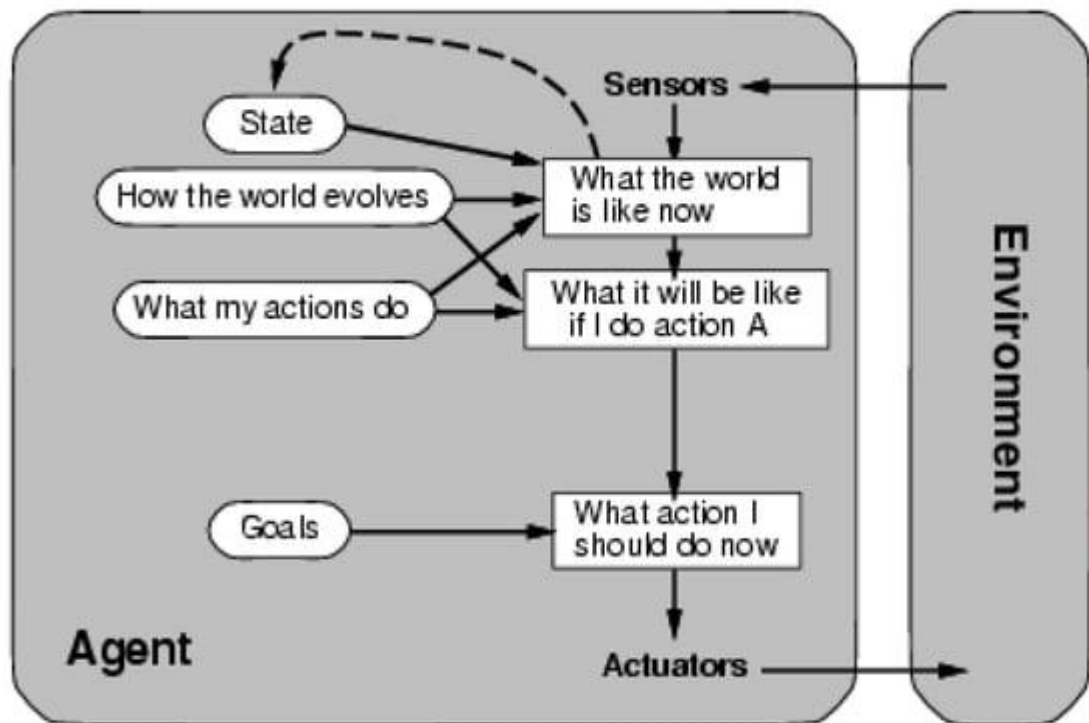
MODEL BASED REFLEX AGENTS



MODEL BASED REFLEX AGENTS

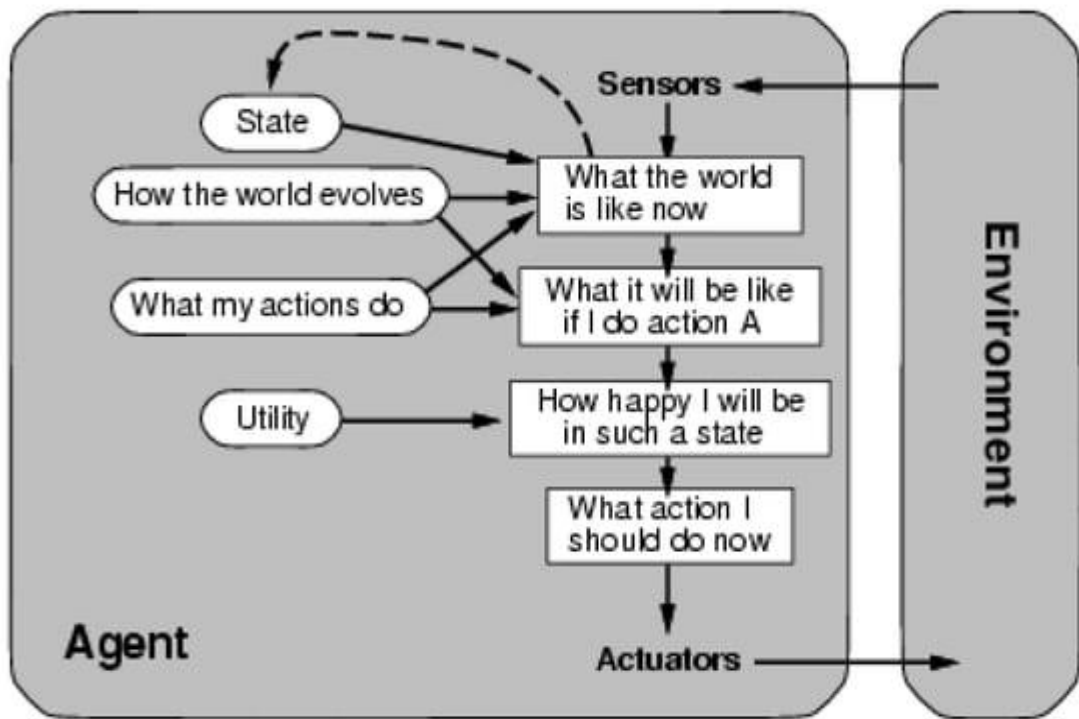
- ◉ The most effective way to handle partial observability is for the agent to keep track of the part of the world it can't see now.
- ◉ The agent should maintain some sort of internal state that depends on the percept history and thereby reflects at least some of the unobserved aspects of the current state
- ◉ **Model based agent**
- ◉ The knowledge about “how the world works” whether implemented in simple boolean circuits or in complete scientific theories is called model of the world.
- ◉ The agent that uses such a model is called a model-based agent

