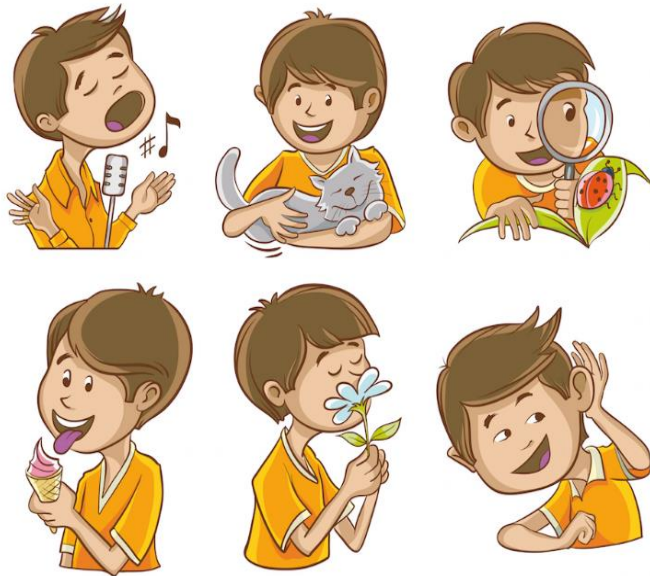




# SNS COLLEGE OF ENGINEERING

(Autonomous)

DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING



**Guess Today's Topic????**

**SENSORS, ACTUATORS AND SMART INSTRUMENTS/19SB404**





## Why Sensor



- conventional wall socket switchboards for switching on industrial appliances or home appliances such as fan, cooler, industrial motors, and so on
- it is very difficult to operate the switches regularly
- Automation developed for ease of controlling all the required electrical and electronics loads.
- This automation in a power system can be designed using various types of sensors and sensor circuits





