



Unit-1 STATICS OF PARTICLES

Topic-4

Vectorial Representation of Forces





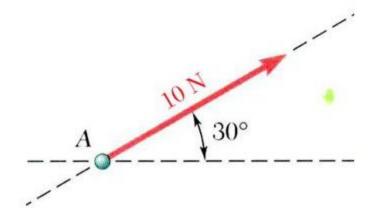
VECTORIAL REPRESENTATION OF FORCE

- The quantities which possess magnitude as well as direction are called as vector quantities.
- Symbol of vector 'P' is represented with an arrow such as
- Magnitude of vector is represented by or P.
- Free vector can be moved anywhere in space provided it maintains the same direction and magnitude.
- Sliding vector may be applied at any point along its line of action.
- Bound vector It will remain at the same point of application.
- Negative vector The negative of a vector P is the vector-P which has same magnitude & inclination but in opposite direction.

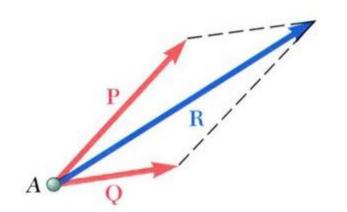




VECTORIAL REPRESENTATION OF FORCE



 force: action of one body on another; characterized by its point of application, magnitude, line of action, and sense.

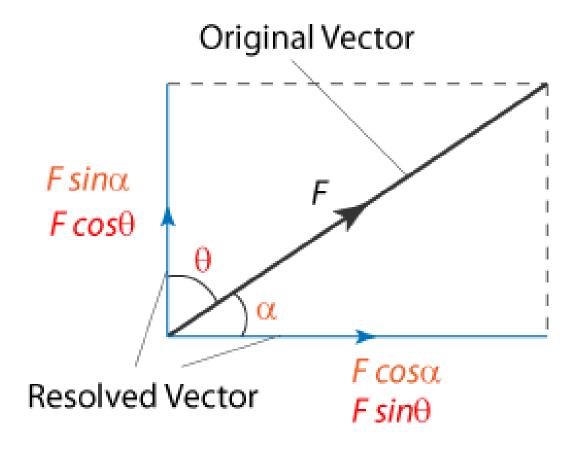


- Experimental evidence shows that the combined effect of two forces may be represented by a single resultant force.
- The resultant is equivalent to the diagonal of a parallelogram which contains the two forces in adjacent legs.
- Force is a vector quantity.





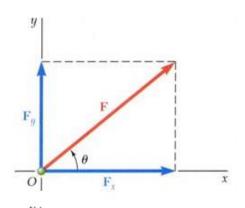
COMPONENTS OF FORCE

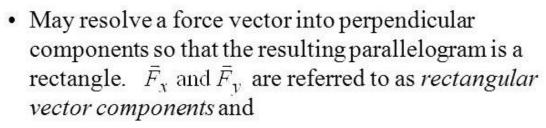




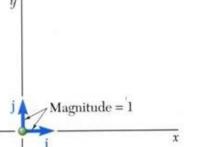


RECTANGULAR COMPONENTS OF A FORCE

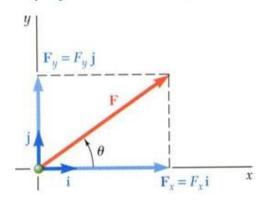




$$\vec{F} = \vec{F}_x + \vec{F}_y$$



• Define perpendicular *unit vectors* \vec{i} and \vec{j} which are parallel to the x and y axes.



 Vector components may be expressed as products of the unit vectors with the scalar magnitudes of the vector components.

$$\vec{F} = F_x \vec{i} + F_v \vec{j}$$

 F_x and F_y are referred to as the scalar components of \bar{F}