



# Homogeneous Coordinates

Computer Graphics

# Homogeneous Coordinates

To represent a 2-dimensional transformation as matrix multiplication, we represent each coordinate position  $(x,y)$  with homogeneous coordinate tuple  $(x_h, y_h, h)$ .

$$x_h = x/h$$

$$y_h = y/h$$

- A convenient choice is to set  $h=1$
- Each 2-D position is represented with homogeneous coordinates
- This allows us to represent all geometric transformation equations as matrix multiplication

# Translation matrix

Translation  $n$  :

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

or

$$\mathbf{P}' = \mathbf{T}(t_x, t_y) \mathbf{P}$$

## Rotation matrix

Rotation :

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

or

$$\mathbf{P}' = \mathbf{R}(\theta)\mathbf{P}$$

# Scaling Matrix

Scaling :

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

or

$$\mathbf{P}' = \mathbf{S}(s_x, s_y) \mathbf{P}$$

## Why we need Homogeneous Coordinates?

- ◆ One of the many purposes of using homogeneous coordinates is to capture the concept of infinity.
- ◆ If we don't use homogeneous coordinates, it would be difficult to design certain classes of very useful curves and surfaces. These curves and surfaces are very crucial in developing algorithms in computer vision, graphics, CAD, etc.
- ◆ We have seen that basic transformations can be expressed in matrix form. But many graphic application involve sequences of geometric transformations. Hence we need a general form of matrix to represent such transformations.