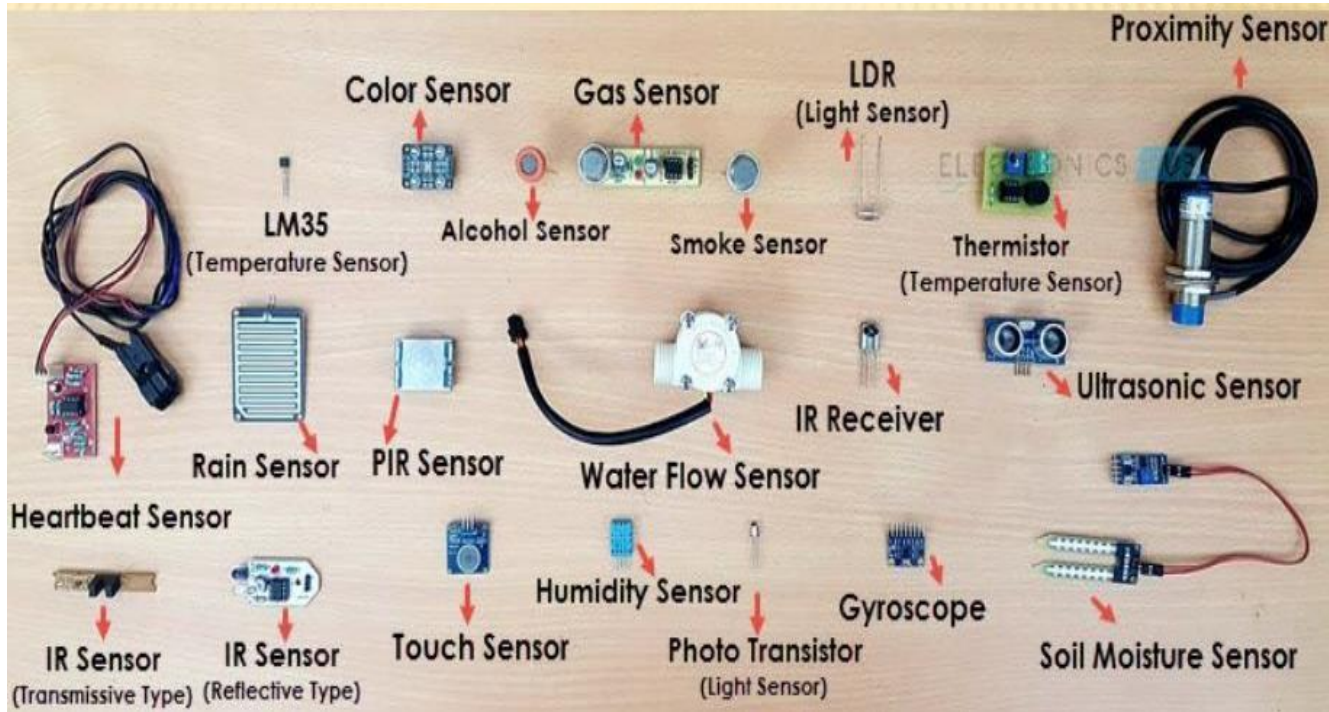
# Sensor



- Sensors are a part of everyday life at home and work
- A sensor is a device that can See, Feel, Hear, Smell, and even Taste.
- **A sensor can be defined as an appliance that detects changes in physical or electrical or other quantities and by this means, generally, produces an electrical or optical signal output as an acknowledgement of the change in that specific quantity.**
- In-process control, sensors are classified as
  - Passive** – requiring an external excitation to produce an electrical output
  - Active** – producing a voltage output without any external excitation



# Sensor Types

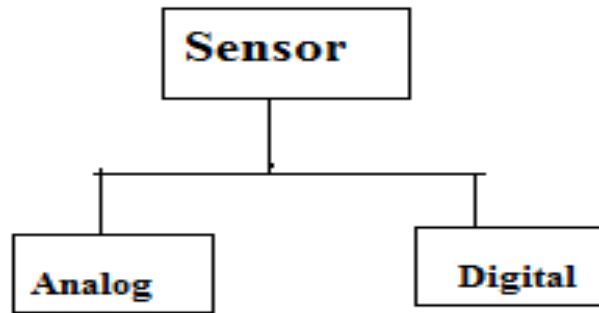


<https://youtu.be/XI49uFm5HRE>





# Sensor Types

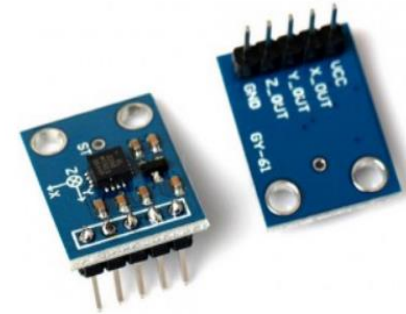


- **Analog:** produce continuous analog output signal and these sensors are considered as analog sensors. Output is proportional to measurement.
- various types of analog sensors are as follows: accelerometers, pressure sensors, light sensors, sound sensors, temperature sensors, and so on.



## **Accelerometers:**

- Analog sensors that detect changes in position, velocity, orientation, shock, vibration, and tilt by sensing motion are called as accelerometers.
- Its available in both analog and digital



