## SNS COLLEGE OF ENGINEERING

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# DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING 

COURSE NAME : 19EC513 - IMAGE PROCESSING AND COMPUTER VISION
III YEAR / V SEMESTER
Unit I- DIGITAL IMAGE FUNDAMENTALS AND
TRANSFORMS
Topic: SVD transform

## Singular Value Decomposition

- Handy mathematical technique that has application to many problems
- Given any $m \times n$ matrix $\mathbf{A}$, algorithm to find matrices $\mathbf{U}, \mathbf{V}$, and $\mathbf{W}$ such that
$\mathbf{A}=\mathbf{U W} \mathbf{V}^{\mathrm{T}}$
$\mathbf{U}$ is $m \times n$ and orthonormal
$\mathbf{W}$ is $n \times n$ and diagonal
$\mathbf{V}$ is $n \times n$ and orthonormal

- Treat as black box: code widely available In Matlab:
$[\mathrm{U}, \mathrm{W}, \mathrm{V}]=\operatorname{svd}(\mathrm{A}, 0)$
- The $w_{i}$ are called the singular values of $\mathbf{A}$
- If $\mathbf{A}$ is singular, some of the $w_{i}$ will be 0
- In general $\operatorname{rank}(\mathbf{A})=$ number of nonzero $w_{i}$
- SVD is mostly unique (up to permutation of singular values, or if some $w_{i}$ are equal)
- Application \#1: inverses
- $\mathrm{A}^{-1}=\left(\mathbf{V} \mathrm{T}_{)}-1 \mathbf{W}^{-1} \mathbf{U}^{-1}=\mathbf{V} \mathbf{w}^{-1} \mathbf{U}_{\mathbf{U}} \mathrm{T}\right.$
- Using fact that inverse $=$ transpose for orthogonal matrices
- Since $\mathbf{W}$ is diagonal, $\mathbf{W}^{-1}$ also diagonal with reciprocals of entries of $\mathbf{W}$

Singular Value Decomposition aka SVD is one of many matrix decomposition

Technique that decomposes a matrix into 3 sub-matrices namely $\mathrm{U}, \mathrm{S}, \mathrm{V}$ where U is the left eigenvector, S is a diagonal matrix of singular values and V is called the right eigenvector. We can reconstruct SVD of an image by using linalg.svd() method of NumPy module.

## Syntax:

linalg.svd(matrix, full_matrices=True, compute_uv=True, hermitian=False)

## Parameters:

1.matrix : A real or complex matrix of size $>2$.
2.full_matrices: If True the size of $u$ and $v$ matrices are $m \times n$, if False then the shape of $u$ and $v$ matrices are $m x k$, where $k$ is non-zero values only.
3.compute_uv: Takes in boolean value to compute $u$ and $v$ matrices along with $s$ matrix.
4.hermitian: By default matrix is assumed to be Hermitian if it contains real-values, this is used internally for efficiently computing the singular values.


## Output:



## Any Query????

Thank you......