GOAL-BASED AGENTS



- ◉ Goal:
- ◉ The agent needs some sort of goal information that describes situations that are desirable.
- ◉ Example: being at the passenger's destination
- ◉ The agent program can combine this information about the results of possible actions in order to choose actions that achieve the goals.
- ◉ Search and planning are the subfields of AI devoted to finding action sequence that achieve the agent's goals.
- ◉ Although the goal-based agent appears less efficient, it is more flexible because the knowledge that supports its decisions is represented explicitly and can be modified.

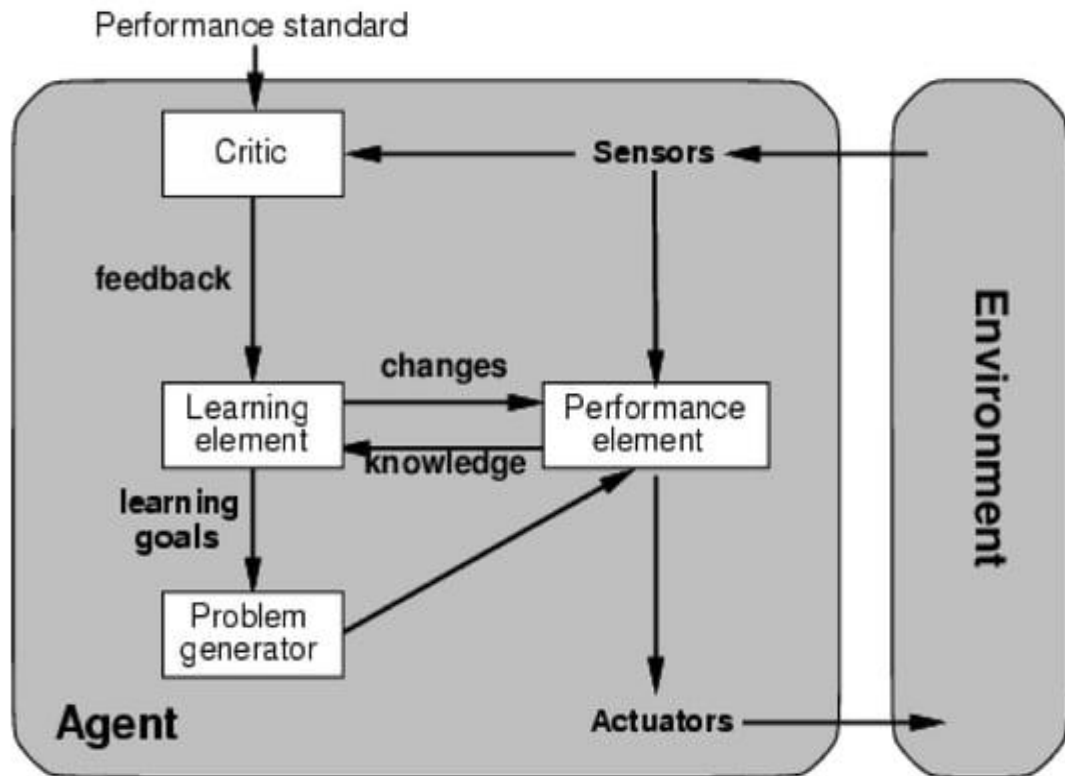
UTILITY BASED AGENTS



UTILITY BASED AGENTS

- ◉ Goals alone are not really enough to generate high-quality behavior in most environment.
- ◉ Utility-if one world state is preferred to another, then it has higher utility for the agent.
- ◉ Utility function
- ◉ It maps a state (or sequence of states) onto a real number, which describes the associated degree of happiness.
- ◉ A complete specification of the utility function allows rational decision in two kinds of cases where goals are inadequate.
- ◉ When there are conflicting goals, only some of which can be achieved, the utility function specifies appropriate tradeoff.
- ◉ When there are several goals that the agent can aim for utility provides a way in which the likelihood of success can be weighed up against the importance of the goals.

LEARNING AGENTS



LEARNING AGENTS

- ⊙ Method to build learning machines and then to teach them, which is used in many areas of AI for creating state-of-the-art systems.
- ⊙ Advantage ->it allows agent to operate in initially unknown environment and to become more competent than its initial knowledge alone might allow.
- ⊙ Conceptual components of learning agent
- ⊙ Learning element- responsible for making improvements.
- ⊙ Performance element-responsible for selecting external actions.
- ⊙ Critic-the learning element uses feedback from the critic on how the agent is doing and determines how the performance element should be modified to do better in the future.

- ⊙ Problem generator-responsible for suggesting actions that will lead to new and informative experiences.
- ⊙ The performance standard distinguishes part of the incoming percept as a reward(or penalty) that provides direct feedback on the quality of the agent's behavior
- ⊙ Example: hard-wired performance standards such as pain and hunger in animals can be understood in this way.