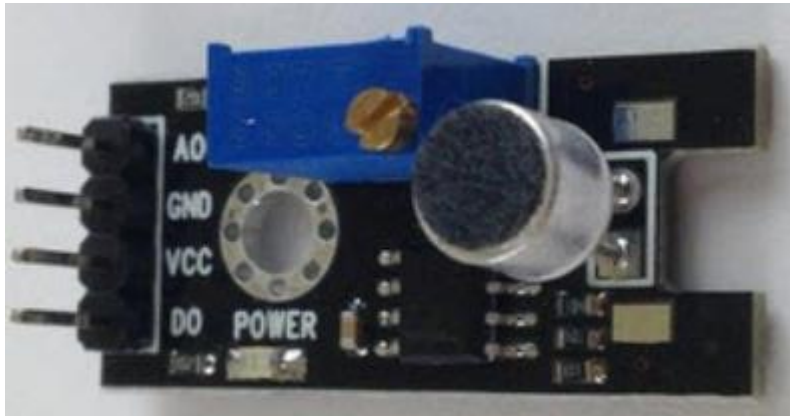
## **Light Sensors:**



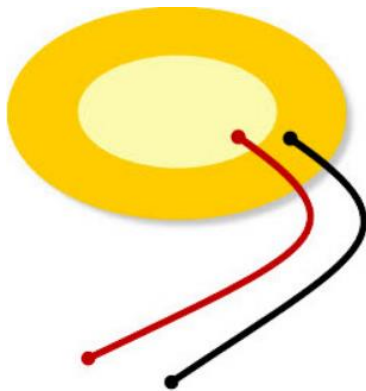
- Classified into various types like photo-resistor, Cadmium Sulfide (CdS), and photocell
- [Light dependent resistor](#) (LDR) can be used as analog light sensor



## Sound Sensors:



## Pressure Sensor:



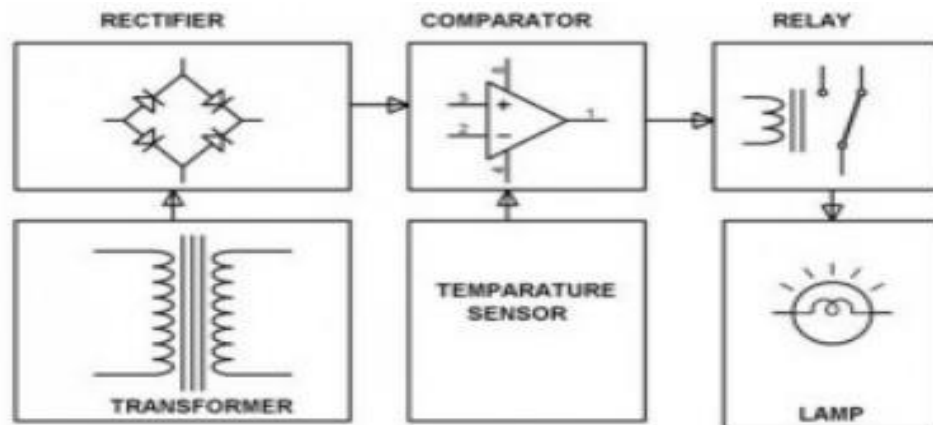
➤The analog sensors that are used to measure the amount of pressure applied to a sensor are called as analog pressure sensors.

➤Pressure sensor will produce an analog output signal that is proportional to the amount of applied pressure.



## Analog Temperature Sensor:

- Eg: Thermistor ,
- There are different types of thermistor that are used for different applications. Thermistor is a thermally sensitive resistor that is used for detecting changes in temperature.



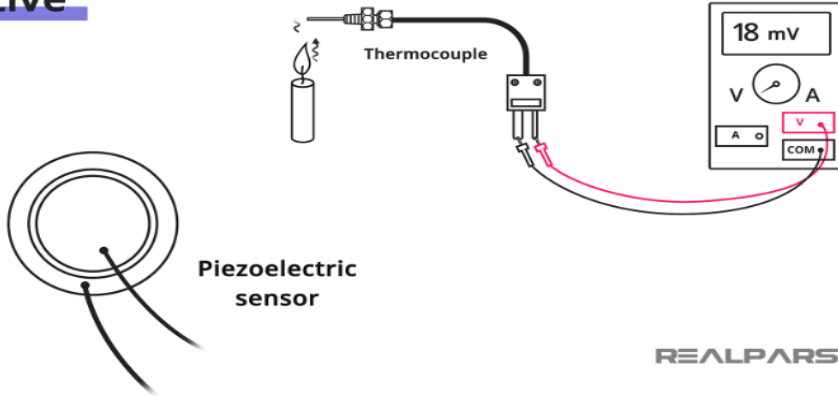
- Practical example of analog temperature sensor is thermistor based temperature control system.
- Maintain constant temperature in an enclosed area.





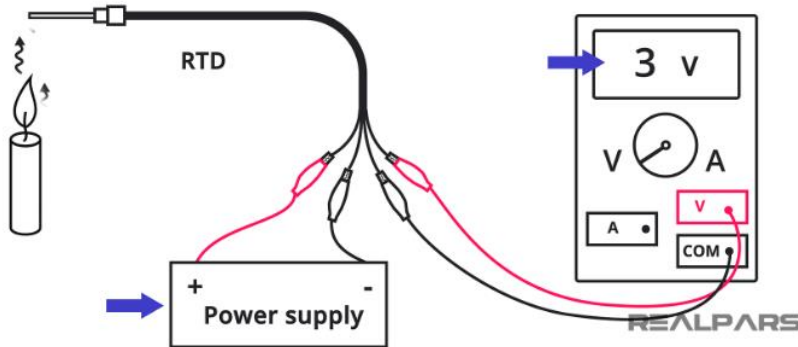
# Sensor

## Active



➤ Active – Eg: Thermocouple

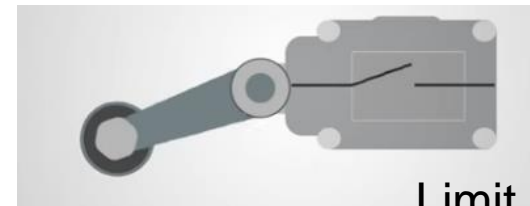
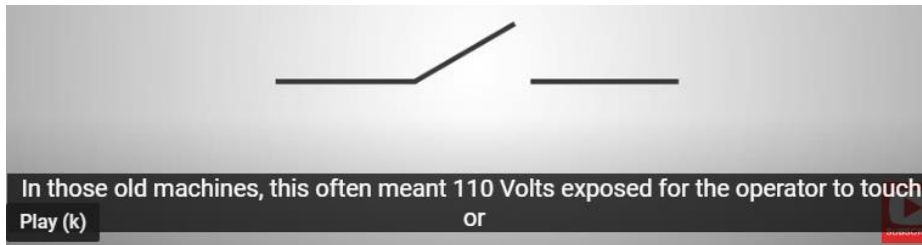
## Passive



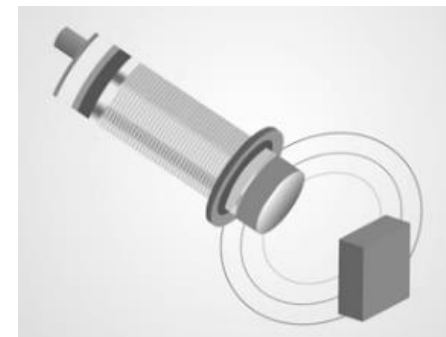
➤ Passive-Eg: Strain Gauge



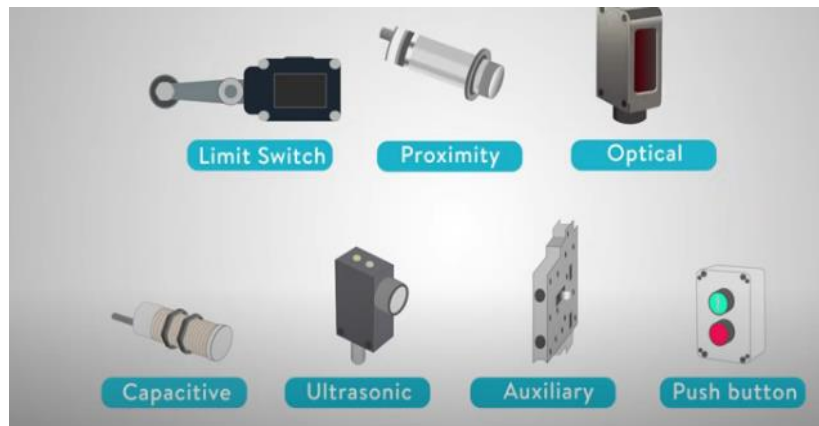
- Digital Sensor are used in industry
- In theoretical we refer one or more bits of information per sensor



Limit Switch



Proxes

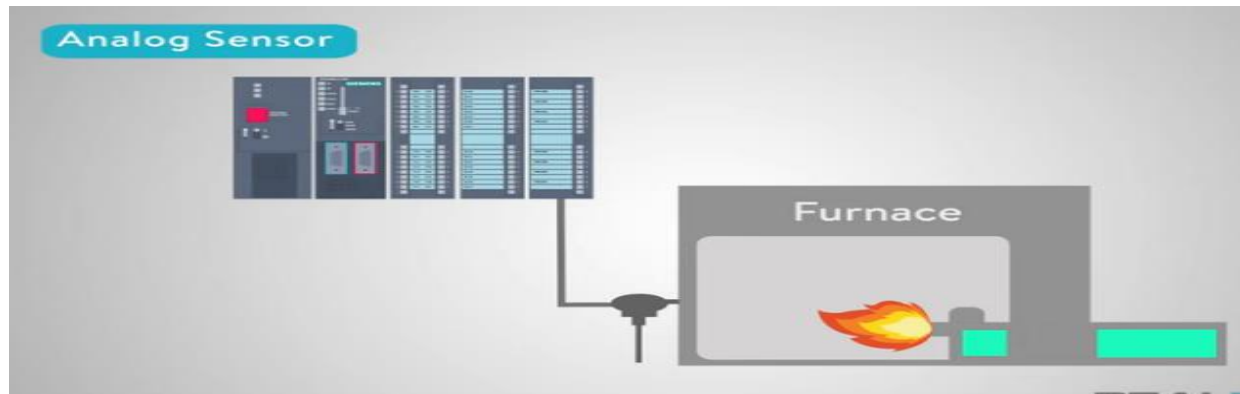
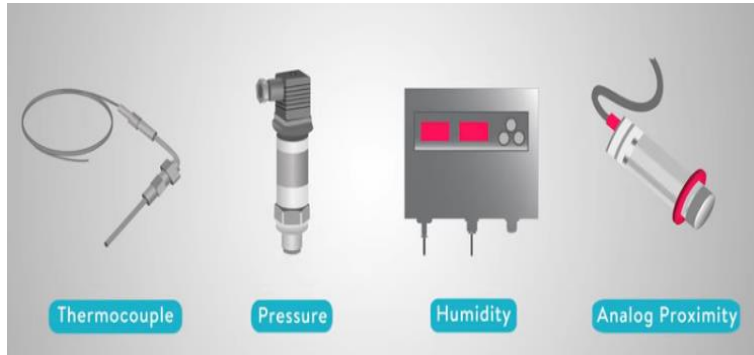


- Digital Sensors



# Sensor Types

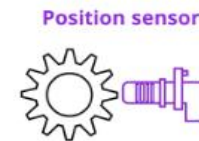
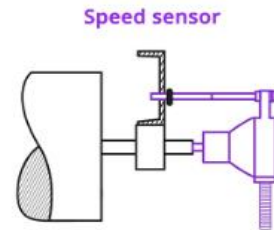
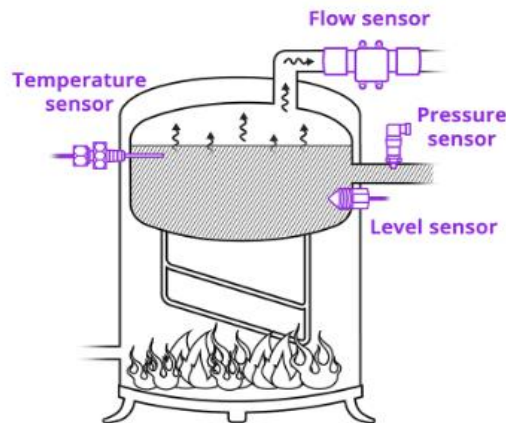
- Passive Sensor
- Analog Sensor that return a range of values





Pressure Sensor

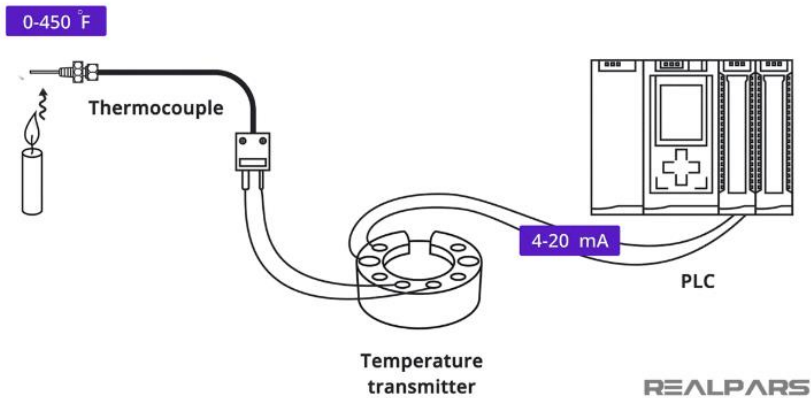
➤ we define a Sensor as a device that detects changes in physical, electrical, or chemical properties and produces an electrical output in response to that change.



REALPARS

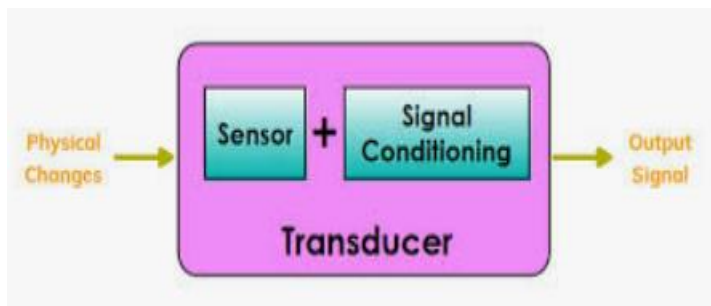
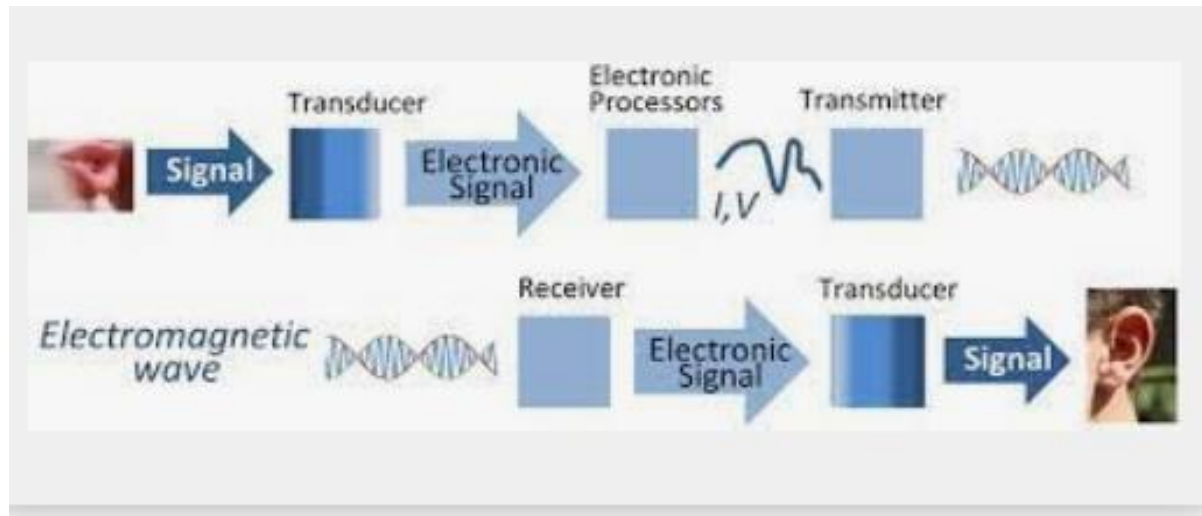


# Why Transmitter in sensor



➤ Almost every sensor used in process control will be connected to a Transmitter because a sensor's output needs to be conditioned or amplified.

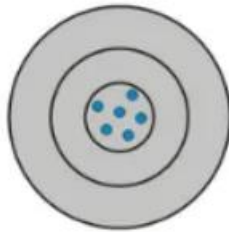




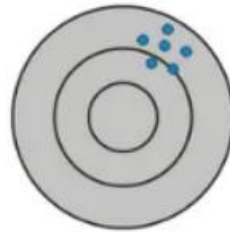
<p style="text-align: center;"><b>TRANSDUCER</b></p> <p>A TRANSDUCER IS A DEVICE THAT CONVERTS ENERGY FROM ONE FORM TO ANOTHER. USUALLY A TRANSDUCER CONVERTS A SIGNAL IN ONE FORM OF ENERGY TO A SIGNAL IN ANOTHER.</p>	<p style="text-align: center;"><b>SENSOR</b></p> <p>SENSOR IS A DEVICE, MODULE, OR SUBSYSTEM WHOSE PURPOSE IS TO DETECT EVENTS OR CHANGES IN ITS ENVIRONMENT AND SEND THE INFORMATION TO OTHER ELECTRONICS, FREQUENTLY A COMPUTER PROCESSOR.</p>



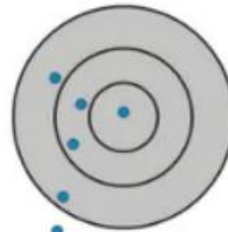
## What are the Characteristics of Sensors?



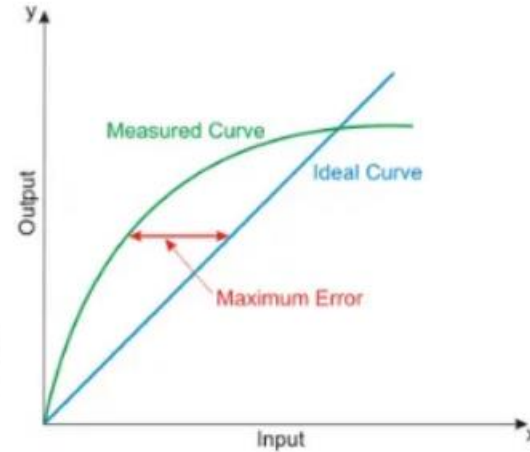
High Accuracy  
High Precision



Low Accuracy  
High Precision



Low Accuracy  
Low Precision





# Characteristics of Sensors



- 1. Range:** It is the minimum and maximum value of physical variable that the sensor can sense or measure. For example, a [Resistance Temperature Detector](#) (RTD) for the measurement of temperature has a range of -200 to 800°C.
- 2. Span:** It is the difference between the maximum and minimum values of input. In above example, the span of RTD is  $800 - (-200) = 1000^\circ\text{C}$ .







# Characteristics of Sensors



- 3. Accuracy:** The error in measurement is specified in terms of accuracy. It is defined as the difference between measured value and true value. It is defined in terms of % of full scale or % of reading.

$$\begin{aligned} \text{Absolute Error} &= |\text{Measured value} - \text{True value}| \\ \Rightarrow E_a &= |X_m - X_t| \end{aligned}$$

$X_t$  is calculated by taking mean of infinite number of measurements.

$$\begin{aligned} \text{Relative error} &= \frac{\text{Absolute error}}{\text{True value}} \\ \Rightarrow E_r &= \frac{|X_m - X_t|}{X_t} \end{aligned}$$





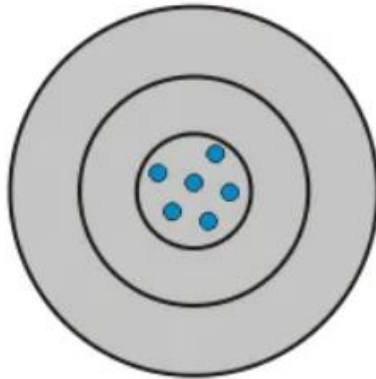
# Characteristics of Sensors



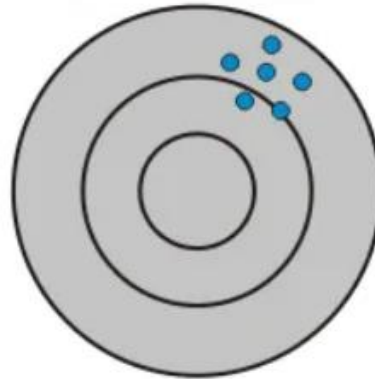
4. **Precision:** It is defined as the closeness among a set of values. It is different from accuracy. Let  $X_t$  be the true value of the variable  $X$  and a random experiment measures  $X_1, X_2, \dots, X_i$  as the value of  $X$ . We will say our measurements  $X_1, X_2, \dots, X_i$  are precise when they are very near to each other but not necessarily close to true value  $X_t$ . However, if we say  $X_1, X_2, \dots, X_i$  are accurate, it means that they are close to true value  $X_t$  and hence they are also close to each other. Hence accurate measurements are always precise.



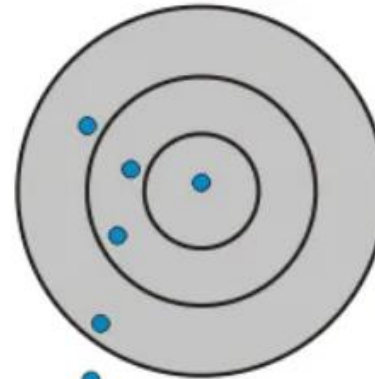
## *Precision*



High Accuracy  
High Precision



Low Accuracy  
High Precision



Low Accuracy  
Low Precision





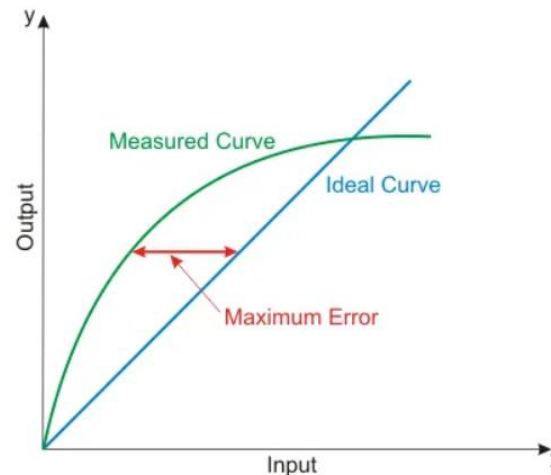
# Characteristics of Sensors



5. **Sensitivity:** It is the ratio of change in output to change in input. If Y be the output quantity in response to input X, then sensitivity S can be expressed as

$$S = \frac{dY}{dX} = \frac{\Delta Y}{\Delta X}$$

6. **Linearity:** Linearity is the maximum deviation between the measured values of a sensor from ideal curve.

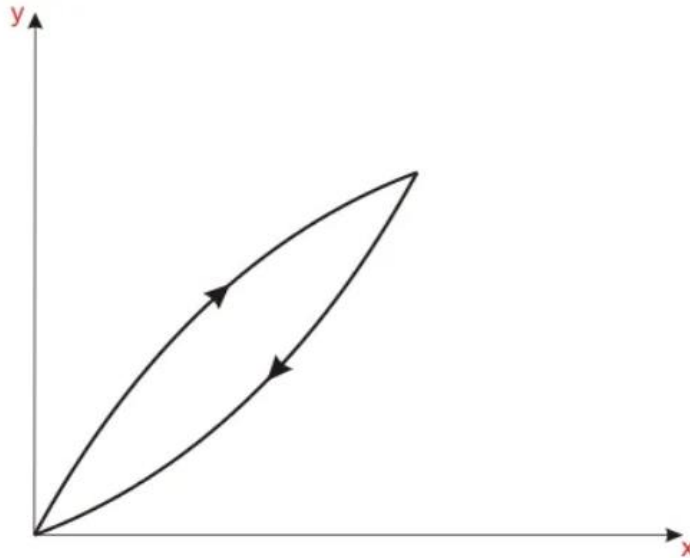




# Characteristics of Sensors



7. **Hysteresis:** It is the difference in output when input is varied in two ways- increasing and decreasing.





# Characteristics of Sensors



8. **Resolution:** It is the minimum change in input that can be sensed by the sensor.
9. **Reproducibility:** It is defined as the ability of sensor to produce the same output when same input is applied.
10. **Repeatability:** It is defined as the ability of sensor to produce the same output every time when the same input is applied and all the physical and measurement conditions kept the same including the operator, instrument, ambient conditions etc.
11. **Response Time:** It is generally expressed as the time at which the output reaches a certain percentage (for instance, 95%) of its final value, in response to a step change of the input.





Thank  
you

